

UNIVERSITY OF SPLIT

FACULTY OF ELECTRICAL ENGINEERING, MECHANICAL ENGINEERING AND NAVAL ARCHITECTURE

DETAILED PROPOSAL OF THE STUDY PROGRAMME

GRADUATE UNIVERSITY STUDY IN AUTOMATION AND SYSTEMS

SPLIT, July 2017

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GENERAL INFORMATION OF HIGHER EDUCATION INSTITUTION

Name of higher education institution	FACULTY OF ELECTRICAL ENGINEERING, MECHANICAL ENGINEERING AND NAVAL ARCHITECTURE
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GENERAL INFORMATION OF THE STUDY PROGRAMME

Name of the study programme	AUTOMATICS AND SYSTEMS					
Provider of the study programme	FACULTY OF ELEC ENGINEERING AN		,	IECHANICAL		
Other participants						
Type of study programme	Vocational study pro	ogramme 🗆	University stud	y programme 🖂		
Level of study programme	Undergraduate 🗆	Graduate 🖂		Integrated		
	Postgraduate	Postgraduat	e specialist 🗆	Graduate specialist □		
Academic/vocational title earned at completion of study	Master of Engineeri	ing in Automa	ation and Syster	ns; mag. ing. el.		

1. INTRODUCTION

1.1. Reasons for starting the study programme

Automation is a branch of science which deals with problems of automatic control of engineering systems and encompasses analysis, synthesis and implementation of control units, as well as wide area of control theory. As multidisciplinary and interdisciplinary systematic field, automation uses and consolidates scientific achievements and practical knowledge from electrical engineering, electronics, computing, information-communication technologies, mechanical engineering, materials technology, information systems, biosystems and advancements in mathematics and physics. With the aim of emphasising this systematic approach, the graduate study is titled *Automation and Systems*.

Graduates who complete the graduate university study programme in Automation and Systems acquire the competencies for research and application of methods, conceptions, and contemporary information technologies in modelling, simulation and control of systems in the wide scope of human activities. There is virtually no area of human activity in which there is no need for automated systems or automated procedures (engineering, economic, social, medical systems). Through development of new technologies that enable the remote transfer of information, voice, image and data transfer using wireless networks and through development of microelectronics, new and almost indefinite possibilities are opened, providing access to new procedures which facilitate day-to-day work activities and life, but also influence the advancement of economy. The knowledge of these type of experts is the foundation for healthy economy and advancement of any contemporary society, this being the reason why this area is often emphasised as priority development area in a number of countries.

An important feature of the graduate university study programme in Automation and Systems is the wide scope of application of fundamental knowledge acquired during the undergraduate studies in electrical engineering and information technology, and which knowledge is deepened during the graduate university studies, through completing the coursework at professional courses.

Following the completion of the graduate university study programme in Automation and Systems, employment opportunities are open in the industrial sector as well as various public institutions. The study programme can also be followed by further academic advancement of students at postgraduate studies in research or specialist fields.

1.2. Relationship with the local community (economy, entrepreneurship, civil society, etc.)

The goal of the proposed university study programme Automation and Systems is to educate professional staff in the area of automatic control of systems to meet the demands of the industry, governmental and other public institutions. As multidisciplinary and interdisciplnary systematic field, automation uses and consolidates scientific achievements and practical knowledge from electrical engineering, electronics, computing, information-communication technologies, mechanical engineering, materials technology, information systems, biosystems and advancements in mathematics and physics. With the aim of emphasising this systematic approach, the graduate study is titled *Automation and Systems*.

One of the basic tasks of the Faculty is the education of young professionals who will use their knowledge, skills and abilities to become stakeholders in the economic and general development of local and wider community. Having been training leading professionals for more than 55 years, the Faculty successfully accomplished its task, providing necessary staff to participate in the development of economy sectors based on different branches of engineering. The Faculty trained professionals who significantly contributed to economic development in the region, thus supporting the region to initiate and successfully develop high-tech based production activities with its own human resources potential. Successful development of new technologies influenced the development of all engineering sciences, especially the interdisciplinary areas such as automatic control. Experts educated at FESB have been designing automated systems based on new technologies, especially the information technology. Early developments started back in 1966, with the purchase of the first computer funded by local enterprises and establishment of the Computer Centre at FESB. This was the first computer purchased in town and the first installed computer at a higher education institution in Croatia, representing a major breakthrough which allowed for gaining valuable experience, not only in teaching and research activities at the Faculty, but also in IT education and can be considered as the starting point in development of IT sector in the region. Professionals trained at FESB are the founders of a number of companied based on automation technology and ICT companies in the Split-Dalmatia County and town of Split.

There is virtually no area of human activity in which there is no need for automated systems or automated procedures (engineering, economic, social, medical systems). Through development of new technologies that enable the remote transfer of information, voice, image and data transfer using wireless networks and through development of microelectronics, new and almost indefinite possibilities are opened, providing access to new procedures which facilitate day-to-day work activities and life.

Following the completion of the graduate university study programme in Automation and Systems, employment opportunities are open in the industrial sector as well as various public institutions. The study programme can also be followed by further academic advancement of students at postgraduate studies in research or specialist fields.

Split is the economic and university hub of the entire Dalmatian region, as well as one part of the neighbouring region of Bosnia and Herzegovina. FESB is the only higher education institution in the region which delivers the university graduate study programme awarding the master's degree in automatics and systems.

1.3. Compatibility with requirements of professional organizations

The study programme is compatible with the requirements of the Croatian chamber of electrical engineers.

1.4. Name possible partners outside the higher education system that expressed interest in the study programme

FESB is a signatory to a number of cooperation agreements with the aim of promoting academic and educational activities, concluded with private enterprises and public organisations, e.g. Ericsson Nikola Tesla, Hrvatska elektroprivreda (national power company), Split-Dalmatia County, Ministry of Defence, Energy institute "Hrvoje Požar", Croatian Telecom, Croatian academic and research network - CARNet, Technology Centre Split, Brodosplit, Siemens, VIPnet, Microsoft Croatia, etc. It is important to note that the Croatian Armed Forces expressed a special interest in cooperation, since prospective officers are trained at the Faculty.

1.5. Financing

The study programme is financed by the Ministry of Science, Education and Sports

1.6. Comparability of the study programme with other accredited programmes in higher education institutions in the Republic of Croatia and EU countries

During the implementation of the university study programme in Automation and Systems, careful consideration is given to following the developments of higher education on the global level and especially in Europe. In the process of developing the new curriculum, special attention was given to consolidating the curriculum and course contents with other renowned foreign higher education institutions. There is an established system of educating experts in the field of automated systems, i.e. wider area of automation and systems in the world and in Europe, with different approaches. As a rule, the first stage is acquiring knowledge of mathematics and fundamental natural sciences, followed by specialist courses and certain nonengineering courses, of which courses in economics are of special interest. The study programme proposal is consolidated with the recommendations given in the framework of the ERASMUS project THEIERE (Towards the Harmonisation of Electrical and Information Engineering Education in Europe, http://www.eaeeie.org/theiere/).

The curriculum of the university study programme in Automation and Systems highly corresponds to the curricula of related fields of study and study programmes at renowned Croatian and European universities, e.g.:

- Faculty of Electrical Engineering and Computing at the University of Zagreb,
- Faculty of Electrical Engineering at the University of Osijek,
- Faculty of Engineering at the University of Rijeka,
- Faculty of Electrical Engineering at the University of Ljubljana,
- Faculty of Electrical Engineering and Computer Science, University of Maribor,

- Technische Univerzität Münich/ Technical University of Munich,
- Universita degli studi di Trieste/ University of Trieste, Italy.

The following study programmes should be specially listed: L'Ecole doctorale en "Automatique et systèmes" (System and Control) at Université catholique de Louvain in Belgium (<u>http://www.ucl.ac.be/recherche/ecoles/ausy.html</u>), which is titled indentically to the proposed study programme and the graduate study Automaatioja systeemitekekniikan koulutusohjelma (Automation and System Technology) at the Helsinki University of Technology, Finland (<u>http://www.hut.fi/Units/AS/Studies/</u>)

1.7. Openness of the study programme to student mobility (horizontal, vertical in the Republic of Croatia, and international)

Graduate university study programme in Automation and Systems enables vertical and horizontal mobility of students. In terms of vertical mobility, the programme can primarily be followed by the postgraduate university study in Electrical Engineering and Information Technology at FESB. Vertical mobility is enabled also for other related postgraduate study programmes. In terms of horizontal mobility, the graduate university study is open for mobility of students of related studies at all Croatian universities, including the Faculty of Electrical Engineering and Computing at the University of Zagreb, Faculty of Engineering at the University of Rijeka and the Faculty of Electrical Engineering at the University of Osijek. Students have the opportunity to complete a part of the study programme at a similar institution in Croatia or abroad. The comparability of the study programme with similar study programmes at the same level enables the students to fulfil a part of their course requirements at other higher education institutions in Croatia or abroad.

1.8. Compatibility of the study programme with the University mission and the strategy of the proposer, as well as with the strategy statement of the network of higher education institutions

Graduate university study programme in Automation and Systems Engineering conforms with the Strategy of the University of Split 2015-2020. In addition to mission and vision of the University of Split, in the process of defining strategic goals, the following strategic documents were taken into account as guidelines:

- EUROPA 2020 strategy for smart, sustainable and inclusive growth,
- Strategic documents of the European Research Area (ERA),
- Strategic documents of the European Higher Education Area (EHEA),
- Strategy of Education, Science and Technology of the Republic of Croatia.

Preparation of the study programme was done in line with the mission, vision and goals which are partly derived from the Scientific Strategy of the University of Split 2009 – 2014, document which promotes creation of internal development plans at the level of University constituents.

Graduate university study programme in Automation and Systems conforms with the development guidelines of the Faculty, as well as mission, vision and strategic goals defined in the FESB Development Strategy for the period 2012 – 2016, and is the only programme of this type at the University of Split and the wider region.

The proposed study programme conforms with the strategic document Network of Higher Education Institutions and Study Programmes in the Republic of Croatia, which encourages launching new study programmes in STEM area, as automation is one of STEM disciplinary program areas.

1.9. Current experiences in equivalent or similar study programmes

FESB has extensive experience in delivering courses at similar programmes. Faculty of Electrical Engineering in Split was established in 1960, implementing a 2nd level study programme in electrical engineering, with programme duration of 8 semesters. After the integration with the studies in mechanical engineering and naval architecture, the Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture (FESB) was established in 1971. Since 1974 the Faculty has been a constituent part of the University of Split.

Continuous work at developing the curricula resulted in establishing a number of study programmes at undergraduate and graduate level. At the undergraduate study programmes in Electrical Engineering the programme was implemented in the following fields of study: Power Engineering and Electronic Engineering. The first three semesters of the study programme are identical for both fields of study, and the following semesters provide specialist courses with elective disciplines of study. The disciplines of study in Power Engineering are: Electric Drives and Facilities and Power Engineering Systems, and in Electronic Engineering: Automation and Systems, Electronic Communication Systems, Applied Electronic Engineering and Computer Technology.

In 1979 vocational study programmes were established at the Faculty (former level VI study programme) which are implemented since, with a pause during years 1998-2001.

Postgraduate study in the scientific field of electrical engineering was first introduced in 1969, in cooperation with the Faculty of Electrical Engineering in Zagreb, and since 1989 the programme is delivered independently at the Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture of the University of Split. The programme provided specialisation in the areas of telecommunications and computer information systems, electronics, power engineering and electromechanical engineering, automation and computing.

Continuous work at developing the curricula resulted in establishing a number of study programmes at undergraduate, graduate and postgraduate level, which are constantly supplemented by new elective courses.

Quality of education at FESB is confirmed by success and excellence of FESB engineers worldwide, including the most highly developed countries of the world. However, the most important is the fact that professionals trained at FESB represent a foundation of highly educated engineering labour force in the region.

2. DESCRIPTION OF THE STUDY PROGRAMME

2.1. General information

Scientific/artistic area of the study programme	Engineering sciences
Duration of the study programme	2 years
The minimum number of ECTS required for completion of study	120
Enrolment requirements and admission procedure	Completed undergraduate study programme in Electrical Engineering and Information Technology or completed other related undergraduate study programme with acquired at least 180 ECTS credits, with applicable classification procedure. For students who completed other related study programmes, in addition to requirements for enrolling specific courses, the Faculty Council may define additional admission requirements.

2.2. Learning outcomes of the study programme (name 15-30 learning outcomes)

The learning outcomes of the study programme are directly related to the learning outcomes of an individual course and represent learning outcomes to be achieved by each student who completes the graduate university study programme in *Automation and Systems*. The learning outcomes are aligned with the Croatian Qualification Framework Act and are listed as common learning outcomes and additional learning outcomes depending on the selected elective courses, in the areas of knowledge, skills and corresponding independence and responsibility.

KNOWLEDGE

- 1. To apply appropriate mathematical, physical and scientific principles in solving highly complex problems of controlled automated systems.
- 2. To apply advanced engineering knowledge and engineering principles in presenting and solving highly complex and original problems of controlled systems. To apply methods of standard and digitally controlled systems.
- 3. To apply acquired knowledge in identifying, formulating and solving highly complex engineering problems.
- 4. To develop innovative analytical methods and advanced modelling procedures in solving highly complex engineering problems.

- 5. To critically review the features of new and upcoming products and processes, as well as methods that enable independent and purposeful work.
- 6. By applying scientific principles, to design innovative experiments with the use of state-of-the-art technological solutions in the area of controlled systems, specifically the methods of remotely controlled systems.
- 7. To select optimal economically viable engineering solutions in the design and construction of highly complex automated systems, which require compromise between theoretical solutions and the practical possibilities.
- 8. To critically assess and provide arguments for the possibilities of applied techniques and methods and their limitations.

SKILLS

- 9. To apply advanced programming skills in solving highly complex controlled systems problems, especially using the possibilities of the internet environment.
- 10. To conduct complex experiments and measurements, analyse and interpret collected data and measurement results and give conclusions and proposals for solutions.
- 11. To manage simple multidisciplinary and international teams.
- 12. To prepare design documents and technical reports, using modern technologies.
- 13. To use the literature, databases and other sources of information.
- 14. To give a public presentation, to prepare a written report and present project results in Croatian and English.

INDEPENDENCE

- 15. To manage and lead development activities in the environment with unforeseen conditions.
- 16. To make decisions in uncertain conditions.
- 17. To work in the field and under unforeseen conditions

RESPONSIBILITY

- 18. To demonstrate awareness of the influences of engineering practice on the individual, society and environment.
- 19. To assume personal and team responsibility for strategic decision-making and successful performance and completion of tasks in unforeseen conditions.
- 20. To assume social and ethical responsibility during performance of tasks and the consequent results of those tasks.
- 21. To adopt and transfer new knowledge and technology.

ADDITIONAL LEARNING OUTCOMES ACHIEVED THROUGH ELECTIVE COURSES (APPLYING KNOWLEDGE ON AUTOMATION AND SYSTEMS)

- 1. To consolidate theoretical knowledge and practical skills in solving highly complex problems in the area of telemedicine, bio-cybernetics and bioelectrical systems.
- 2. To propose new procedures and new solutions for modernisation of industrial robots.
- 3. To develop innovative methods and software solutions for AI and digital processing and analysis of images and computers graphics.
- 4. To design advanced algorithmic solutions for regulating and controlling of vessels and vehicles.
- 5. To analyse physical phenomena in conceptions of modern physics.
- 6. To organise and manage the investigation of complex problems, in general the measurements and processing of signal, specifically in solar cells.
- 7. To design innovative solutions in the development, design, implementation and investigation of elements and devices of electronic and virtual instruments.

2.3. Employment possibilities

Following the completion of studies, the acquired knowledge enables the students to find employment in the industry, research institutes, software and ICT companies, education, healthcare, service industry, etc. There is virtually no working environment in which experts with completed university degree in Automation and Systems could not find employment and the labour market demand for this profile of experts are very high. This is especially relevant in this moment, with social and economic changes driving the development of new, small and medium technologically advanced enterprises that could serve as the new driving force for economic development. Graduates who complete the graduate university study programme in Automation and Systems are equipped with knowledge and skills for research and application of methods, concepts and stat-of-the-art information technology in modelling, simulation and control of systems in the wide scope of human activities. Following the completion of studies, fully educated experts are capable of solving the most complex engineering tasks and participating in scientific research. The demand for experts with these competences considerably exceeds the available number of educated experts in the region, Croatia and the world.

2.4. Possibilities of continuing studies at a higher level

After completing the graduate university study programme in Automation and Systems, graduates may continue their studies at the postgraduate study programme in Electrical Engineering and Information Technology at FESB or at any other related postgraduate study programme.

2.5. Name lover level studies of the proposer or other institutions that qualify for admission to the proposed study

Undergraduate university study programme in Electrical Engineering and Information Technology, field of study Automation and Systems or completed any other related study programmes with acquired at least 180 ECTS credits, with applicable classification procedure.

2.6. Structure of the study

The study programme is structured per semesters, lasting 4 semesters, two in each academic year. Each semester corresponds to 30 ECTS credits. Through first two semesters of the first year of study and the winter semester of the second year of study, in addition to required courses, the students select two elective courses per semester from the provided lists. The final component of the study programme is preparing and defending the diploma thesis. Preparing of the diploma thesis is the only workload in the summer semester of the second year of study. The conditions for enrolling a course are listed in the course table. Lectures are delivered in groups up to 100 students, auditory exercises and seminars in groups of 30 students and laboratory exercises in groups of 10 students.

2.7. Guiding and tutoring through the study system

During the course of study programme activities, students have access to all the Faculty services. For the purpose of timely and effective communication, notifications and information are provided to students through the e-learning portal.

2.8. List of courses that the student can take in other study programmes

The educational and research field of automation and systems is interdisciplinary, therefore in the list of required and elective courses for all semesters there is a list of courses from other university graduate study programmes at the Faculty (Electrical Engineering, Communication and Information Technology, Computer Engineering, Mechanical Engineering and Industrial Engineering) which students can select to expand the knowledge and skills acquired during the core courses. In accordance with the study programme, students may select any course from the provided list of elective courses, within the limits of planned ECTS credits. Students may, according to their personal preference, choose courses from other study programmes that are not part of the list, as elective courses which are not included in the standard workload of 30 ECTS credits per semester.

2.9. List of courses offered in a foreign language as well

Course tables for individual courses list the option of teaching a course in a foreign language.

2.10. Criteria and conditions for transferring the ECTS credits

Transfer or recognition of ECTS credits between related graduate university study programmes is allowed. The criteria and conditions for transferring the ECTS credits are regulated by the *Regulations on Studies and Study System at the University of Split*.

2.11. Completion of study

Final requirement for completion of study	Final thesis □ Diploma thesis ⊠	Final exam □ Diploma exam □					
Requirements for final/diploma thesis or final/diploma/exam	The requirement for applying for the diploma thesis is acquired 60 ECTS credits.						
Procedure of evaluation of final/diploma exam and evaluation and defence of final/diploma thesis	The diploma thesis is evaluate defence is public and held in the	d by the commission and the ne presence of the commission.					

2.12. List of mandatory and elective courses

		List of courses						
Year of study	: 1.							
Semester: I.								
07.0710	0005	001/005	HO	URSI	N SEI	MEST	ER*	FOTO
STATUS	CODE	COURSE	L	S	AE	LE	DE	ECTS
	FEMG01	Modern physics	30	0	0	30	0	4
	FELG01	Linear control systems	45	0	15	15	0	6
	FELG02	Computer systems	30	0	0	30	0	5
Mandatory	FELG03	System identification	30	0	0	30	0	5
ivianualory		Elective course 1**						
		Elective course 2**						
	Total		135	0	15	105	0	20
	*L = predav	ranja, S = seminar, AE = auditorne vježbe, LE = labo	ratorijsk	e vježb	e, DE =	= konst	rukcijsk	e vježbe
**lzborni se	predmeti	mogu birati s predložene liste izbornih pre	edmeta	ι ονοί	g stud	lija.		
	FELG32	Telemedicine and Biocybernetics	30	0	0	30	0	5
	FELG05	Industrial robotics	30	0	0	30	0	5
	FELG07	Electronic and virtual instrumentation	30	0	0	30	0	5
	FELG20	Computer methods in bioengineering	30	0	0	30	0	5
	FELH11	Artificial intelligence	30	0	0	30	0	5
	FELG30	Introduction to machine learning	30	0	0	30	0	5
Elective**	FETG01	Project management	30	0	30	0	0	5
	FELK04	Computer graphics	30	0	0	30	0	5
	FENI03	Measurements and signal processing	30	0	0	30	0	6
	FEMK01	Numerical analysis	30	0	30	0	0	5
	FELG09	Digital image processing and analysis	30	0	30	0	0	5
	Bira se: -	2 Elective courses						
	*L = predav	ranja, S = seminar, AE = auditorne vježbe, LE = labo	ratorijsk	e vježb	e, DE =	= konst	rukcijsk	e vježbe

List of courses									
Year of study	: 1.								
Semester: II.									
			HO	URSI	N SEI	MEST	ER*		
STATUS	CODE	COURSE	L	S	AE	LE	DE	ECTS	
	FELG10	Digital control	45	0	30	0	0	6	
	FELG11	Nonlinear control systems	30	0	30	0	0	5	
	FELG12	Practicum of automatic control	15	0	0	45	0	4	
Mandatory	FELG13	Programmable logic controllers	30	0	0	30	0	5	
ivial luator y		Elective course 1**							
		Elective course 2**							
	Total		120	0	60	75	0	20	
	*L = predav	ranja, S = seminar, AE = auditorne vježbe, LE = labo	ratorijsk	e vježb	e, DE =	= konst	rukcijsk	e vježbe	
**lzborni se	predmeti	mogu birati s predložene liste izbornih pr	edmeta	a ovo	g stud	lija.			
	FELG14	Operations research	30	0	0	30	0	5	
	FELG15	CAD in automatic control	30	0	0	30	0	5	
	FELG16	Digital instrumentation 2	30	0	0	30	0	5	
	FETG02	Hydraulic and pneumatic systems	30	0	0	30	0	5	
	FELG27	Modelling and control of vessels and ground vehicles	30	0	0	30	0	5	
	FELG18	Computational intelligence (neuro-fuzzy- genetic systems)	30	0	0	30	0	5	
Elective**	FELG19	Programming agents	30	0	0	30	0	5	
	FELH35	Solar cells	30	0	0	30	0	5	
	FENG01	Engineering economy	30	0	0	30	0	5	
	FELH07	Digital systems projecting	30	0	0	30	0	5	
	FENG02	Adaptive control	30	0	0	30	0	5	
	FELG33	Optoelectronic measurement methods	30	0	0	30	0	5	
	Bira se: -	2 Elective courses							
	*L = predavanja, S = seminar, AE = auditorne vježbe, LE = laboratorijske vježbe, DE = konstrukcijske vježbe								

List of courses										
Year of study: 2.										
Semester: III.										
			НО	URSI	N SEI	MEST	ER*			
STATUS	CODE	CODE COURSE -		S	AE	LE	DE	ECTS		
	FELG21	Process control	45	0	30	0	0	6		
	FELG22	Process control laboratory	15	0	0	30	0	4		
	FELG23	Optimization and optimal systems	30	0	30	0	0	5		
Mandatory	FELG24	Microcontrollers and network embedded systems	30	0	0	30	0	5		
		Elective course 1**								
		Elective course 2**								
	Total		120	0	60	30	0	20		
	*L = predav	vanja, S = seminar, AE = auditorne vježbe, LE = labor	atorijsk	e vježb	e, DE :	= konst	rukcijsk	e vježbe		
**lzborni se	predmeti	mogu birati s predložene liste izbornih pre	edmeta	a ovo	g stud	lija.				
	FELG17	Bioelectrical systems and equipment	30	0	0	30	0	5		
	FELG25	Mobile robotics	30	0	0	30	0	5		
	FELG26	Multivariable control	30	0	0	30	0	5		
	FENG03	Electric servo drives	30	0	0	30	0	5		
	FELG29	Computer aided process control	30	0	0	30	0	5		
	FETL23	Production management	30	0	30	0	0	5		
Elective**	FELH13	Electronic circuits	15	0	15	30	0	5		
LICCIVE	FEOG01	English language for academic purposes***	0	45	0	0	0	3		
	FENG04	Energy storage systems	30	0	0	15	0	5		
	FEXX06	Professional Training						5		
	Bira se: -	2 Elective courses						-		
	***Može s	vanja, S = seminar, AE = auditorne vježbe, LE = labor se upisati kao dodatni predmet jer mu je opter nijeniti neki od stručnih izbornih predmeta	ećenje	9 3 EC	TS-a	i s nji	me se	ne		

	List of courses									
Year of stu	dy: 2									
Semester:	IV.									
STATUS					НО	URSI	N SEN	MEST	ER*	ECTS
51A105	CODE	COURSE	L	S	AE	LE	DE	ECIS		
	FEXX02	Diploma thesis						30		
	Total									
*L = predava	anja, S = sem	inar, AE = auditorne vježbe, LE = laboratorijske vježbe	DE = k	onstrul	kcijske	vježbe				

2.13. Course description

NAME OF THE COURSE	ADAPTIVE CONTROL								
Code	FENG02	Year of study	2						
Course teacher	Ozren Bego, Ph.D., Associate Professor	Credits (ECTS)	5						
Associate teachers	Danijel Jolevski, Ph.D., Assistant Professor	Type of instruction (number of hours)	S 0	AE 0	LE 30	DE 0			
Status of the course	Elective	Percentage of application of e-learning	0		1				
	COURSI	E DESCRIPTION							
Course objectives	 analyze of adaptive co design of adaptive con 						ation,		
Course enrolment requirements and entry competences required for the course	None								
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 define structure of ada choose adaptive control identify process param 	 Students will be able to: define structure of adaptive control systems, choose adaptive control concept according to defined requirements, identify process parameters, design control system with adaptive controllers, 							
	Course content				L or S hours		\E ours		
	Introduction in adaptive co variable process control.	ntrol systems. Concept of	time		2		0		
	Structures od adaptive con	ntrol systems.			2		0		
	Process parameters identit structure.	fication. Defining of proces	SS		2		0		
	Recursive identification, leader execution, identification res		ment		2		0		
	Deterministic adaptive con	trollers.			2		0		
	Stochastic adaptive contro	llers.			2		0		
Course content	Self-adaptive controllers.				2		0		
broken down in	First midterm exam				2		0		
detail by weekly class schedule	Adaptive controllers with re				2		0		
(syllabus)	Adaptive controller with ga				2		0		
(-,)	Predictive controllers – par				2		0		
	Predictive controllers – par				2		0		
	Examples of adaptive cont	0			2	0			
	Examples of adaptive cont	roller design.			2		0		
	Second midterm exam				2		0		
	List of laboratory or design	exercises					or DE ours		
	Identification of water tank						3		
	Identification of water tank validation, analyze.		executi	on,			3		
	Pole placement adaptive co	ontroller					3		

	Gain scheduling controller -experiment preparation Gain scheduling controller -experiment execution, validation								
	Self-adaptive control Predictive controller	Self-adaptive controller with relay method Predictive controller							
Format of instruction	 lectures seminars and wo exercises on line in entirety partial e-learning field work 	 ☑ lectures ☑ seminars and workshops ☑ exercises ☑ on line in entirety ☑ partial e-learning ☑ independent assignments ☑ multimedia ☑ laboratory ☑ work with mentor ☑ (other) 							
Student responsibilities									
Screening student work (name the	Class attendance	1	Researc	h	F	Practical trainir	ng		
proportion of ECTS credits for each	Experimental work		Report		L	aboratory atte	endance	1	
activity so that the	Essay		Seminal essay			ndependent w		2	
total number of ECTS credits is equal to the ECTS	Tests	0.5	Oral exa	am		Preparation for aboratory work		0.5	
value of the course)	Written exam		Project			(Other)			
Grading and evaluating student work in class and at the final exam	There are two midte lecturing and the set that did not pass the is the positive asse midterm exam or the formula: the activities in perce • NP - attenda • LV – laborat • M1, M2 – te	cond on e midter essmen e final e rade(%) entage: ance at l cory ass	e is after m exams t of labc xam. Gra = 0,05 N ectures, essment,	the ne take p pratory ade (in	xt 6 week part. The r exercises percentag	ks. In the final requirement fo s and 50 % ge) is formed 4 (M1 + M2)	exams s or passing points o	tudents g grade n each	
Required literature (available in the library and via other		Title				Number of copies in the library	Availabi other r	-	
media)	O. Bego: Predavanja upravljanje, FESB	a iz prec	lmeta Ad	aptivno			e-lear por	-	
Optional literature (at the time of submission of study programme proposal)									
Quality assurance methods that ensure the acquisition of exit competences	 Evaluation of results in accordance with the above learning outcomes Feedback from students via surveys Self-evaluation of teachers, Institutional and non-institutional evaluations 								
Other (as the proposer wishes to add)									

NAME OF THE COURSE	ARTIFICIAL INTELLIGE	ARTIFICIAL INTELLIGENCE								
Code	FELH11	Year of study	1							
Course teacher	Darko Stipaničev, Ph.D., Full Professor (60%) Ljiljana Šerić, Ph.D., Assistant Professor (40%)	Credits (ECTS)	5							
Associate teachers	Toni Jakovčević, Ph.D., Assistant Professor	Type of instruction (number of hours)	L 30	S 0	AE 0	LE 30	DE 0			
Status of the course	Elective	Percentage of application of e-learning	80	1						
	COURSE	DESCRIPTION								
Course objectives	The aim of the course is to intelligence, ways of collect by which this knowledge is introduction to the theoretic many applications in scier	s used in solving complex ical foundations of artificial	je, to n tasks.	nethod In add	s and ition to	algorit o an	hms			
Course enrolment requirements and entry competences required for the course	Basic knowledge of computers and programming. To follow the College is necessary knowledge of English.									
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 computational intellige Present complex task Understand the different systems based on known Explain the procedure different types of mathematical logic). Apply the structural renetworks, frames, scee Describe and present intelligence, especially and directed search) Apply logical reasoning Apply simple machine Write simple programs intelligence (Prolog, L 	s between biological intelli ence and distributed intellig s and prepare them for au ence between data, inform owledge. s of knowledge elicitation nematical logic (proposition presentation of knowledge narios, stereotypes, and p standard methods of solvi y methods of searching the g, probabilistic reasoning, learning tasks (unsupervi s in programming language	gence. tomatic ation a and kn hal logi roduct ng task e know fuzzy sed an es and	, artific c solvir nd kno cowled c, prec cularly ion rul- ks of a ledge reasor d supe tools	ng the powledg ge sto dicate sema es. rtificia base (base (porvised of artif	m. ge and ring us logic, r ntic l (undire d).	sing non-			

	Course content					L or S	LE
			ll'act i	41	n n hint : :	hours	hours
	Introduction to Artifi related disciplines. multiple intelligence intelligence. The teo success criteria.	Biologic es. The l	al intellig	ence, th area of	e theory of artificial	4	0
	Complex tasks and methods. Problem s (undirected and dire	solving t	technique			4	0
Course content broken down in detail by weekly class	Knowledge and sto data, information, k Knowledge and sto logic (standard and	nowledo rage of	ge. Know knowledg	ledge-ba ge - II pa	ased systems.	4	0
schedule (syllabus)	Logical reasoning. I conditional probabil models). Fuzzy (fuz		6	0			
	Knowledge and sto storage knowledge script, frames, prod		2	0			
	Machine learning (u			l superv	ised)	4	0
	Examples of applica systems. Processin vision.		2	8			
	The programming la	anguage	e LISP			0	15
	The programming la	anguage	e Prolog	and exp	ert system shell	0	15
Format of instruction		□ partial e-learning					
Student responsibilities	The presence on le Performed all requi				t least 70 % of the	times sche	eduled.
Screening student work (name the	Class attendance	1,5	Researc		Practical tr	raining	
proportion of ECTS	Experimental work		Report		Individual	work	
credits for each activity so that the	Essay		Semina essay	r		Laboratory exercises	
total number of ECTS credits is equal to the ECTS value of the	Tests		Oral exa	am	Preparatio laboratory		
course)	Written exam	2	Project		(Otl	her)	
Grading and evaluating student work in class and at the final exam	The exam consists the semester will be second at 18 weeks exams in June and points through coll condition for taking The exam is complet tasks with auditory student has a total 25% passing the th a student has less points from the th	be two s. A stud d July, s oquia ta the fina rehensive exercis of at le eoretica than 2	tests. The dent can students ake the l exam is ve and in ses. The ast 50% al part of the 5% of the	e first c pass the who hav whole success cludes t condition on the e he mate e points	olloquium in 8 we e course by these re not collected in ubject covered by sfully finished prace he theoretical par on for positive ass exam or when it m erial and 25% of the on the tasks and	eeks of cla tests. In the adequate r the two to tical lab exe t of the ma sessment is ust have a e deposited I / or less t	sses, the e two final umber of ests. The ercises. terial and that the minimum duties. If han 25%

	Students who did not pass the exam after two fina autumn periods. All test questions students will be k							
	These rules apply equally to students who are enrol and to those students who enter college for the second		for the first time					
	The final grade is determined as follows: percentage Rating 50% to 61% is sufficient (2) 52% to 74% good (3) 75% to 87% of very good (4) 38% 100% Excellent (5)							
	the first colloquium will take the material to the teaching units to the seventh week inclusive, and on the other the rest of the teaching weeks. Examinations are held in terms of the anticipated calendar of classes.							
	Under Article 65 of the Statute of the Faculty, the student is required to participate in all forms of teaching and attend: lectures at least 70% of classes. If she or he do not meet these requirements, the student will not be able to take the exam and get a signature.							
	Title Number of copies in the library							
Required literature (available in the library and via other media)	D.Stipaničev, Lj. Seric, Lectures from artificial intelligence, lecturing notes and internal textbook		e-learning portal					
Optional literature (at the time of submission of study programme proposal)	 A.Cawsey, The Essence of Artificial Intelligence, P S.Russel, P.Norvig, Artificial Intelligence: A Modern Ed. 2002. AI on the Web (<u>http://http.cs.berkeley.edu/%7Erust</u> American Association for Artificial Intelligence (wwwwwwwwwwwwwwwwwwwwwwwwwwwwwwwwwwww	n Approach, Pi <u>sell/ai.html</u>)						
Quality assurance methods that ensure the acquisition of exit competences	 Evaluation of results in accordance with the Feedback from students via surveys Self-evaluation of teachers Institutional and non-institutional evaluations 	above learnin	g outcomes					
Other (as the								

NAME OF THE COURSE	BIOELECTRICAL SYSTE	MS AND EQUIPMENT								
Code	FELG17	Year of study	2.							
Course teacher	Mirjana Bonković, Ph.D., Full Professor	Credits (ECTS)	5							
Associate teachers	Zoran Valić, Ph.D., Full Professor	Type of instruction (number of hours)	L 30	S 0	AE 0	LE 30	DE 0			
Status of the course	Elective	Percentage of application of e-learning	0		1		1			
	COURSE	E DESCRIPTION								
Course objectives	 scientific disciplines sure rehabilitation engineering physiological principles necessary precondition basic methods for bioe 	ical engineering as area th ich as biomechanics, biom ing, biotechnology, tissue of s underlying the formation of for the functionality of me electric signals analysis and	at impinat impinaterials aterials engine of bioe edical of d proce	inge or s, med ering a lectric liagnos	n the v ical im ind so signal stic de	arious aging on. s whic vices.	, h is			
Course enrolment requirements and entry competences required for the course		functional components of typical diagnostic devices based on these analysis.								
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 define the reasons and define the sensors and define the functionality define and comment p bioelectric signals to m 	 Students will be able to: define the reasons and the principles causing the bioelectric signals formation. define the sensors and their functionality for measuring the bioelectrical activity define the functionality of some of the typical medical diagnostic devices. define and comment procedures which should be applied to the measured bioelectric signals to make them useful in diagnosis. apply the appropriate procedures to remove the noise and / or detect specific procedures form the measured bioelectric signals. 								
	Course content						or S			
	Biomedical engineering: hi	storical perspective					ours 2			
	Anatomy and physiology.						2			
	Bioelectric phenomenon.						2			
	Biomedical sensors.						2			
	Biomedical devices.						2			
		is and processing								
Course content broken down in	Bioelectrical signals analys Characteristics and method		nd resp	iratory			2 6			
detail by weekly	signals processing.	odical images					4			
class schedule	Analysis and processing medical images.									
(syllabus)	Devices for medical diagnostics.									
	List of laboratory or design exercises									
	Biomedical sensors. Biomedical devices. Functio unit)	onal components (Sensors	s, ADC	, proce	essing		6 4			
		is and processing					6			
	Bioelectrical signals analysis and processing. Physiological modeling.									
	Biomechanics.									
	Analysis and processing of	madicalimanaa					2 6			

Format of instruction	 lectures seminars and workshops exercises on line in entirety partial e-learning field work 			⊠ mul ⊠ labo	 independent assignments multimedia laboratory work with mentor (other) 			
Student responsibilities								
Screening student work (name the	Class attendance	2	Researc	h		Practical traini	ng	
proportion of ECTS	Experimental work		Report Ir		Individual work	K	0,6	
credits for each activity so that the	Essay		Seminar essay 1 L		Laboratory exe	ercises	0,8	
total number of ECTS credits is equal to the ECTS	Tests	0,2	Oral exa	ım		Preparation for laboratory exe		0,2
value of the course)	Written exam	0,2	Project			(Other)		
Grading and evaluating student work in class and at the final exam	of lectures and the se defense of the project in a written format wir positive assessment o + M2)/2) or the final ex- midterm exams, as lor Grade (in percentage) Grade(%) = 0,1L + 0,4 where: • L – laboratory • M1, M2 – mid According to Article 6 activities attending at	<pre>uring the semester there are two midterm exams. The first midterm exam is after 7 we f lectures and the second one is after 13 weeks of lectures (in a form of presentation efense of the project assignment). Each midterm test (as well as the final test) is carried a written format with duration of 90 minutes. The requirement for passing grade is ositive assessment of laboratory exercises and 50 % points on average midterm exam (M2)/2) or the final exam. Students are allowed to have at least 45% of total points on e nidterm exams, as long as the final midterm average is at least 50% of total points. arade (in percentage) is formed according to the formula: arade(%) = 0,1L + 0,45M1 + 0,45M2 there: L – laboratory assessment, M1, M2 – midterm test results.</pre>						
Deswined literature		Title	•			Number of copies in the library	Availabi other n	-
Required literature (available in the library and via other media)	J.D.Enderle, S.M.Bla Introduction to biomo Press, 1999	edical e	ngineerin	g, Acac			e-learnin	-
	Ante Šantić: Biomec knjiga, Zagreb, 1995		elektronil	ka, Ško	lska		e-learnin	g
Optional literature (at the time of submission	 Knjiga, Zagreb, 1995. R. Palaniappan: Biological Signal Analysis (http://bookboon.com/en/introduction-to-biological-signal-analysis- ebook#download) 							
of study programme proposal)	ebook#download		 Keeping records of student attendance. Annual analysis of course statistics in terms of midterm and finals exams. Feedback from students via surveys. Teacher self-evaluation. Feedback from graduated students (or senior students) on course content relevance. Periodic institutional evolution of course teachers. 					
of study programme	 Keeping records o Annual analysis of Feedback from stu Teacher self-evalu Feedback from grade 	course s dents via ation. aduated s	a surveys. students (c	terms o or senior	students			nce.

NAME OF THE COURSE	CAD IN AUTOMATIC CONTROL	-						
Code	FELG15	Year of study	1.					
Course teacher	Mojmil Cecić,. Ph.D., Full Professor Ana Kuzmanić Skelin, Ph.D., Assistant Professor	Credits (ECTS)	5					
		Type of	L	S	AE	LE	DE	
Associate teachers	Tomislav Pezelj, mag. ing.	instruction (number of hours)	30	0	0	30	0	
Status of the course	Elective	Percentage of application of e- learning						
	COURSE DESC							
Course objectives	 Training students: to develop an understanding of computers role in design of automatic control systems to understand techniques and apply CAD tools for analysis and design of feedback control systems to understand techniques and apply CAD tools for analysis and design of analog and digital electronic circuits 							
Course enrolment requirements and entry competences required for the course	completed undergraduate course in classic linear control theory							
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will able to: apply knowledge of design pro- use analytical methods and ex- control tasks use CAD tools to aid the designer of the the designer of the the the the the the the the the the	xperimental simulat on process ont for modeling and ation of electronic o	tion to s	solve s ating t	simple he aut	omatic		
	Course content	•			L		١E	
		C			hours		ours	
	Introduction: computers in automa				1		n/a	
	VISSIM: fundamentals, block diag				1	r	ı/a	
	VISSIM: block arrangements and properties and parameters, basic VISSIM: setting and solving advar		2		n/a n/a			
Course content broken down in	operations, solving differential equ VISSIM: creating models hierarch		diagran	ns,	2		i/a	
detail by weekly	replacement blocks VISSIM analysis of different system	mc			2		ı/a	
class schedule	MATLAB-Simulink: fundamentals,		d ite		2			
(syllabus)	properties	SIUCK UIAYIAIIIS AII			1	r	ı/a	
	MATLAB-Simulink: block arranger simulation properties and paramet operations, solving differential equ	ters, basic mathem			2	r	ı/a	
	ELECTRONIC WORKBENCH (EV elements and its properties	VB): fundamentals,		-	1	r	ı/a	
	ELECTRONIC WORKBENCH (EV electronic circuits	VB): simulation of a	analogu	le	2	r	ı/a	

	ELECTRONIC WOR electronic circuits (T		CH (EWB)): simul	ation of	digital	2	n/a	
	ELECTRONIC WOR electronic circuits (C		CH (EWB)): simul	ation of	digital	2	n/a	
	PROTEL (Schematic basic components): fundam	entals,	represe	ntation of	2	n/a	
	PROTEL (PCB Edito			esentati	on of ba	ISIC	2	n/a	
	components and it's PROTEL: simulation			inital cir	cuits		2	n/a	
	List of laboratory or o			igital on	ouno		-	LE hours	
		SSIM: block diagrams, solving differential equations							
		SSIM: simulation of simple configurations							
	VISSIM: simulation o				3			2	
	MATLAB-Simulink: b					al equations	3	2	
	MATLAB-Simulink: s		-				-	2	
	MATLAB-Simulink: s	imulatio	n of com	plex sys	stems			3	
	EWB: simulation of a	WB: simulation of analogue circuit							
	EWB: simulation of digital circuit							3	
	PROTEL (Schematic Editor): drawing electric circuit scheme							3	
	PROTEL (PCB Edito	ROTEL (PCB Editor): drawing printed circuit scheme							
Format of instruction	 □ seminars and workshops □ exercises □ on line in entirety □ partial e-learning □ field work □ independent assignments □ multimedia □ aboratory □ work with mentor □ (other) 								
Student responsibilities	At least 70% attenda All laboratory assign					ours is requi	red.		
Screening student work (name the	Class attendance	2	Researc	h		Practical tra	aining		
proportion of ECTS credits for each	Experimental work		Report			Independe	nt work	2,5	
activity so that the total number of	Essay		Seminai essay	r	0,2	(Oth	ner)		
ECTS credits is	Tests	0,2	Oral exa	am		(Oth	ner)		
equal to the ECTS value of the course)	Written exam	0,1	Project			(Oth	ner)		
Grading and evaluating student work in class and at the final exam	weeks of lecturing a consists of 3 prob Students that did no consist of 6 proble correctly solved pro	Written exam0,1Project(Other)There are two midterm exams and final exam. The first midterm exam is after 7veeks of lecturing and the second one is after next 6 weeks. Each midterm testconsists of 3 problem questions. Students carry out tests using computers.Students that did not pass the midterm exams take part in final exam. Final examconsist of 6 problem questions. Grade is formed according to the number ofcorrectly solved problem questions: 50 % points on midterm exams or the finalexam is required for passing grade.							

Required literature	Title	Number of copies in the library	Availability via other media				
(available in the	VISSIM, User Guide	1					
library and via other media)	MATLAB-Simulink, User Guide	1					
	Electronics Workbench, User Guide	1					
	Cecić, M.: PROTEL, Interna skripta, FESB, Split, 2001	0	e-learning portal				
Optional literature (at the time of submission of study programme proposal)	 Zanchi, V.; Cecić, M.; Cecić, M.: Programska podrška linearnoj teoriji automatske regulacije, FESB-Split, 1990. 						
Quality assurance methods that ensure the acquisition of exit competences	 Evaluation of results in accordance with learning Feedback from students via surveys Self-evaluation of teachers Institutional and non-institutional evaluations 	outcomes					
Other (as the proposer wishes to add)							

NAME OF THE COURSE	COMPUTATIONAL INTEI	LLIGENCE (NEURO-FUZ	ZY-GEN	IETIC	SYST	EMS))		
Code	FELG18	Year of study	1						
Course teacher	Darko Stipaničev, Ph.D., Full Professor (40%) Toni Jakovčević,Ph.D., Assistant Professo (30%) Marin Bugarić,Ph.D.(30%)	Credits (ECTS)	5	5					
Associate teachers	Dunja Gotovac,mag.ing (100%)	Type of instruction (number of hours)	L 30	S 0	AE 0	LE 30	DE 0		
Status of the course	Elective	Percentage of application of e-learning	80						
	COURSE	DESCRIPTION	-						
Course objectives	The aim of the course is to teach students basic knowledge in the field of computational intelligence, and above all in the theory and application of fuzzy (fuzzy) sets, artificial neural networks and genetic algorithms.								
Course enrolment requirements and entry competences required for the course	0 1	Basic knowledge of computers and programming. To follow the College is necessary knowledge of English.							
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to successfully mastering the subject: Explain what is intelligence, computational intelligence, artificial intelligence and distributed intelligence. Understand the theoretical basis of the theory of fuzzy sets. Basic definitions and mathematical operations. Fuzzy set, fuzzy relations, composition of fuzzy relations. Fuzzy production systems. Linguistic modelling based on fuzzy sets. The application of fuzzy sets in modelling, control, forecasting, decision-making. Understand the theoretical foundations of artificial neural networks (ANN). Types of networks and their division. Setting weight. The activation functions. Hebb network. Perceptron. Associates sample. Learning algorithms (Hebbean rule, delta rule). Neural networks based on competition. Adaptive Resonance Theory. The neural network of the type "Back-propagation". Application of ANN in signal processing, pattern recognition, business. Understand the theoretical foundations of evolutionary processes in nature (genetic code, cross correlation and mutation). Genetic algorithms as an example of artificial evolutionary process. A simple genetic algorithms (the fitness function, selection procedures, genetic operators). Adaptive genetic algorithms. Parallel genetic algorithms. Selection Procedures (proportional selection, ranking selection, elimination tournament selection). Application of 								
	Course content				_ or S		_E ours		
	Intelligence, computational and distributed intelligence		ligence		2		0		
Course content broken down in detail by weekly class schedule (syllabus)	Introduction to the theory o mathematical operations. F composition of fuzzy relation Linguistic modelling based fuzzy sets in modelling, con	f fuzzy sets. Basic definition Fuzzy set, fuzzy relations, ons. Fuzzy production syst on fuzzy sets. The application- intol, forecasting, decision-	ems. ation of making.		8		0		
	fuzzy sets in modelling, contol, forecasting, decision-making.Introduction to the theory of artificial neural networks (ANN).Types of networks and their division. Setting weight. The activation functions. Hebb network. Perceptron. Associates sample. Learning algorithms (Hebbean rule, delta rule). Neural								

	The neural network Application of ANN i	etworks based on competition. Adaptive Resonance Theory. The neural network of the type "Back-propagation". Application of ANN in signal processing, pattern recognition, business.							
	Introduction to the nature (genetic code algorithms as an exa simple genetic algor procedures, genetic Parallel genetic algo selection, ranking se	e, cross ample of ithms (th operato prithms. election,	correlatic f artificial ne fitness rs). Adap Selection eliminati	n and n evolutio functio tive gen Proceo	nutation onary pr n, selec netic alg lures (p). Genetic ocess. A ction porithms. roportional	6	0	
	Application of genetic			f11771/ S	ets (Ma	itlah)	0	9	
	Simulation exercises on the theory of fuzzy sets (Matlab) Simulation exercises on the theory of artificial neural networks (Matlab)						0	9	
	Simulation exercises (Matlab)	s on the	theory of	genetio	c algorit	hms	0	8	
Format of instruction	 ☑ I lectures ☑ seminars and workshops ☑ exercises □ on line in entirety □ partial e-learning □ field work □ independent assignmen ☑ multimedia ☑ aboratory □ work with mentor □ (other) 			nts					
Student responsibilities	The presence on lect Performed all require				t least 7	0 % of the t	imes sche	duled.	
Screening student work (name the	Class attendance	1,5	Researc	ch Practical tra			aining		
proportion of ECTS	Experimental work		Report			Individual v	vork		
credits for each activity so that the	Essay		Seminar essay			Laboratory		1,5	
total number of ECTS credits is equal to the ECTS	Tests		Oral exam			Preparation laboratory			
value of the course)	Written exam	2	Project			(Oth	ier)		
Grading and evaluating student work in class and at the final exam	the semester will b second at 18 weeks exams in June and points through collo condition for taking t The exam is compr tasks with auditory student has a total of 25% passing the the a student has less points from the the Students who did m autumn periods. All These rules apply er and to those student The final grade is de percentage Rating	Written exam2Project(Other)The exam consists of a written part and if necessary additional oral exam. During the semester will be two tests. The first colloquium in 8 weeks of classes, the second at 18 weeks. A student can pass the course by these tests. In the two final exams in June and July, students who have not collected inadequate number of points through colloquia take the whole subject covered by the two tests. The condition for taking the final exam is successfully finished practical lab exercises.The exam is comprehensive and includes the theoretical part of the material and tasks with auditory exercises. The condition for positive assessment is that the student has a total of at least 50% on the exam or when it must have a minimum 25% passing the theoretical part of the material and 25% of the deposited duties. If a student has less than 25% of the points on the tasks and / or less than 25% points from the theoretical part of the material again taken the entire exam.Students who did not pass the exam after two final exams can pass the exam in autumn periods. All test questions students will be known before the exam.These rules apply equally to students who are enrolled this course for the first time and to those students who enter college for the second time.The final grade is determined as follows: percentage Rating 50% to 61% is sufficient (2)							

	88% 100% Excellent (5)						
	The first colloquium will take the material to the teaching units to the seventh week nclusive, and on the other the rest of the teaching weeks. Examinations are held in erms of the anticipated calendar of classes. Under Article 65 of the Statute of the Faculty, the student is required to participate n all forms of teaching and attend: lectures at least 70% of classes. If she or he do not meet these requirements, the student will not be able to take the exam and get a signature.						
	Title	Number of copies in the library	Availability via other media				
Required literature	lectures on FESB e-learning system		e-learning portal				
	W.Pedrycz, Fuzzy Control and Fuzzy Systems, J.Wiley & Sons Inc. New York 1989.						
(available in the library and via other media)	Laurene V. Fausett, Fundamentals of Neural Networks, Prentice Hall, 1994.						
	D.E.Goldberg, Genetic Algorithms in Search, Optimisation and Machine Learning, Addison- Wesley Pub. Co., Inc., Reading, Mass., 1989.						
Optional literature (at the time of submission of study programme proposal)	Computational Intelligence – the logical approach (<u>http://www.cs.ubc.ca/spider/poole/ci.html</u>)		<u> </u>				
Quality assurance methods that ensure the acquisition of exit competences	 Evaluation of results in accordance with the a Feedback from students via surveys Self-evaluation of teachers Institutional and non-institutional evaluations 	above learning	outcomes				
Other (as the proposer wishes to add)							

FELG29 Computer aided process control - BETTI

NAME OF THE COURSE	COMPUTER GRAPHICS									
Code	FELK04	Year of study	1.							
Course teacher	Vladan Papić, Ph.D., Full Professor	Credits (ECTS)	5							
	Denis Štajduhar, mag.	Type of instruction	L	S	AE	LE	DE			
Associate teachers	ing.	(number of hours)	30	0	0	30	0			
Status of the course	Elective	Percentage of application of e-learning	0							
	COURSI	E DESCRIPTION								
Course objectives	 understanding of comp design and application 	c principles and algorithms outer graphics technologie is of computer graphics alg in of graphical libraries in p	s, gorithm	s in C	progra		g			
Course enrolment requirements and entry competences required for the course	None									
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to: explain graphical pipeline, analyse basic algorithms of computer graphics, , connect sequence of graphical transformations in order to achieve needed transformation for view, recommend type of shading and animation in order to achieve desired result, critical argue on possibilities and limitations of various display and hardcopy technologies, model simpler objects with computer modelling software tools, , create simpler animations with software tools, create simpler computer programs for object presentation using graphical libraries. 									
	Course content				L		١E			
	Lhund				hours	nc	ours			
	Uvod	d reator avatama interacti			2					
	Image elements, vector an graphics concept	id raster systems, interacti	ve		2					
	Basic algorithms of compu	ter graphics			2					
	Primitives filling and clippin	ng			2					
	Graphical hardware	5			4					
	Antialiasing				2					
	Geometric transformations	6			2					
Course content	Objects in 3D space				2					
broken down in detail by weekly	Curves and surfaces				3					
class schedule	Lightning and shading				3					
(syllabus)	Animation				2					
· · · ·	List of laboratory exercises	3			_	IF	hours			
	Introducton to OpenGL	,					4			
	OpenGL exercise: Animatic	on					2			
	OpenGL exercise: Textures									
	OpenGL exercise: Textures2OpenGL exercise: Texture filters2									
	OpenGL exercise: Ligthing						2			
	OpenGL exercise: Color ble						2			
	OpenGL exercise: 3D						4			
	Blender: modelling						4			
	Blender: animation						4			

Format of instruction	 □ seminars and workshops □ exercises □ on line in entirety □ partial e-learning □ work with 			ltimedia oratory k with m (othe	mentor			
Student responsibilities	The presence on lect Performed all require				it least 7	0 % of the time	es schedu	led.
Screening student work (name the	Class attendance	1,5	Researc	h		Practical traini	ng	
proportion of ECTS	Experimental work		Report			Individual work	(1,4
credits for each activity so that the total number of	Essay		Seminai essay		0,8	Laboratory exe		0,5
ECTS credits is equal to the ECTS	Tests	0,2	Oral exa	am		Preparation for laboratory exe		0,5
value of the course)	Written exam	0,1	Project			(Other)		
Grading and evaluating student work in class and at the final exam	lecturing and the seco answering parts they carried out as written The requirement for p written and accepted final grading (in perce work with max. 30%, (30%+30%+30%+10% Final grade is formed Percentage Grade 50% to 61% sufficien 62% to 74% good (3)	There are two midterms and final exams. The first midterm exam is after 7 weeks of lecturing and the second one is after the next 6 weeks. In the final exams students a answering parts they did not pass in the midterms. The midterm and final exams are carried out as written tests and it lasts for max. 60 minutes. The requirement for passing grade is 50% points on each midterm exam or final exams written and accepted seminar work and positive assessment of laboratory exercises final grading (in percentage), each midterm exam contributes with max. 30%, semin work with max. 30%, lab. exercises with max. 10% out of total possible points (30%+30%+30%+10%). Final grade is formed in the following way: Percentage Grade 50% to 61% sufficient (2) 62% to 74% good (3) 75% to 87% very good (4)						
Required literature		Title)			Number of copies in the library	Availabi other r	-
(available in the library and via other	T Papić, V.: Introduc		•	graphic	CS,		e-lear	-
media)	Faculty textbook, 20	13. (in C	Jroatian)				por	lai
Optional literature (at the time of submission of study programme proposal)	J.D.Foley, A.Dam, S.K (second edition in C), <i>J</i> D.Hearn, M.P.Baker, C F.S.Hill, Jr. i S.M. Kelle education, 2007. Shreiner, D., Woo, M., biblioteka, 2007.	Addison- Computer ey, Comp	Wesley Pu Graphics outer Grap	ublishing , C Vers hics Usi	g Compai sion, Prer ng Open	ny, 1996. ntice Hall; 2nd ed GL, 3rd edition, F	lition, 1996 Pearson	i.
Quality assurance methods that ensure the acquisition of exit competences	 Evaluation of resu Feedback from stu Self-evaluation of Institutional and no 	udents vi teachers	a surveys			arning outcomes		
Other (as the proposer wishes to add)								

NAME OF THE COURSE	COMPUTER METHODS IN BIOENGINEERING									
Code	FELG20 Year of study 1.									
Course teacher	Vladan Papić, Ph.D., Full ProfessorCredits (ECTS)5									
	Josip Musić, Ph.D.,	Type of instruction	L	S	AE	LE	DE			
Associate teachers	Assistant Professor	(number of hours)	30	0	0	30	0			
Status of the course	Elective	Percentage of application of e-learning	0							
	COURSE DESCRIPTION									
Course objectives Training students for: - understanding of standard computer-based methods used in biomec bioengineering Application of simple data processing and visualization methods as v system simulation methods in biomechanics.										
Course enrolment requirements and entry competences required for the course	None									
	Students will be able to:									
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Explain working principles of systems for data acquisition and processing; Interpret standard signals measured during movements; Compare measured and expected movement signals; Critically discuss processed data; Evaluate measured signals using digital image analysis; Write computer program for calculation of anthropometric data using finite elements method. 									
	Course content						or S ours			
Course content broken down in detail by weekly class schedule (syllabus)	Introduction to measurements, data acquisition and processing.									
	Signals and systems for human movement.									
	Statistical methods of data interpretation.									
	Digital image based processing and data interpretation.									
	Data classification.									
	Data visualization.									
	Anthropometric data and calculation based on finite elements method									
	Examples.						6 or DE			
	List of laboratory or design exercises									
	Introduction to MATLAB									
	Signal processing in MATLAB									
	Image processing: Siluettes (Matlab)									
	Image processing: Anthropometry (Matlab)									
	Image processing: Movements (Matlab)						2			
	Statistical classification methods I (Matlab)						2			
	Statistical classification methods II (Matlab)						2			
	Simulation of bilogical systems (Matlab – Simulink and Vissim)									
	Individualn project – seminar work									

Format of instruction	 lectures seminars and workshops exercises on line in entirety partial e-learning field work 			 ☑ independent assignments ☑ multimedia ☑ laboratory ☑ work with mentor ☑ (other) 						
Student responsibilities	The presence on lectures in the amount of at least 70 % of the times scheduled. Performed all required laboratory exercises.									
Screening student work (name the	Class attendance	1,5	Researc	:h		Practical traini				
proportion of ECTS credits for each	Experimental work		Report			Laboratory exe	1,2			
activity so that the	Essay		Seminal essay		1	Individual worl	0,5			
total number of ECTS credits is	Tests	0,2	Oral exa	ım			0,5			
equal to the ECTS value of the course)	Written exam	0,1	Project			(Other)				
Grading and evaluating student work in class and at the final exam	There are two midterms and final exams. The first midterm exam is after 7 weeks of lecturing and the second one is after the next 6 weeks. In the final exams students are answering parts they did not pass in the midterms. The midterm and final exams are carried out as written tests and it lasts for max. 60 minutes. The requirement for passing grade is 50% points on each midterm exam or final exam and positive assessment of laboratory exercises. In final grading (in percentage), each midterm exam contributes with max. 25%, seminar work with max. 40%, lab. exercises with max. 10% out of total possible points (25%+25%+40%+10%). Final grade is formed in the following way: Percentage Grade 50% to 61% sufficient (2) 62% to 74% good (3) 75% to 87% very good (4) 88% to 100% excellent (5)									
Required literature	Title				Number of copies in the library	Availab other	ility via media			
(available in the library and via other media)	V.Papić, Computer methods in bioengineering, FESB (in Croatian)					e-lea poi	rning rtal			
Optional literature (at the time of submission of study programme proposal)	MATLAB tutorial, Ma M. Seul, L. O'Gorma Description, example	ın, M.J.	Sammon					is:		
Quality assurance methods that ensure the acquisition of exit competences	 Keeping records of student attendance. Annual analysis of course statistics in terms of midterm and finals exams. Feedback from students via surveys. Teacher self-evaluation. Feedback from graduated students (or senior students) on course content relevance. 									
Other (as the proposer wishes to add)	/									

NAME OF THE COURSE	COMPUTER SYSTEMS								
Code	FELG02	Year of study							
Course teacher	Maja Štula, Ph.D., Full Professor Toni Jakovčević, Ph.D., Assistant ProfessorCredits (ECTS)5								
A 1 1 1		Type of instruction	L	S	AE	LE	DE		
Associate teachers		(number of hours)	30			30			
Status of the course	Obligatory	Percentage of application of e-learning	10%						
Course objectives Training students for: - Acquiring knowledge on computer architectures (PC, microcontrollers usage - Understanding execution of automatization applications - Acquiring basic knowledge necessary for developing automatization applications on PC architecture									
Course enrolment requirements and entry competences required for the course	Knowing at least one programming language								
000100	Students will be able to:								
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Explain computer architecture and computer systems working principles Present bus protocols and periphery units Explain computer application flow of execution and interaction with users Use PC-control systems for automatization of simple processes Develop PC application for automatization with GUI Compare different PC architectures for automatization system realization 								
	Course content						AE ours		
	Computer architectures		hours 2		0				
	Operating systems role		2		0				
	Visual studio IDE tool		2		0				
	C# programming language		4		0				
	User interface		3		0				
	Event-driven applications of		3		0				
	Permanent data storage		2		0				
Course content	Periodic application execut		2		0				
broken down in	PC-control computer system, architecture, working mode and						0		
detail by weekly class schedule	possibilities		2		0				
(syllabus)	Developing PC-control .NET application						0		
	Distributed control systems						0		
	Communication standards		2		0				
	List of laboratory or design exercises								
	IDE tools usage								
	Developing basic .NET application with user interface								
	Developing basic .NET application with event handling								
	Adding user controls								
	Developing .NET application with permanent data storage								
	Periodic application execut	ion with C# Timer control					3		

	Developing application with PC MotorBee system for DC motor control						rol	4		
	Developing application with PC SteperBee system for step motor control							4		
	Developing application with sound sensor						4			
	Developing application with light sensor							4		
Format of instruction	 ☑ lectures □ seminars and workshops ☑ exercises □ on line in entirety □ partial e-learning □ field work □ independent assignments □ multimedia ☑ laboratory □ work with mentor □ (other) 									
Student responsibilities	The presence on lectures in the amount of at least 70 % of the times scheduled. Performed and uploaded on e-learning portal all required laboratory exercises.									
Screening student work (name the	Class attendance	2	Research			Practical training		0,5		
proportion of ECTS credits for each	Experimental work		Report			(Other)				
activity so that the total number of	Essay		Seminar essay	1		(Other)				
ECTS credits is equal to the ECTS	Tests	0,5	Oral exam	kam 1		(Other)				
value of the course)	Written exam		Project		(Other)					
Grading and evaluating student work in class and at the final exam	 exam is after 7 weeks of lecturing and the second one is after the next 6 weeks. I the final exams students that did not pass the midterm exams take part. Th requirement for passing grade is 50 % points on each midterm exam or the final exam and positive laboratory assessment. Grade (in percentage) is forme according to the formula: Grade(%) = (M1 + M2)/2 the activities in percentage: M1, M2 – test results. 							art. The the final		
Required literature (available in the library and via other media)	Title				Number of copies in the library	Availability vi other media				
	M. Štula, Authorized lecture materials					e-learning portal				
Optional literature (at the time of submission of study programme proposal)	 Kevin James, PC Interfacing and Data Acquisition, Newnes An imprint of Butterworth-Heinemann, 2000. Jan Axelson, Serial Port Complete: COM Ports, USB Virtual COM Ports, and Ports for Embedded Systems Second Edition, Lakeview Research, 2000. 									
Quality assurance methods that ensure the acquisition of exit competences	 Students' surveys for teacher evaluation Students attendance track Annual statistic on passed exam 									
Other (as the proposer wishes to add)										
NAME OF THE COURSE	DIGITAL CONTROL									
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Code	FELG10	Year of study	1							
Course teacher	Darko Stipaničev, Ph.D., Full Professor	Credits (ECTS)	6							
Associate teachers	Josip Musić, Ph.D., Assitant Professor	Type of instruction (number of hours)	S 0	AE 30	LE 0	DE 0				
Status of the course	Obligatory	Percentage of application of e-learning	80							
	COURSI	E DESCRIPTION								
Course objectives	The acquisition of advance knowledge about the processes of analysis and design of digital control.									
Course enrolment requirements and entry competences required for the course	Completed course Linear of	completed course Linear control systems.								
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Identify the difference Explain quantisation of Apply techniques for the holder, D / A converter To model discrete system Modified-Z transform. Know how to identify Describe the discrete system Analyse discrete system Accuracy and error st Analyse discrete system Accuracy and error st Apply various discrete Continuous controller. (setup poles and zeror response). The design State feedback design Establish and implem function of a discrete 	I development of digital m between continuous and of continuous signal by tim restoring continuous signa er. stems using equations diffe Impulse transfer functions impulse transfer function. by system state variables. em as follows: Stability. Ar eady state. em in the frequency doma em), and analyse discrete e control systems design p Design of discrete control es, the procedure based or n of discrete controllers in n principles. ent digital control through controller. roblems of implementation	anagem discrete e, samp l from d erence. S. The e nalysis o in, in cc system rocedur lers bas n the de the pse realizat	e signa bling, iiscret Z-trar quiva of tran omplex by sta res: S sed or finition udo-fi	A / D c e sign hsform lent sy sient i c areas ate var a conti n of th requer impuls	conver als, 0- ation. respon s (root riables ng of th nuous e desin ncy doi se tran	ter. -order -order se. - - - - - - - - - - - - - - - - - - -			
	Course content	· · ·			L or S hours		\E ours			
	Introduction to digital contr and systems, sampling and				6		0			
Course content	Modeling of discrete system transform, modified Z trans	ms - difference equations,			3		8			
broken down in detail by weekly class schedule	Impulse transfer function a function. Parameter identif transfer function				6		2			
(syllabus)	Description of discrete sys	tems by state variables			3		2			
	Analysis of discrete contro transients. Analysis of disc domain. Analysis of discret frequency domain. Analysi state space domain.	rete control systems in control systems in control systems in pseu	mplex do-		6		6			

	Design of discrete co controllers. Discrete			tization of cor	ntinuous	3	2	
	Discrete controller d Kalman method)							
	Discrete controller d	<u> </u>				3	2	
	Realization of impler	ems.	3	2				
Format of instruction	 ☑ lectures □ seminars and workshops ☑ exercises □ on line in entirety □ partial e-learning □ field work □ independent assignm ☑ multimedia ☑ laboratory □ work with mentor □ (other) 							
Student responsibilities	The presence on lec Performed all require				70 % of the t	times sche	duled.	
Screening student	Class attendance	2,5	Researc	h	Practical tr	aining		
work (name the proportion of ECTS	Experimental work		Report		Individual v	work		
credits for each activity so that the total number of ECTS credits is equal to the ECTS	Essay		Seminar essay		Laboratory	exercises		
	Tests		Oral exa	m	Preparation laboratory			
value of the course)			(Oth	ner)				
Grading and evaluating student work in class and at the final exam	the semester will b second at 18 weeks exams in June and points through collo condition for taking t The exam is compression tasks with auditory student has a total of 25% passing the the a student has less points from the the Students who did mathematical these rules apply erand to those student The final grade is de percentage Rating 50% to 61% is suffic 62% to 74% good (3 75% to 87% of very 88% 100% Excellen The first colloquium inclusive, and on the terms of the anticipal Under Article 65 of ti in all forms of teachin not meet these requires	A stud July, si oquia ta he final ehensiv exercis of at lea eoretical than 25 eoretical than 26 eoretical than 26 eoreti	lent can p tudents w ke the w exam is s e and inc es. The o ast 50% o part of the l part of the exam estions stu o students enter colle d as follow) e the mate he rest of endar of cl ute of the attend: le	ass the cours the have not hole subject successfully fi- cludes the the condition for in the exam of the material after two fir idents will be who are enrige for the sec ws: erial to the teaching lasses. Faculty, the ctures at leas	se by these t collected ina covered by nished practi eoretical part positive assor when it mud 25% of the e tasks and again take al exams ca known before olled this cou cond time.	ests. In the adequate in the two the cal lab exect of the material estimation and the estimation and the estimation and the to the seven inations and equired to passes. If sho	e two final number of ests. The ercises. aterial and s that the minimum d duties. If than 25% ire exam. e exam in h. e first time enth week are held in participate e or he do	

	Title	Number of copies in the library	Availability via other media				
Required literature	D.Stipaničev, J.Marasović, Digitalno vođenje on-		e-learning				
(available in the	line, on-line (Web) udžbenik, MZT – Informatički		portal				
library and via other media)	projekt, 2004. <u>http://laris.fesb.hr/digitalno_vodjenje</u>						
modia							
Optional literature (at the time of submission of study programme proposal)	Prentice-Hall Int. series, London, 1996.J.R.Vaccaro, Digital Control – A State Space App	 Prentice-Hall Int. series, London, 1996. J.R.Vaccaro, Digital Control – A State Space Approach, McGrawHill, 1995. J.A.Borrie, Modern Control Systems – A Manual of Design Methods, Prentice Hall Int., 2000 					
Quality assurance	- Evaluation of results in accordance with the above	e learning outo	comes				
methods that ensure	- Feedback from students via surveys						
the acquisition of exit competences	 Self-evaluation of teachers Institutional and non-institutional evaluations 						
Other (as the proposer wishes to add)							

NAME OF THE COURSE	DIGITAL IMAGE PROCES	SSING AND ANALYSIS									
Code	FELG09	Year of study	1								
Course teacher	Damir Krstinić, Ph.D., Associate Professor Darko Stipaničev, Ph.D., Full ProfessorCredits (ECTS)5										
Associate teachers	Maja Braović, Ph.D.	Type of instruction (number of hours)LSAELE3030									
Status of the course	Elective	Percentage of application of e-learning	30%								
	COURSE DESCRIPTION										
Course objectives	 Understanding acquisiti Understanding and usir Application of aritmetic, improve digital images Understanding statistica useful for image interpr 	 Understanding the biological and machine vision Understanding acquisition, encoding and storage of digital image Understanding and using of mathematicam model of digital image Application of aritmetic, gemoetric and logical operations to manipulate and improve digital images Understanding statistical parameters of digital images and extracting features useful for image interpretation 									
Course enrolment requirements and entry competences required for the course	Application of mathematical operations for processing image sequences Knowledge of mathematics										
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 be aware of standards understand the mathem understand and apply to features and image hist apply image processing describe and apply more understand and apply resegmentation understand methods for 	y techniques based on loca phological operations on b nethod for object extracting	transfe gital im e analy al featu pinary i g base	iage sis bas ires mage d on ir	sed on	•	tical				
	Course content				L or S		λE				
	Introduction to digital image	e processing and application	ons		hours 2	nc	ours				
	Biological and machine vis			of							
Course content broken down in	vision CCD camera and conversion signal. Standards: RGB, Y- signal (NTSC, PAL). Syste digitalization of digital image		2								
detail by weekly class schedule (syllabus)	The theory of digital image of digital images. Color ima The mathematical represen digital image. Histograms		2								
	Processing of digital image transformation	es: optimization, reconstruc	ction ar	nd	2						
	Unary operations and LUT	. Geometric operations			2						
	Binary and multi-modal ope operations on digital image		gical		2						

	Preliminary exam					2		
	Convolution and filtering							
	Analysis of digital images: image feature extraction. Extracting objects, Image segmentation					2 2		
	Mathematical morph			a binar	v images	2		
	Form analysis, coun	0, 1				2		
	Color and luminesce		-		,	2		
	Preliminary exam	int anal	, 0.0			2		
	List of laboratory or	design e	exercises				LE hours	
	Image processing an						2	
		ng Matlab for image processing						
		ograms, RGB and HSI color space						
		or space transformation						
	Unary operations and							
	Geometrical operation						2	
	Binary operations on images							
	Preliminary exam						2	
	Convolution and filtering							
	Segmentation							
	Mathematical morph							
	Shape analysis						2	
	Counting and sorting						2	
	Shape identification,	analysi	s of brigh	thes an	d color		2	
	Preliminary exam			1			2	
	Seminars and workshops							
Format of instruction	□ on line in entirety							
	⊠ partial e-learning							
	$\Box \text{ field work} \qquad \Box \qquad \text{(other)}$							
Student								
responsibilities								
Screening student work (name the	Class attendance	1	Researc	ch	Practical tra	aining	1	
proportion of ECTS credits for each	Experimental work		Report		(Oth	er)		
activity so that the total number of	Essay	1	Semina essay	r	(Oth	er)		
ECTS credits is	Tests	2	Oral exa	am	(Oth	er)		
equal to the ECTS value of the course)	Written exam		Project		(Oth	er)		
Grading and evaluating student work in class and at the final exam	• grade achieved	oratory itten ser in two	exercice minar ess peliminar	s ay and y exam	its oral presentation is, or grade achiev ir both preliminary e	ed in fina	al exam, if	

	Title	Number of copies in the library	Availability via other media				
Required literature	Stipaničev, Darko; krstinić, Damir, Uvod u digitalnu obradu i analizu slike, materijali s predavanja, FESB 2011.						
(available in the library and via other media)	A. K. Jain, Fundamentals of Digital Image Processing, ISBN: 0-13-336165-9, Prentice Hall Int., London, 1989.						
	B. Jahne, Digital Image Processing, ISBN: 978-3- 662-11565-7, Springer-Verlag, Berlin, 1991.						
	L.J. Galbiati, Machine Vision and Digital Image processing Fundamentals, PrenticeHall, London 1990.						
Optional literature (at the time of submission of study programme proposal)	 Digital Image Analysis abnd processing, <u>http://www.ph.ac.uk/~wjh/teaching/dia</u> CVIPtools <u>http://www.ee.siue.edu/CVIPtools/</u> Course pages on internal e-learnign portal 	<u>/</u>					
Quality assurance methods that ensure the acquisition of exit competences	 Evaluation of resutls in accordance with the above Feedback from student via surveys Self-evaluation of teachers Institutional and non-institutional evaluations 	 Feedback from student via surveys Self-evaluation of teachers 					
Other (as the proposer wishes to add)							

DIGITAL INSTRUMENTA	TION 2								
FELG16	Year of study	1							
Tihomir Betti, Ph.D., Assistant Professor Ivan Marasović, Ph.D., Assistant Professor	Credits (ECTS)	5							
	Type of instruction (number of hours)	L S AE 30			LE 30	DE			
Elective	Percentage of application of e-learning								
COURSE DESCRIPTION									
- Using frequency and ti	me-frequency for signal ar	nalysis		-		ems.			
				-					
 Describe digital signal acquisition methods, Design appropriate digital filter, Explain reconstruction signal techniques, Use time-frequency transformations for signal analysis, Use wavelet transformation in non-stationary signal analysis 									
Digital signal acquisition te Time and amplitude signal Aliasing and anti-aliasing fi Signal reconstruction. Mathematical representation Frequency transformations Algorithms and windows for Correlation and spectral ar Time-frequency transformation for CWT and DWT algorithms Adaptive wavelet analysis. List of laboratory or design Introduction in MATLAB. Ti Time and amplitude signal Signal reconstruction and a Frequency transformations Algorithms and windows for Correlation and spectral an	chniques. quantization. liter. on of discrete signals. a for signal analysis. or spectral analysis. ations for signal analysis. non-stationary signal anal for signal decomposition. exercises me and frequency signal re quantization in MATLAB. liasing. for signal analysis. r spectral analysis. r spectral analysis.	ysis.	ntatior).		ours 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 3 3 3 3 3 3 3 3 3 3 3			
	FELG16 Tihomir Betti, Ph.D., Assistant Professor Ivan Marasović, Ph.D., Assistant Professor Elective COURSI Training students for: Understanding, recogr Using frequency and ti Understanding and usi Completed course Digital in Students will be able to: Describe digital signal Design appropriate dig Explain reconstruction Use time-frequency tra Use wavelet transform Develop and implemer Course content Introduction. Time and free Digital signal acquisition te Time and amplitude signal Aliasing and anti-aliasing fi Signal reconstruction. Mathematical representation Algorithms and windows for Correlation and spectral ar Time-frequency transformation for CWT and DWT algorithms Adaptive wavelet analysis. List of laboratory or design Introduction in MATLAB. Ti Time and amplitude signal Signal reconstruction and a	Tihomir Betti, Ph.D., Assistant Professor Ivan Marasović, Ph.D., Assistant Professor Credits (ECTS) Assistant Professor Type of instruction (number of hours) Elective Percentage of application of e-learning COURSE DESCRIPTION Training students for: - Understanding, recognition and classifying digita - Understanding, recognition and classifying digita - Understanding and using wavelet transformation Completed course Digital instrumentation 1. Students will be able to: - Describe digital signal acquisition methods, - Design appropriate digital filter, - Explain reconstruction signal techniques, - Use time-frequency transformations for signal an - Use wavelet transformation in non-stationary sign - Develop and implement algorithm for digital signal Course content Introduction. Time and frequency signal representation Digital signal acquisition techniques. Time and amplitude signal quantization. Aliasing and anti-aliasing filter. Signal reconstruction. Mathematical representation of discrete signals. Frequency transformations for signal analysis. Algorithms and windows for spectral analysis.	FELG16 Year of study 1 Tihomir Betti, Ph.D., Assistant Professor Credits (ECTS) 5 Ivan Marasović, Ph.D., Assistant Professor Type of instruction (number of hours) 1 Elective Percentage of application of e-learning 1 Training students for: 0 0 OURSE DESCRIPTION Training students for: 0 Understanding, recognition and classifying digital signal Using frequency and time-frequency for signal analysis Understanding and using wavelet transformations for si 0 Completed course Digital instrumentation 1. 0 Students will be able to: - Describe digital signal acquisition methods, - Design appropriate digital filter, - Explain reconstruction signal techniques, - Use time-frequency transformations for signal analysis, - Use wavelet transformation in non-stationary signal analysis, - Use time-frequency transformations for signal analysis, - Use wavelet transformation in non-stationary signal analysis, - Use wavelet transformation of discrete signals. - Frequency transformations for signal analysis. - </td <td>FELG16 Year of study 1 Tihomir Betti, Ph.D., Assistant Professor Credits (ECTS) 5 Van Marasović, Ph.D., Assistant Professor 5 30 5 Assistant Professor Type of instruction L S Assistant Professor Percentage of application of e-learning 30 5 Elective Percentage of application of e-learning 5 5 COURSE DESCRIPTION Training students for: Understanding, recognition and classifying digital signal proce Using frequency and time-frequency for signal analysis. Understanding and using wavelet transformations for signal a a Completed course Digital instrumentation 1. 5 Students will be able to: - Design appropriate digital filter, - Describe digital signal acquisition methods, - - Design appropriate digital filter, - - Use wavelet transformations for signal analysis, - - Use wavelet transformation for digital signal analysis - - Use wavelet transformation of discrete signals. - - Trepuency transformati</td> <td>FELG16 Year of study 1 Tihomir Betti, Ph.D., Assistant Professor 5 Assistant Professor Credits (ECTS) 5 Assistant Professor Type of instruction (number of hours) L S AE Assistant Professor Type of instruction (number of hours) L S AE Belective Percentage of application of e-learning - - - Training students for: - Understanding, recognition and classifying digital signal processing - Using frequency and time-frequency for signal analysis. - Understanding, recognition and classifying digital signal analysis - - - - Understanding and using wavelet transformations for signal analysis - - - - Understanding and using wavelet transformations for signal analysis -<td>FELG16 Year of study 1 Tihomir Betti, Ph.D., Assistant Professor Credits (ECTS) 5 Assistant Professor Type of instruction (number of hours) 1 30 30 Elective Percentage of application of e-learning 30 30 30 COURSE DESCRIPTION Training students for: - - - - Understanding, recognition and classifying digital signal processing problet - - - - Understanding and using wavelet transformations for signal analysis. - - - - Understanding and using wavelet transformations for signal analysis. - - - Completed course Digital instrumentation 1. - - - - - Students will be able to: -</td></td>	FELG16 Year of study 1 Tihomir Betti, Ph.D., Assistant Professor Credits (ECTS) 5 Van Marasović, Ph.D., Assistant Professor 5 30 5 Assistant Professor Type of instruction L S Assistant Professor Percentage of application of e-learning 30 5 Elective Percentage of application of e-learning 5 5 COURSE DESCRIPTION Training students for: Understanding, recognition and classifying digital signal proce Using frequency and time-frequency for signal analysis. Understanding and using wavelet transformations for signal a a Completed course Digital instrumentation 1. 5 Students will be able to: - Design appropriate digital filter, - Describe digital signal acquisition methods, - - Design appropriate digital filter, - - Use wavelet transformations for signal analysis, - - Use wavelet transformation for digital signal analysis - - Use wavelet transformation of discrete signals. - - Trepuency transformati	FELG16 Year of study 1 Tihomir Betti, Ph.D., Assistant Professor 5 Assistant Professor Credits (ECTS) 5 Assistant Professor Type of instruction (number of hours) L S AE Assistant Professor Type of instruction (number of hours) L S AE Belective Percentage of application of e-learning - - - Training students for: - Understanding, recognition and classifying digital signal processing - Using frequency and time-frequency for signal analysis. - Understanding, recognition and classifying digital signal analysis - - - - Understanding and using wavelet transformations for signal analysis - - - - Understanding and using wavelet transformations for signal analysis - <td>FELG16 Year of study 1 Tihomir Betti, Ph.D., Assistant Professor Credits (ECTS) 5 Assistant Professor Type of instruction (number of hours) 1 30 30 Elective Percentage of application of e-learning 30 30 30 COURSE DESCRIPTION Training students for: - - - - Understanding, recognition and classifying digital signal processing problet - - - - Understanding and using wavelet transformations for signal analysis. - - - - Understanding and using wavelet transformations for signal analysis. - - - Completed course Digital instrumentation 1. - - - - - Students will be able to: -</td>	FELG16 Year of study 1 Tihomir Betti, Ph.D., Assistant Professor Credits (ECTS) 5 Assistant Professor Type of instruction (number of hours) 1 30 30 Elective Percentage of application of e-learning 30 30 30 COURSE DESCRIPTION Training students for: - - - - Understanding, recognition and classifying digital signal processing problet - - - - Understanding and using wavelet transformations for signal analysis. - - - - Understanding and using wavelet transformations for signal analysis. - - - Completed course Digital instrumentation 1. - - - - - Students will be able to: -			

	Adaptive wavelet and	alysis in	MATLAE	8.				3	
Format of instruction	□ seminars and workshops ⊠ multimedia ⊠ exercises ⊠ laboratory □ on line in entirety □ work with n □ partial e-learning □ (otherwork)					nentor			
Student responsibilities	Students should atte laboratory exercises		ast 70%	of the le	ectures.	Students must	complete	e all	
Screening student	Class attendance	1	Researc	h		Practical traini	ng		
work (name the proportion of ECTS	Experimental work		Report			Individual work	K	2	
credits for each activity so that the	Essay		Semina essay			Laboratory exe	ercises	1	
total number of ECTS credits is equal to the ECTS	Tests	0.15	Oral exa	ım		Preparation for laboratory exe			
value of the course)	Written exam	0.1	Project		0,75	(Other)			
Grading and evaluating student work in class and at the final exam	scheduled after 7 we Each midterm exam exam lasts 90 minu and also have a pos The final grade (in p where: • T1, T2 – gra • P – grade fr Students not passin theoretical questions students must score laboratory exercise. where:	 T1, T2 – grade from theoretical questions in midterms given in percentage, P – grade from final project given in percentage, Students not passing the midterm exams take part in the final exam. It consists of theoretical questions problems and lasts 165 minutes. For passing the final exam, students must score at least 50%, as well as have a positive assessment of the aboratory exercise. The grade on final exams is determined by the formula: Grade(%) = 0.6(T)+0.4(P), where: T – grade from theoretical questions given in percentage, 							
		Title				Number of copies in the library	Availab other	media	
Required literature	S. Beroš: Digitalna i predavanja, FESB	nstrume	ntacija 2,	autoriz	zirana		e-lea poi	•	
(available in the library and via other media)	J.M. Candy: Signal F Approach, McGraw-		ing – The	Moder	'n				
	I. Daubechies: Ten I Industrial and Applie				-				

Optional literature (at the time of submission of study programme proposal)	 A.V. Oppenheim, R.W. Schafer: Discrete-time Signal Processing, Prentice-Hall D. Brook, R.J. Wynne: Signal Processing, Edward Arnold, London L.B. Jackson: Digital Filters and Signal Processing, Kluwer Academic Press, Boston M.V. Wicherhauser: Adapted Wavelet Analysis from Theory to Software, IEEE Press
Quality assurance methods that ensure the acquisition of exit competences	 Record of number of students attending the classes Evaluation of results in accordance with expected learning outcomes Feedback from students via student surveys Teachers self-evaluation Institutional and non-institutional evaluations
Other (as the proposer wishes to add)	

NAME OF THE COURSE	DIGITAL SYSTEMS PROJECTING									
Code	FELH07	Year of study	1							
Course teacher	Julije Ožegović, Ph.D., Full Professor	Credits (ECTS)	5							
Associate teachers	Vesna Pekić, Ph.D. Ante Kristic, Ph.D.	Type of instruction (number of hours)								
Status of the course	Obligatory	Obligatory Percentage of application of e-learning 0								
	COURS	E DESCRIPTION								
Course objectives	hardware definition lan	nced knowledge of digital s guages, block synthesis m ex programmable logic stru	ethods	and s						
Course enrolment requirements and entry competences required for the course	None									
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to: design digital systems using program definition of hardware organize HDL modeling and synchronization create a system using HDL syntax and functions libraries evaluate results of simulation measurements justify application of CPLD and FPGA architectures 									
	Course content		L hours		∖E ours					
	Approach to program spec		2		0					
	Verilog basic syntax.				2		0			
	Logic gate level modelling.				2		0			
	Fields of logic gates.				2		0			
	Bistables at the logic gate	level.			2		0			
	Delay, power and types of				2		0			
	Data flow level modelling.				2		0			
	Behavioral level modelling				2		0			
a	Behavioral level modelling				2		0			
Course content broken down in	Control structures on beha	vioral level.			2		0			
detail by weekly	Functions and tasks. User	defined elements.			2		0			
class schedule	Transistor level modeling.				2		0			
(syllabus)	Development system man	agement.			2		0			
	Advanced digital structures	-			2		0			
	CPLD and FPGA program		ure.		2		0			
	List of laboratory or design						nours			
	Programmable logic develo						4			
	Verilog language syntax ap	plications.					4			
	Signal power, fields of logic	c gates.					4			
	Data flow level modelling.						4			
	Behavioral level modeling.	defined along outs					4			
	Functions and tasks. User Advanced digital structures						4 4			
	nuvanueu uigitai struutures						+			

Format of instruction	 ☑ lectures □ seminars and wo ☑ exercises □ on line in entirety □ partial e-learning □ field work 	nt assignments nentor er)									
Student responsibilities		Attend all forms of teaching, pass ingress and egress tests, perform 100% aboratory exercises, pass preliminary exams or full exam (numeric and theory).									
Screening student work (name the	Class attendance	1	Researc	h		Practical traini	ng	1			
proportion of ECTS credits for each	Experimental work		Report			Auditory exerc	ises	0,5			
activity so that the total number of	Essay		Seminai essay			Individual lear	ning	2,5			
ECTS credits is	Tests		Oral exa	ım		(Other)					
equal to the ECTS value of the course)	Written exam		Project			(Other)					
Grading and evaluating student work in class and at the final exam	Continuous assessment: laboratory tests, practical tests, knowledge tests, preliminary exams. Exam: written and oral (numeric and theory) as unity.										
		Number of copies in the library	Availabi other r	-							
Required literature (available in the library and via other media)	1. T. R. Padmanab "Design Through - Willey Interscie		Inter	net							
Optional literature (at the time of submission of study programme proposal)	 Lecture notes: O upgraded A. Kristić: Upute 	za laboi	ratorijske		Ū		ntinuously	,			
Quality assurance methods that ensure the acquisition of exit competences	 Lecture attending e Annual exam pass Student feedback e Teacher self-evalu Graduated student 	ing analy with teac ation	/sis her evalua	ition							
Other (as the proposer wishes to											

NAME OF THE COURSE	ELECTRIC SERVO DRIVES									
Code	FENG03	Year of study	2.							
Course teacher	Božo Terzić, Ph.D., Full Professor	Credits (ECTS)	5							
Associate teachers	Goran Majić, Ph.D.	Type of instruction (number of hours)	L 30	S 0	AE 0	LE 30	DE 0			
Status of the course	Elective		1							
	COURSI	E DESCRIPTION								
Course objectives	Training students for: - understanding the stru drives	 understanding the structure and operation principle of electric servo motors and 								
Course enrolment requirements and entry competences required for the course	- Basic knowledge of the									
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to: select the type, power and speed of the motor for defined duty cycle, select power converter for servo drives, as well as speed and rotor position sensor of servo motor, set basic parameters of power converter for simpler servo drives, optimize parameters of speed and rotor position controllers using experimental methods, measure and analyse motor current and voltage waveforms detect and solve simpler problems and failures in electric servo drives. 									
	Course content						\E ours			
	The basic structures of classic and modern electric servo drives. Application of servo drives in machine tools, robotics and cars.						0			
	Mechanical systems in servo drives. Calculation and reduction of moment of inertia. Mechanical transmissions, shafts, bearings and mechanical couplings.						0			
	DC motors. Operation principle and methods of speed change. Dynamic characteristics and transfer function of DC motor.						0			
Course content	Speed control of DC motor. Thyristor rectifier for voltage control of DC motor. Control structures and for speed control DC motor. Methods for adjusting the controller parameters.						0			
broken down in detail by weekly class schedule (syllabus)	Step motors. Operation pri permanent magnet, relucta Stepper motor control circu the microstep operation.	ance and hybrid step moto uit. The control of stepper r	rs. motor ir	n	2		0			
	Three-phase inverters for s space vector pulse width m	nodulation of three-phase	inverter							
	The permanent magnet motors. Brushless DC motors (BLDCM). Voltage and current waveforms of the BLDCM. Control structures of BLDCM drives. Speed control of the BLDCM.					2				
	Permanent magnet synchronous motor (PMSM). Basic structure and operation principle. Voltage and current waveforms of the PMSM. Vector control of PMSM.						0			
	Servo drives with induction vector control of the IM.				2		0			
	Induction motors. Basic co	nstruction and operation p	rinciple							

	Equivalent circuit an	d torque	charact	ristics	Startin	n and		
	speed control of indu			51131103.	Starting	y and	2	0
	Presentation of stud							
	Servo drives with inc of induction motor.	duction i	motor. Ro	otor flux	oriente	d control	2	0
	Linear motors. Oper motors. Basic contro	•	•			s for linear	2	0
	Motor speed and rot and sin/cos encoder	or posit	ion sensc			l, absolute	2	0
	Communication inte	rfaces ir	n servo di		ROFIB	JS,	2	0
	Industrial Ethernet, C Examples of servo d	lrives in	machine	tools a	nd robo	tics.	2	0
	Presentation of stud		actical wo	ork.				
	List of laboratory exe							LE hours
	Stationary characteri		DC moto	r				3
	Speed control of DC		20					3
	Speed control of Brue					<u></u>		3
	Vector control of perr Servo drive with step							3
	Stationary characteri				peratio	11		3
	Vector control of indu			motor				3
	Rotor position measu			ementa	lencod	er		3
	Positioning system w							3
	Positioning system w			-	,			3
Format of instruction	 ☑ lectures ☑ seminars and workshops ☑ exercises ☑ on line in entirety ☑ partial e-learning ☑ independent assignme ☑ independent assignme ☑ multimedia ☑ laboratory ☑ work with mentor ☑ (other) 						nts	
Otypicant	☐ field work		4		4 1 4 -	70.0/ = f +h = +		a alcal a al
Student responsibilities	The presence on lect Performed all require				t least <i>i</i>	0 % of the t	imes sche	eduled.
Screening student work (name the	Class attendance	1	Researc			Practical tra	aining	
proportion of ECTS	Experimental work		Report			Individual v	vork	1
credits for each activity so that the	Essay		Semina essay	•	1	Laboratory		s 1
total number of ECTS credits is	Tests		Oral exa	ım		Preparation laboratory		1
equal to the ECTS value of the course)	Written exam		Project					
Grading and evaluating student work in class and at the final exam								

	Students who did not pass the exam after two final exams take a makeup exam in the autumn period according to the same way as the final exam. The final grade is obtained by the same criteria as for two final exams.						
Required literature (available in the	Title	Number of copies in the library	Availability via other media				
library and via other media)	B. Terzić: Authorized lectures, FESB		e-learning portal				
Optional literature (at the time of submission of study programme proposal)	 N. Mohan, Electric Drives - an integrative approad SAD, 2001. 	 N. Mohan, Electric Drives - an integrative approach, MNPERE, Minneapolis, SAD, 2001. T. J. E. Miller, Brushless Permanent Magnet and Reluctance Motor Drives, 					
Quality assurance methods that ensure the acquisition of exit competences	 Evaluation of results in accordance with the above learning outcomes Feedback from students via surveys Self-evaluation of teachers Institutional and non-institutional evaluations 						
Other (as the proposer wishes to add)							

NAME OF THE COURSE	ELECTRONIC AND VIRT	UAL INSTRUMENTATIO	N				
Code	FELG07	Year of study	1.				
Course teacher	Ivo Mateljan, Ph.D., Full Professor	Credits (ECTS)	5				
		Type of instruction	L	S	AE	LE	DE
Associate teachers		(number of hours)	30			30	
Status of the course	Obligatory	Percentage of application of e-learning	0				
	COURS	E DESCRIPTION					
Course objectives	- programming for virtua	chastic and deterministic s		ectroni	c mea	surem	ent,
Course enrolment requirements and entry competences required for the course	None						
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 define electronic circu define techniques use apply digital algorithm crosscorrelation and s measure spectrum an 	ectronic instrumentation ch it for measurement sensor d to measure stochastic ar s for mean value, rms valu pectrum estimation. d system frequency respor ual instrumentation, with m	s applic nd dete e, FFT nse	cation rminis , autoc	orrela	tion,	neter
	Course content				L		ΑE
	Metrology				hours 2	nc	ours
	Statistical analysis of mea	surements			2		
	Uncertainity of measureme				2		
	Analog signals and system				2		
	Discrete signals and syste				2		
	Random signals, spectral				2		
		e and frequency response			2		
	Basic electronic circuits fo				2		
Course content	Signal generators				2		
broken down in	AD and DA converters				2		
detail by weekly	Standars interfaces				2		
class schedule	Virtual instrumentation				2		
(syllabus)	Distributed measurement	svstems			2		
	List of laboratory or design exercises						
	Spectral analysis and disto	ortion of signals					ours 2
	PC souncard quality meas						2
	Deterministic and random	signals					2
	Frequency response meas						2
	Impulse response measure						2
	SFT and Wavelet signal ar						2
	Bandpass and heterodyne						2
	Use of Matlab in measuren	nents					2

Format of instruction	\boxtimes seminars and worksnops \boxtimes exercises \square on line in entirety			ltimedia pratory k with n				
Student responsibilities								
Screening student work (name the	Class attendance	2.5	Researc	ch		Practical traini		
proportion of ECTS	Experimental work		Report Ir		Individual worl	k	1	
credits for each activity so that the total number of	Essay		Seminar essay 0.5 L		Laboratory wo	ork	0.5	
ECTS credits is	Tests		Oral exa	am		(Other)		
equal to the ECTS value of the course)	Written exam		Project		0.5	(Other)		
Grading and evaluating student work in class and at the final exam	student presentation learning check out grade is the positive seminar work or the formula:	on eve assess final e	ry labora sment of	atory ex laborate	kercise. ory exei	The requiren 9 cises and 50	nent for % points	passing on each
	the activities in perce SR – semina LV – laborat UI – final exa	entage: ar, ory ass	le(%) = 0 essment,	,1 SR +	- 0,1 LV	+ 0,8 UI		
	 SR – semina LV – laborat 	entage: ar, ory ass	essment,	,1 SR +	- 0,1 LV	+ 0,8 UI Number of copies in the library		ility via media
Required literature	 SR – semina LV – laborat UI – final exa 	entage: ar, ory asse am. Title	essment,			Number of copies in the library	other	-
Required literature (available in the library and via other	 SR – semina LV – laborat UI – final exa Ivo Mateljan: Electro script, FESB,	entage: ar, ory ass am. Title nic and	essment, e Virtual Ir	nstrume	ntation,	Number of copies in the library	other Inte	media
Required literature (available in the	 SR – semina LV – laborat UI – final exa Ivo Mateljan: Electro script, FESB, Ivo Mateljan: Labora Virtual Instrumentation 	entage: ar, ory ass am. Title nic and tory Exe on, scrip	virtual Ir ercise in l	nstrume Electror 2007.	ntation, nic and	Number of copies in the library	other Inte	media rnet
Required literature (available in the library and via other	 SR – semina LV – laborat UI – final exa Ivo Mateljan: Electro script, FESB, Ivo Mateljan: Labora Virtual Instrumentation Ivo Mateljan: ARTA se 	entage: ar, ory ass am. Title nic and tory Exe on, scrip	virtual Ir ercise in l	nstrume Electror 2007.	ntation, nic and	Number of copies in the library	other Inte	media rnet
Required literature (available in the library and via other	 SR – semina LV – laborat UI – final exa Ivo Mateljan: Electro script, FESB, Ivo Mateljan: Labora Virtual Instrumentation 	entage: ar, ory ass am. Title nic and tory Exe on, scrip	virtual Ir ercise in l	nstrume Electror 2007.	ntation, nic and	Number of copies in the library	other Inte	media rnet rnet

NAME OF THE COURSE	ELECTRONIC CIRCUITS							
Code	FELH13	Year of study	2.					
Course teacher	Ivan Marinović, Ph.D., Full Professor	Credits (ECTS)	5					
Associate teachers	Duje Čoko, Ph.D., Assistant Professor	Type of instruction (number of hours)	L 15	S	AE 15	LE 30	DE	
Status of the course	Elective: 210 Obligatory: 221	Percentage of application of e-learr	ning					
	COURSE	DESCRIPTION						
Course objectives	Training students for: - synthesis of electronic - analysis of complex ele - projecting of simple ele	ectronic circuits						
Course enrolment requirements and entry competences required for the course	Finished coarse <i>Electronic circuits</i>							
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to: design electronic circuits construct a prototype of the projected circuit make measurements of electronic parameters applying oscilloscopes and analyzers understand principles of operation of more complex circuits 							
	Course content				L		AE ours	
	Synthesis of electronic circ	uits			2		2	
	Cutoff frequencies as para				1		1	
	Design of feedback amplifi	-			1		1	
	Operational amplifiers, slev				3		3	
Course content	C-class, D-class and E-clas				2		2	
broken down in	Energy converters, rectifier		oltage, LM72	23	3		3	
detail by weekly class schedule	Switching regulators		U /		1		1	
(syllabus)	Timers, NE555				1		1	
	Oscillators				1		1	
	List of laboratory or design	exercises					_E ours	
	Electronic project: construct simulation, PCB design and measurements on the devic	construction, solderi			3		30	
Format of instruction	measurements on the device, final report) □ lectures □ seminars and workshops □ exercises □ on line in entirety □ partial e-learning □ field work							
Student responsibilities	The presence on lectures a scheduled. Performed all re			least 7	70% o	f the ti	mes	

Class attendance	2	Research		Practical traini	ng			
Experimental work		Report		Exercises		1		
Essay		Seminar essay		Individual work	ĸ	2		
Tests		Oral exam		(Other)				
Written exam		Project		(Other)				
5	he course will be graded according to outcomes of the project and oral exam. psolute grading is applied.							
	Number of copies in the library	Availability via other media						
knjiga, Zagreb • U. Tietze, C. Sch	5							
 Evidence of stude Annual analysis of Teachers self-eva 	f grades luation	achieved	urveys		<u> </u>			
	Experimental work Essay Tests Written exam The course will be g absolute grading is a P. Biljanović: Ele knjiga, Zagreb • U. Tietze, C. Sch circuits - Evidence of stude - Annual analysis o - Teachers self-eva	Experimental work Essay Tests Written exam The course will be graded a absolute grading is applied. Title P. Biljanović: Elektroničk knjiga, Zagreb U. Tietze, C. Schenk, Ac circuits - Evidence of students atter Annual analysis of grades Teachers self-evaluation	Experimental work Report Essay Seminar essay Tests Oral exam Written exam Project The course will be graded according to outc absolute grading is applied. Title • P. Biljanović: Elektronički sklopovi, Škols knjiga, Zagreb • U. Tietze, C. Schenk, Advanced electron circuits • Evidence of students attendance - Annual analysis of grades achieved - Teachers self-evaluation	Experimental workReportEssaySeminar essayTestsOral examWritten examProjectWritten examProjectThe course will be graded according to outcomes of absolute grading is applied.Title• P. Biljanović: Elektronički sklopovi, Školska knjiga, Zagreb• U. Tietze, C. Schenk, Advanced electronics circuits• Evidence of students attendance - Annual analysis of grades achieved	Experimental work Report Exercises Essay Seminar essay Individual work Tests Oral exam (Other) Written exam Project (Other) Written exam Project (Other) The course will be graded according to outcomes of the project and absolute grading is applied. Number of copies in the library • P. Biljanović: Elektronički sklopovi, Školska knjiga, Zagreb 5 • U. Tietze, C. Schenk, Advanced electronics circuits 5 • Evidence of students attendance - Annual analysis of grades achieved - Teachers self-evaluation Image: State	Experimental work Report Exercises Essay Seminar essay Individual work Tests Oral exam (Other) Written exam Project (Other) The course will be graded according to outcomes of the project and oral exa absolute grading is applied. Number of copies in the library Availabi other r • P. Biljanović: Elektronički sklopovi, Školska knjiga, Zagreb 5 Image: Comparison of the project and oral exa solute grading is applied. • U. Tietze, C. Schenk, Advanced electronics circuits 5 Image: Comparison of the project and oral exa solute grading is applied. • Evidence of students attendance - Annual analysis of grades achieved - Teachers self-evaluation Feaster of students attendance		

NAME OF THE COURSE	ENERGY STORAGE SYS	STEMS						
Code	FENG04	Year of study	2.					
Course teacher	Ozren Bego, Ph.D., Associate Professor	Credits (ECTS)	5		-			
	Danijel Jolevski, Ph.D.,	Type of instruction	L	S	AE	LE	DE	
Associate teachers	Assistant Professor	(number of hours)	30	0	0	15	0	
Status of the course	Elected	Percentage of application of e-learning	0					
	COURSI	E DESCRIPTION						
Course objectives	- selection of energy sto economical aspects,	and concepts of different er brage system regard to tech tore system functions in or	hnical,	techno	ologica	al and	grid.	
Course enrolment requirements and entry competences required for the course	None						0	
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to: analyse needs for energy storage, select energy storage technology according to requirements from grid system, build mathematical model of: battery based energy storage, impact of energy store on grid define requirements on energy storage advanced functions 							
	Course content				L hours		\E burs	
	Energy storage – concept, Application of energy stora Especial overview on appli microgrids.	S,	2					
	Separation and overview of term and long- term system	5	short-		2			
	Techno-economical aspec implementation.	ts of energy storage			2			
	Thermal energy storage. Compressed air energy storage (CAES).							
Course content broken down in	Mechanical energy storage hydro power plants) and ki	netic energy (flywheel).		e	2			
detail by weekly class schedule	Reversible chemical reactiand methane.	on for energy storage: hyd	lrogen		2			
(syllabus)	Energy storage in electrom application of supercapatite				2			
	Electrochemical energy sto characteristics	prage: batteries. Technolog	gy and		2			
	Supervision of battery state hardware for battery monit		stimato	ors,	2			
	Battery based energy stora Concept of whole system (grid, grid state supervision	battery, monitoring, conne			2			
	Active devices for connectifront end (AFE).	ing battery storage to grid:			2			
	Applications in grid stabiliz reserve, UPS, voltage regu		ng		2			

	List of laboratory exe	ercises						LE hours	
	Supercapacitors – m	Ŭ						3	
	Supercapacitors – m		g system					3	
	Batteries – modelling							3	
	Batteries – monitorin							3	
	Presentation of indep	pendent	assignm	ents				3	
	☑ lectures☑ seminars and work	rkshops			epender timedia	nt assignments			
Format of instruction									
Format of instruction	□ on line in entirety				,	oontor			
	□ partial e-learning								
	☐ field work				(Oth				
Student responsibilities	The presence on lect Performed all require	ne presence on lectures in the amount of at least 70 % of the times scheduled. erformed all required laboratory exercises.							
Screening student	Class attendance 1 Research Practical training				ng				
work (name the proportion of ECTS	Experimental work		Report			Individual work	K	1	
credits for each activity so that the	Essay		Seminal essay	r	2	Laboratory exe	ercises	0,5	
total number of	Tests	0	Oral exa		0,5	Preparation fo	r		
ECTS credits is equal to the ECTS	1 6515	0	Utal exa	4111	0,5	laboratory exe	rcises		
value of the course)	Written exam	0	Project			(Other)			
Grading and evaluating student work in class and at the final exam	During semester stu in last week of seme Final grade (in perce the activities in perce IA – indeper OE – oral ex	ester. Aff entage) entage: ndent as	er that on is formed Grade(%	ral exar l accorc) = 0,4	n will be ling to th	e done. ne formula:		presented	
Required literature (available in the library and via other		Title				Number of copies in the library		ability via er media	
media)	O. Bego: Predavanja	a iz prec	lmeta Su	stavi za	l I			earning	
	pohranu energije						p	oortal	
Optional literature (at the time of submission of study programme proposal)	Robert A. Huggins: I								
Quality assurance	 Evaluation of res 				the abo	ve learning out	comes		
methods that ensure	 Feedback from s 			eys					
the acquisition of	 Self-evaluation of 	of teach	ers						
exit competences	- Institutional and	non-ins	titutional	evaluat	ions				
Other (as the proposer wishes to add)									

NAME OF THE COURSE	ENGINEERING ECONON	IY							
Code	FENG01	Year of study	3.						
Course teacher	Ranko Goić, Ph.D., Full Professor	Credits (ECTS)	5						
Associate teachers	Josip Vasilj, Ph.D., Damir Jakus, Ph.D., Assistant Professor Stipe Vodopija, Teaching Assistant	Type of instruction (number of hours)	AE 0	LE 30	DE 0				
Status of the course	Elective	Percentage of application of e-learning							
	COURSE	E DESCRIPTION							
Course objectives	 understanding of time cost estimation and bill analysis of feasibility c evaluation of projects f 	l of quantity preparation alculations for investment easibility	decisio	ons	ring ec	onom	y and		
Course enrolment requirements and entry competences required for the course	None	preparation of spreadsheet models for decision making lone							
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 describe and apply me prepare terms of reference and overall decision me design and make spread overall decision making 	adsheet models for analys g models adsheet models for analys	stment eters fo is of fe	decisi or feasi asibilit	bility c y calcı	ulation	and		
Course content broken down in detail by weekly class schedule (syllabus)	Course content Introduction in engineering Theory of costs Time value of money (1 st p Time value of money (2 nd p Methods for calculation of Methods for calculation of Analysis of alternatives Analysis of equipment repla Decision models Income taxes and deprecia Bill of quantity, contracting Feasibility studies Sensitivity analysis, risk an Case study (1) Case study (2) List of laboratory exercises Basic spreadsheet models Basic of programming in M Example of cost analysis (Compound interest calcula Model for loan repayment	art - theory) part - examples) profitability of investments profitability of investments acement ation alysis (MS Excel) 1S Excel 1) 2) ation (1)					Durs 2		

	Model for profitability							2
	Model for profitabilit		. ,					2
	Model for analysis o							2
	Model for analysis o			acemen	t			2
	Model for sensitivity		S					2
	Model for risk analys		bility with	donroo	iction			2
	Model for analysis o Making of BoQ	or prolita	Dility with	i deprec	lation			2
								2
	□ seminars and wo	vorkshops				t assignments		
	\boxtimes exercises	i Konopo		🛛 mult	timedia			
Format of instruction				🛛 labo	ratory			
	\boxtimes partial e-learning	□ on line in entirety □ work with me						
	\square field work				(othe	er)		
Otivitant			41		1			la d
Student responsibilities	The presence on lect Performed all require				least /	0 % of the time	es schedu	lied.
Screening student work (name the	Class attendance	1	Researc	ch		Practical training	ng	
proportion of ECTS	Experimental work		Report			Individual work	(2,2
credits for each activity so that the	Essay		Semina essay	r		Laboratory exe		1
total number of ECTS credits is	Tests	0,2	Oral exa	am		Preparation for laboratory exercises		0,5
equal to the ECTS value of the course)	Written exam	0,1	Project			(Other)	101565	
						· · ·		
	 During semester, students are solving colloquiums through homeworks based on additional tasks over the basic spreadsheet models form laboratory exercises. Final exam is possible in three ways: Making of seminar – advanced spreadsheet model Making on spreadsheet model on computer, based on existing model from laboratory exercises (max. grade 4) Making on spreadsheet model on computer, new model (max. grade 5) In 2nd and 3rd option, first possibility to take the exam is during last week of lecturing. After that, there are two final exams. Students who did not pass the entire exam after two final exams can pass the exam in the two additional exams. The requirement for passing grade of the course is at least 50 % in all options of final exam. Grade is formed according to following: 50 % to 61 % - pass (2) 62 % to 74 % - good (3) 75 % to 87 % - very good (4) 							
Grading and evaluating student work in class and at the final exam	exam is possible in t 1. Making of se 2. Making on s laboratory e: 3. Making on s In 2 nd and 3 rd optic lecturing. After that, exam after two final The requirement for final exam. Grade is formed acc • 50 % to 61 % - • 62 % to 74 % -	hree wa eminar - preadsl xercises preadsl on, first there ar exams o passing ording t - pass (2 - good (- very go	ays: - advance neet mod s (max. g neet mod possibil re two fin can pass g grade g grade o followir 2) 3) pod (4)	dsheet r ed sprea lel on co rade 4) el on co ity to ta al exami the exa of the co	adsheet omputer mputer, ake the s. Stude m in the	model , based on exis new model (m exam is durir ents who did no e two additional s at least 50 %	v exercise sting mod ax. grade ng last v ot pass th exams.	es. Final del from e 5) veek of e entire
evaluating student work in class and at the final exam	exam is possible in t 1. Making of se 2. Making on s laboratory e 3. Making on s In 2 nd and 3 rd optic lecturing. After that, exam after two final The requirement for final exam. Grade is formed acc • 50 % to 61 % - • 62 % to 74 % - • 75 % to 87 % - • 88 % to 100 %	hree wa eminar - spreadsl xercises preadsh on, first there ar exams o passing cording t - pass (2 - good (3 - very go - excel Title	ays: - advance - advance - advance (max. g - advance - advan	dsheet r ed sprea lel on co rade 4) el on co ity to ta al exam the exa of the co ng:	adsheet omputer mputer, ake the s. Stude m in the	model , based on exis new model (m exam is durir ents who did no two additional	v exercise sting mod ax. grade ng last v ot pass th exams.	es. Final del from e 5) veek of e entire tions of
evaluating student work in class and at	exam is possible in t 1. Making of se 2. Making on s laboratory e: 3. Making on s In 2 nd and 3 rd optic lecturing. After that, exam after two final The requirement for final exam. Grade is formed acc • 50 % to 61 % - • 62 % to 74 % - • 75 % to 87 % -	hree wa preadsl xercises preadsl on, first there ar exams of passing ording t pass (2 good (i very go - excel Title vanja iz učilište	ays: - advance - advance - advance - advance (max. g - beet mod possibil - two fine can pass g grade - o followir 2) 3) - bod (4) lent (5) 	dsheet r ed sprea lel on co rade 4) el on co ity to ta al exam the exa of the co ng:	adsheet omputer, ake the s. Stude m in the ourse is	model , based on exis new model (m exam is durir ents who did no two additional two additional at least 50 %	v exercise sting moo ax. grade ng last v ot pass th exams. in all op	es. Final del from e 5) veek of e entire tions of ility via media

Optional literature (at the time of submission of study programme proposal)	 W. L. Winston, S. C. Albright: Practical Management Science, Duxbury Press, 2001. F. Khan, R. Parra: Financing Large Projects: Using Project Finance Techniques and Practices, Pearson Education Asia Pte., 2003. Lj. Vidučić: Financijski menadžment, RRIF-plus d.o.o., 2002. http://www.ise.ufl.edu/ein6357/downloads.html
Quality assurance methods that ensure the acquisition of exit competences Other (as the proposer wishes to add)	 Evaluation of results in accordance with the above learning outcomes Feedback from students via surveys Self-evaluation of teachers Institutional and non-institutional evaluations

NAME OF THE COURSE	ENGLISH LANGUAGE F	OR ACADEMIC PURPOS	ES						
Code	FEOG01	Year of study	2.						
Course teacher	Daniela Matić, Ph.D., Assistant Professor	Credits (ECTS)	3				-		
Associate teachers	/	Type of instruction (number of hours)	L	S 45	AE	LE	DE		
Status of the course	Elective	Percentage of application of e-learning	0%		<u>.</u>				
	COURSI	E DESCRIPTION							
Course objectives	 improving their writing environment or further helping students acqui structures; help students improve level (written and oral 	b basic scientific discourse and speaking skills neede education at foreign institu ire and enhance knowledg English for special purpos reception) depending on the areness of their own response	ed for w utions le on fo ses kno ne cour	reign l wledge se of s	acade angua e at re studies	mic ge ceptive s;			
Course enrolment requirements and entry competences required for the course	None	help students raise awareness of their own responsibility in learning process.							
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 discourse of science a recognize various text apply various reading authentic texts; identify and explain pro- recognize key ideas, w use various g and liste authentic general Engl present various topics 	 authentic texts; identify and explain professional vocabulary; recognize key ideas, words and sentences; 							
	Course content				L or S hours		AE ours		
	Unit 1 – <i>Education</i> - 1A – reading and understanding short informative texts; reading for the main idea and for detail; note-taking, writing a summary; 1B understanding essay titles; paraphrasing						-		
Course content	Unit 1 – 1C Listening for th phrases		3						
broken down in detail by weekly class schedule	Unit 1 – 1D Speaking –preparing for and taking part in a seminar discussion; summarizing and reporting on a seminar discussion, using a dictionary;								
(syllabus)	Alscussion, using a dictionary; Reading a scientific paper-analyzing the organization of the paper, explaining, paraphrasing Unit 2 – <i>Systems</i> – 2A - understanding and extracting key information; recognizing and writing definitions; summarizing key factual information								
	Reading a scientific paper Unit 2 – 2B- identifying the	language and features of	visual		3				

	1				
	information; writing a short description using noun phrases containing relation				
	Reading a scientific paper Unit 2 – 2C- recognizing key factual recognizing definitions in a lecture, r abbreviations and symbols; 2D - rec referring to visual information; recog explanations; presenting visual infor	information in a lecture, tote-taking with ognizing language for nizing noun phrases in	3		
	Unit 2 – building academic vocabula Unit 4 – Order – 4D-Presentations-e guidelines; using signposting langua information;	3			
	8. Mid-term exam				
	Unit 3 – Communication – 3A - ident supporting evidence in a text; buildir adverbs to express stance; 3B - ana sentences; adding supporting evider examples; writing and evaluating a p	3			
	Unit 3 – 3C - understanding the main recognizing the language for introdu supporting evidence, analyzing type examples, definitions and explanation Reading a scientific paper	n ideas in a lecture; cing main ideas and s of supporting evidence:	3		
	3				
	Reading a scientific paper Unit 4 – Order – identifying the purpusing classification to make notes; 3 introduction; writing and evaluating a essay introduction.	B – analyzing an essay	3		
	Reading a scientific paper Unit 4 – 4C – understanding the orga recognizing and practicing signpostion using diagrams. Academic vocabulary in use.		3		
	Presentations Unit 4 – Categorizing words; creating phrases. Academic vocabulary in use.	3			
	15. End-of-term exam □ lectures ⊠ seminars and workshops	⊠ independent assignme	3 nts		
Format of instruction	 seminars and workshops exercises on line in entirety partial e-learning field work 	 multimedia laboratory work with mentor (other) 			
Student responsibilities	 In order to take an exam and eventually obtain a grade, each student has to fulfill the following requirements: minimum class attendance of 70%; delivered and positively graded presentation in English before other students during regular classes. 				

Screening student	Class attendance	1	Research	0.5	Practical traini	ng			
work (name the proportion of ECTS	Experimental work	/	Report	0.5	(Other)	-			
credits for each activity so that the	Essay	/	Seminar essay		(Other)				
total number of ECTS credits is	Tests	1	Oral exam	/	(Other)				
equal to the ECTS value of the course)	Written exam		Project	/	(Other)				
Grading and evaluating student work in class and at the final exam	During the semeste exams, a mid-term a the latter in week architecture lexis fro for their profession. have to take the fina have finished. The final grade is ca - written exam (m exam) – 70% - positively graded - regular attendar - written assignme	he final grade is calculated as follows: written exam (mean of mid-term and end-of term exam positive results, or final exam) – 70% positively graded presentation – 20% regular attendance – 5% written assignments (homework) – 5% Il exams are scheduled according to the current academic year calendar. Number of Availability via							
	Title				Number of copies in the library	Availabi other r	-		
Required literature	de Chazal, Edward, Sam McCarter. (2012). Oxford EAP: A Course in English for Academic Purposes. Upper-intermediate/B2. Oxford: OUP.								
(available in the	McCarthy, Michael, Felicity O'Dell. (2008). Academic Vocabulary in Use. Cambridge: CUP.								
library and via other media)	Master, Peter. (2004 Technical Writing. W Language Programs Department of State								
	Paterson, Ken, Robe Grammar for EAP. C Oxford Learner's Did	erta We Dxford L	Iniversity Press.						
Ontional literature	Oxford University Pr			<u> </u>					
Optional literature (at the time of submission of study programme proposal)	 Powell, Mark. (20 Silobrčić, Vlatko. Zagreb: Medicins 	(20035)	. Kako sastaviti,				elo.		
	 Regular class attendance records Tutorials Evaluation of results in accordance with the above learning outcomes Feedback from students via surveys Self-evaluation of teachers Institutional and non-institutional evaluations 								
Quality assurance methods that ensure the acquisition of exit competences Other (as the proposer	 Evaluation of res Feedback from s Self-evaluation of 	tudents f teache	via surveys ers		ve learning outo	comes			

NAME OF THE COU	IRSE	HYDRAULIC	AND PNEUMATIC SYSTE	MS				
Code	FETG	02	Year of study	1				
Course teacher		arle, Ph.D., ofessor	Credits (ECTS)	5				
Associate teachers	Alen K	lovač	Type of instruction (number of hours)	L 30	S 0	AE 0	LE 30	CE 0
Status of the course	Electiv	/e	Percentage of application of e-learning	0				1
		(COURSE DESCRIPTION	-				
Course objectives			identify hydraulic or pneum that skills for fault finding an	-		ments by	y symbo	ol and
Course enrolment requirements and entry competences required for the course	None							
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	1. Pr pr 2. Id 3. C 4. C 5. D	 pneumatics. Identify components of the system and draw related symbols. Combine various elements with respect to size and design concept. Critically assess workability and supportability of complex hydraulic and pneumatic systems. Determine faults and failure causes. 						
		e content					L	LE
	Introduction to pneumatics. Basic physical principles of						ours	hours
	pneumatics. Standards and Symbols. Compressed air generation and distribution.						2	
			ystems demonstrations.					2
	Basic and d	elements of pri irectional contr	neumatic systems (check, p rol valves).		control		2	
			oment of pneumatic systems					4
		elements of pa actuation type	neumatic systems (direction s).	al contr	ol valves	5,	2	
			neumatic systems (cylinders	s and m	otors).		2	
Course content broken down in			on pneumatic didactic table.					4
detail by weekly			Electropneumatic systems		<u> </u>		2	
class schedule (syllabus)		amental hydrau	aulics. Basic physical princip ulic problems: cleanness, te			S.	2	
			stems demonstrations.					2
	motor	s with constan	for energy conversion: cylin t and adjustable displaceme	ent.			2	
	Basic control elements in hydraulics: check valves, direct acting and pilot operated pressure-relief valves.						2	
			and their most important pa					4
	opera		nts in hydraulics: direct acti control valves, pressure reo				2	
		ulic cylinders - er movement a	 parallel and series circuit. and load. 	Synchro	onizing			4

	conversion (cy	Typical design solutions of hydraulic elements for energy conversion (cylinders, pumps and motors with constant and adjustable displacement).						
		lic circuits	s: accumulate	or holding, pump unloading presses.	,	4		
	Pressure control circuits. Flow and speed control circuits.							
		Piloted and electrically controlled hydraulic systems.						
		xamples: actuator speed adjustments with throttle valve vs. peed control with flow regulators.						
Format of instruction	⊠ exercises □ <i>on line</i> in en	seminars and workshops ⊠ individual assignments seminars and workshops ⊠ multimedia con line in entirety ⊠ laboratory partial e-learning □ work with mentor field work □ individual project (other)						
Student responsibilities	Minimum of 70 exercises.	linimum of 70 percent lecture attendance. Completing all the required laboratory xercises.						
Screening student work (name the	Class attendance	2,0	Research	Practical ti	aining			
proportion of ECTS credits for each	Experimental work		Report	Individual		2,5		
activity so that the total number of	Essay		Seminar essay	Preparatio exercises	n for	0,3		
ECTS credits is equal to the ECTS	Tests	0,2	Oral exam	(Other)	(Other)			
value of the course)	Written exam		Project	(Other)				
Grading and evaluating student work in class and at the final exam	There are two midterms and final exams. The first midterm exam is after 7-week session classes and the second one is after the next 6 weeks. The midterms are carried out as written tests, made up of three questions relating to the basic issues and schematics. The oral exam is focused on the student's interpretation skills. The requirement for passing grade is the positive assessment on each midterm exam (>49%) or the final exam. The final score is: $Score (\%) = 0.35' A_1 + 0.35' A_2 + 0.20' A_3 + 0.10' A_4$ • midterm 1: $A_1 = 50 - 100 \%$,							

	Title	Number of copies in the library	Availability via other media					
Required literature (available in the library and via other media)	 Barle, J.: Hydraulics and pneumatics, (student handbook and workbook in Croatian: <i>Hidraulika i pneumatika</i>), FESB, Split, 2010. Nikolić, G.: Pneumatika, Školske novine, Zagreb, 1994. 		e-learning portal					
Optional literature (at the time of submission of study programme proposal)	Koroman, V.; Mirković, R.: Hidraulika i pneumatika, Školska knjiga, Zagreb, 1991. Lang, R.A. (ed.): Hydraulic Trainer 1; Planning and Design of Hydraulic Power Systems, Mannesmann Rexroth AG, 1998. Rabie, M.: Fluid Power Engineering, McGraw-Hill, 2009.							
Quality assurance methods that ensure the acquisition of exit competences	 Evaluation of results in accordance with the ab Feedback from students via surveys Self-evaluation of teachers Institutional and non-institutional evaluations 	oove learning outco	mes					
Other (as the proposer wishes to add)								

NAME OF THE COURSE	INDUSTRIAL ROBOTICS	;							
Code	FELG05	Year of study	1						
Course teacher	Mojmil Cecić, Ph.D., Full Professor	Credits (ECTS)	5						
	Stanko Kružić, Teaching	Type of instruction	L	S	AE	LE	DE		
Associate teachers	Assistant	(number of hours)	30	0	0	30	0		
Status of the course	Elective	Percentage of application of e-learning			0				
	COURSI	E DESCRIPTION							
	Training students for:								
Course objectives	 dynamics of robots, setting up and solving lastructures, trajectory planning, simulations using MATI using different methods 		oroblem	n of sin	nple m				
Course enrolment requirements and entry competences required for the course	None	ne							
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 describe the different calculate kinematics of calculate dynamics of programming manipu understand the different 	calculate kinematics of typical manipulator structures,							
	Course content			L	nours	AE	nours		
	Introduction, History of Rol		bots		2				
	Robot Mechanical Structur	e, Degress of Freedom			2				
	Kinematics, Rotation Matri Homogeneous Transforma	tions			3				
	Direct Kinematics, Denavit	<u> </u>	on		3				
	Kinematics of Typical Man				3				
	Inverse Kinematics Proble				2				
Course content	Differential Kinematics and	Statics, Jacobian			2				
broken down in	Trajectory Planning				2				
detail by weekly class schedule	Manipulator Dynamics, Lag		se		3				
(syllabus)	Joint Actuating System, Dr	ivers			2				
	Sensors				2				
	List of laboratory or design exercises								
	Homogeneous Transforma	tions					2		
	Direct Kinematics	-					3		
	Inverse Kinematics Probler	I)					3 2		
	· · ·	nalytical Jacobian							
	Dynamics Kinematics and Dynamics (of Typical Manipulator Stru	icture				2 4		
	parternatios and Dynamics (or rypical manipulator Stru				'	т		

	Programing language	es						2
	Programming of mob	5 5						2
	Trajectory generatior			of Mob	ile Robo	ots		2
Format of instruction	The Visual Servoing Iectures seminars and wo exercises on line in entirety partial e-learning field work	Image: seminars and workshops Image: multimedia Image: seminars and workshops Image: seminars Image: seminars Image: seminars						4
Student responsibilities	The presence on lect Performed all require				t least 7	0 % of the time	es schedu	ıled.
Screening student work (name the	Class attendance	2	Researc	h		Practical traini	ng	0,2
proportion of ECTS credits for each	Experimental work		Report			(Other)		2,5
activity so that the total number of	Essay		Seminai essay			(Other)		
ECTS credits is equal to the ECTS	Tests	0,2	Oral exa	ım		(Other)		
value of the course)	Written exam	0,1	Project			(Other)		
Grading and evaluating student work in class and at the final exam	There are two midterms and final exams. The first midterm exam is after 7 weeks of lecturing and the second one is after the next 6 weeks. The requirement for passing grade is the positive assessment of laborator exercises and 50% points on each midterm exam or the final exam. Grade (if percentage) is formed according to the formula: Grade [%] =0,25*L+0.375* (M1 + M2) where L is laboratory assessment and M1 and M2 are the results of the midterm exams in percentage. Each midterm test consists of 10 theoretical questions and numerical problems an final test also consists of 10 theoretical questions and numerical problems divide into two groups (the first and the second part). The requirement for passing grad is 50% of the total number of questions. The students who did not pass the midterr exams take part in the final exam. The midterm and final exams are carried out a written tests. Finally grade is determined as follows: from 50% to 62.5% - dovoljan (2) from 62.5% to 75% - dobar (3) from 75% to 87.5% - vrlodobar (4) from 87.5% to 100% - izvrstan (5) Midterm and final exams are held in the terms provided by the time table.					rade (in term ms and divided g grade midterm		
Poquirod litoraturo		Title	9			Number of copies in the library	Availab other	
Required literature (available in the library and via other media)	 Saeed B. Niku: In Analysis, System 2001. 				e Hall,	1		
	Craig: Introduction Control, Prentice			chanics	s and	1		
Optional literature (at the time of submission of study programme proposal)	 Tadej Bajd: Osno 2000. Kovačić, Laci, Bo Zagreb, 1999. Siciliano, Sciavic 	ogdan: (Osnove ro	botike,	Fakulte	t elektrotehnike	-	
Quality assurance methods that ensure	 Evaluation of res Feedback from s 				he abov	ve learning outo	comes	

the acquisition of exit competences	 Self-evaluation of teachers Institutional and non-institutional evaluations
Other (as the	
proposer wishes to	
add)	

NAME OF THE COURSE	INTRODUCTION TO MAD	CHINE LE	ARNING							
Code	FELG30	Year of s	tudy	1						
Course teacher	Tamara Grujić, Ph.D, Full Professor	Credits (E	ECTS)	5						
	Ivo Stančić, Ph.D.,	Type of ir	nstruction	L	s	AE	LE	DE		
Associate teachers	Assistant Professor	(number		30			30			
Status of the course	Elective	Percenta application	ge of on of e-learning	0						
	COURSE	DESCRI	PTION							
Course objectives	 Training students for: Understanding and application of various Selection and application application Implementation of clate 	algorithms tion of ade	s of machine lea quate classifica	tion alg	or data jorithm	a class of for ea	sificatio	n		
Course enrolment requirements and entry competences required for the course Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	Students will be able to: - Define basic principles - Describe and illustrate algorithms - Apply different classific	udents will be able to: Define basic principles of machine learning Describe and illustrate benefits and limitations of basic machine learning algorithms Apply different classification algorithms								
	Estimate applicability of each machine learning algorithm for each assignm Course content						nent \E			
	Introduction to machine learning: basic terms, applications of					hours	hc	ours		
	machine learning and software tools for machine learning									
	Concept Learning and sea					2				
	Basic algorithm of machine	e learning:	Find-S			2				
	Algorithm of the candidate	elimination	ו			2				
	Decision tree algorithm					2				
Course content	Bayesian Methods, naive E	Bayes clas	sifier			2				
broken down in	Linear Discriminant Analys	is				2				
detail by weekly class schedule	Support Vector Machine					2				
(syllabus)	Artificial Neural Networks					6				
	Evaluation of classification	algorithms	s. Statistical trial	s		4				
	List of laboratory or design							_E ours		
	Algorithms: Find-S, candida	ate elimina	tion decision tr	ee				6		
	Bayesian Methods, naive B			00				6		
	Linear Discriminant Analysi							6		
	Support Vector Machine	-						6		
	Artificial Neural Networks							6		
Format of instruction	 lectures seminars and workshop exercises on line in entirety partial e-learning field work 	s ⊠ independent assignments ⊠ multimedia ⊠ laboratory □ work with mentor □ (other)								
Student responsibilities	The presence on lectures i Performed all required labor) % of	the tim	ies sc	hedule	d.		

Screening student	Class attendance	2	Research		Practical traini	ng	
work (name the proportion of ECTS	Experimental work		Report		Individual work	ĸ	1
credits for each activity so that the	Essay		Seminar essay		Laboratory exe	ercises	1
total number of ECTS credits is	Tests	0,25	Oral exam		Preparations for laboratory exe		0,5
equal to the ECTS value of the course)	Written exam	0,25	Project		(Other)		
Grading and evaluating student work in class and at the final exam	During the semester there are two midterm exams according to teaching calenda followed with the final and correction exam. In the final exam students are required t take part of course not passed by midterms. In correction exam students are required t take whole course. The requirement for passing grade is the positive assessment of laboratory exercises and 50 % points on average midterm exam ((M1 + M2)/2) or th final exam. Requirement for positive assessment of laboratory exercises is attendance to all laboratory exercises and positively graded reports. Each midterm is taking 10 min and consists of 8 questions and assignments. Final exam is taking 120 min an consist of 10 questions and assignments divided in two groups (5 questions an assignments from each midterm). Corrective exam, taking 120 min, consist of questions and assignments. Requirement for passing midterms and final exam i 50% of total questions and assignments. Final grade is formed as follows: Grade(%)= 0,45 (M1 + M2) + 0,1 LE M1, M2 – midterm grades (in %) LE – grade from laboratory exercises (in %) Percentage Grade 50% do 61,9% sufficient (2) 62% do 74,9% good (3) 75% do 89,9% very good (4) 90% do 100% excellent (5)						
Required literature		Title	•		Number of copies in the library	Availabi other r	-
(available in the library and via other media)	I. Kononenko, M. Ku mining: Introduction Horwood Press, 200	to princ			5	e-lear por	-
, ,	Tom M. Mitchell, Ma 1997.		earning, McGraw	∕ – Hill,	5	e-lear por	-
Optional literature (at the time of submission of study programme proposal)	 Ian H. Witten, Eibe Techniques, 2nd e Christopher M. Bis 	dition, Th	ne Morgan Kaufma	nn, 2005	j		
Quality assurance methods that ensure the acquisition of exit competences	 Keeping records of student attendance. Annual analysis of course statistics in terms of midterm and finals exams. Feedback from students via surveys. Teacher self-evaluation. Feedback from graduated students (or senior students) on course content relevance. 						
Other (as the proposer wishes to add)	/						

NAME OF THE COURSE	LINEAR CONTROL SYST	TEMS						
Code	FELG01	Year of study	1.					
Course teacher	Tamara Grujić, Ph.D., Full Professor	Credits (ECTS)	6					
		Type of instruction	L	S	AE	LE	DE	
Associate teachers	-	(number of hours)	45 0 15 15					
Status of the course	Obligatory	Percentage of application of e-learning	0					
	COURSE	E DESCRIPTION						
Course objectives		ol systems in the time and ontrol systems using differe state space						
Course enrolment requirements and entry competences required for the course	- Completed course "Sy	Define the basic concepts of analysis and synthesis of linear control systems						
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Analyze specific linear Calculate the parameter higher order systems b Design a linear control locus method Design a linear control phase lead and lag control 	Define the basic concepts of analysis and synthesis of linear control systems Analyze specific linear control system in time and frequency domain Calculate the parameters of first or second order system for supplementing the higher order systems by first or second order system Design a linear control system in the time domain, by implementing the root locus method Design a linear control system in the frequency domain, by implementing the phase lead and lag compensators Design a linear control system in state space						
	Course content				L hours		AE ours	
	Introductory concepts: analysis and synthesis of linear control systems (LC systems - abbreviated); LC systems analysis in time domain: time response, absolute and relative stability of LC systems						1	
	LC systems analysis in frequency domain (specifications in the frequency domain): frequency response of systems, polar, Nyquist and Bode's diagrams						1	
Course content broken down in	Frequency analysis of LC systems with negative feedback: stability criterion in the frequency domain (Nyquist stability criterion), measures of relative stability: amplitude and phase margins						1	
detail by weekly class schedule (syllabus)	Frequency response of 1 a frequency bandwidth, M - of higher orders by system circles	circles. Supplementing the	e syste	ms	3		1	
	Root locus technique: bas for construction of the R construction				3		1	
	Synthesis (design) of Lo	C systems based on r	oot loo	cus	3		1	
	Introduction to the synthe frequency domain: phase-I First midterm exam				3		1	
	Design of LC systems in phase-lag compensators a		by us	ing	3		1	

	Design of LC syste					3	1	
	phase-lead compens						-	
	Modeling of the cont					3	1	
	Design of LC system the cases of the el and increasing the e	iminatio	n of plar	nt trans	fer function zeros	3	1	
	Design of LC syste adding zeros to the p	ms in s	tate space	ce: cas		3	1	
	Design of LC syste state variables				partially available	3	1	
	Second midterm exam							
		ist of laboratory exercises						
	Supplementing the siby using the M circle	ystems				d 2 order,	LE hours 3	
	Synthesis (design) of					;	3	
		thesis (design) of LC systems in the frequency domain by phase-lag						
	Design of LC systems in state space, Part 1: Creating the desired transfer function of LC system using state variables for two different cases (eliminating zeros and increase the excess of poles over zeros in plant transfer function), Matlab and Simulink							
	Design of LC syste transfer function of L cases (moving and	and transfer function), Mattab and Simulink resign of LC systems in state space, Part 2: Creating the desired ansfer function of LC system using state variables for other two different ases (moving and adding zeros to the plant transfer function in plant ansfer function), Matlab and Simulink						
Format of instruction	 ✓ lectures ✓ seminars and workshops ✓ exercises ✓ on line in entirety ✓ partial e-learning ✓ field work ✓ independent assignments ✓ multimedia ✓ aboratory ✓ work with mentor ✓ (other) 							
Student responsibilities	The presence on lec Performed and posi						eduled.	
Screening student work (name the	Class attendance	2,5	Researc	h	Practical tra	aining		
proportion of ECTS	Experimental work		Report		Individual v	work	1	
credits for each activity so that the	Essay		Seminar essay	,	Laboratory	exercises	1,5	
total number of ECTS credits is	Tests	0,25	Oral exa	ım	Preparation laboratory		0,5	
equal to the ECTS value of the course)	Written exam	0,25	Project		(Oth	ner)		
Grading and evaluating student work in class and at the final exam	There are two midte lecturing and the sec of 8 theoretical que theoretical questions not pass the midtern as written tests. The laboratory exercises Grade (in percentage the activities in perce • LV – laborat • M1, M2 – test	cond on estions a s and nu n exams e require and 50 e) is forn Grac entage: ory asse	e is after and num umerical take par ement for 0% poin med accc le(%) = 0 essment,	the nex erical p problem t. The r passir ts on e ording to	of 6 weeks. Each n problems and final ns. In the final exar nidterm and final ex ng grade is the pos each midterm exan	nidterm tes tests con ms studen xams are o sitive asse	st consists sist of 10 ts that did carried out ssment of	
	The final grade is de	termined	as follows:					
---	--	--	--	---------------------------------------	------------------------------			
	Percentage:	Grade:						
	50% do 61,9%	2						
	62% do 74,9%	3						
	75% do 89,9%	4						
	90% do 100%	5		r				
Doguirod literatura		Title		Number of copies in the library	Availability via other media			
Required literature (available in the library and via other media)	 Tamara Grujić: " Predavanja sa za FESB, Split, 201 	adacima",	egulacijski sustavi – Interna skripta,		e-learning portal			
mediay	•	•	laboratorijske vježbe ijski sustavi", interna		e-learning portal			
Optional literature (at the time of submission of study programme proposal)	McGraw – Hill In M. Fogiel (Editor Research & Educ	ternationa): ''The au cation Ass Bishop: ''	Modern control system	995. s / Robotics; F	roblem solvers",			
Quality assurance methods that ensure the acquisition of exit competences	 Feedback from s Self-evaluation o Institutional and Keeping records 	students v of teacher non-instit of lecture of the pro	s utional evaluations es attendance esence of the laborator					
Other (as the proposer wishes to add)								

COURSE	MEASUREMENTS AND	SIGNAL PROCESSING					
Code	FENI03	Year of study	1.				
Course teacher	Goran Petrović, Ph.D., Associate Professor	Credits (ECTS)	6				_
Associate teachers	Juraj Alojzije Bosnić, m.e.	Type of instruction	L	S	AE	LE	DE
		(number of hours)	30	0	0	30	0
Status of the course	Elective	Percentage of application of e-learning	30				
	COURSI	E DESCRIPTION					
Course objectives		vices for measurements ar al processing and estimati gital spectral analysis.		g-digi	ital co	onversi	ion,
Course enrolment requirements and entry competences required for the course	None						
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 estimate errors of direct determine parameters determine spectral cort determine spectral cort 	acquisition of various signa ct and indirect measuring q of mathematical model, nponents of continuous an nponents of continuous an ces of harmonics and other	d discre d discre d discre s disturk	te per te ape	eriodio	c funct	
		educing of narmonic distor	tions.				
	Course content	educing of narmonic diston	tions.	h	L		AE ours
	Signals. Division and featu	res of signals. Continuous	, discrete	Э	L nours 2	hc	
		res of signals. Continuous g. Types of measuring instr gers. Data acquisition dev	, discrete	Ð		hc	ours
	Signals. Division and feature and digital signal recording Analog recorders. Data log interfaces. Digital oscillosc Systematic errors and rand	res of signals. Continuous J. Types of measuring instr Iggers. Data acquisition dev opes. Sample rate. dom errors. Quantization en	, discrete uments. ices anc	Ð	2	hc	ours 0
	Signals. Division and feature and digital signal recording Analog recorders. Data log interfaces. Digital oscillosc Systematic errors and rand Signal noise ratio.Error but Measurement error and pro-	res of signals. Continuous g. Types of measuring instr ggers. Data acquisition dev opes. Sample rate. dom errors. Quantization en dget of a linear sensor. obability theory. Some imp	, discrete uments. ices anc rror. ortant	Ð	2 2		ours 0 0
Course content	Signals. Division and feature and digital signal recording Analog recorders. Data log interfaces. Digital oscillosc Systematic errors and rand Signal noise ratio.Error bud Measurement error and pro- density functions. Central I Two-dimensional random	res of signals. Continuous g. Types of measuring instr ggers. Data acquisition dev opes. Sample rate. dom errors. Quantization er dget of a linear sensor. obability theory. Some imp imiting theorem. Chi squar variable. Linear regression.	, discrete uments. ices anc rror. ortant e test.	2	2 2 2		0 0 0 0
broken down in	Signals. Division and feature and digital signal recording Analog recorders. Data log interfaces. Digital oscillosc Systematic errors and rand Signal noise ratio.Error but Measurement error and pro- density functions. Central I Two-dimensional random v the expression of uncertain The method of least square	res of signals. Continuous, g. Types of measuring instr ggers. Data acquisition dev opes. Sample rate. dom errors. Quantization er dget of a linear sensor. obability theory. Some imp imiting theorem. Chi squar variable. Linear regression. hty in measurement. es. Linear and nonlinear	, discrete uments. ices anc rror. ortant e test.	2	2 2 2 2		0 0 0 0 0
	Signals. Division and feature and digital signal recording Analog recorders. Data log interfaces. Digital oscillosc Systematic errors and rand Signal noise ratio.Error but Measurement error and pro- density functions. Central I Two-dimensional random of the expression of uncertain The method of least square relationship. Lagrange wei Orthogonal functions analy Orthogonal polynomial analy	res of signals. Continuous, g. Types of measuring instr ggers. Data acquisition dev opes. Sample rate. dom errors. Quantization en dget of a linear sensor. obability theory. Some imp imiting theorem. Chi squar variable. Linear regression. ty in measurement. es. Linear and nonlinear ghting matrix. vsis of continuous signals.	, discrete uments. ices and rror. ortant e test. . Guide t	2	2 2 2 2 2 2		ours 0 0 0 0 0 0 0 0
broken down in detail by weekly class schedule	Signals. Division and feature and digital signal recording Analog recorders. Data log interfaces. Digital oscillosc Systematic errors and rand Signal noise ratio.Error but Measurement error and pro- density functions. Central I Two-dimensional random v the expression of uncertain The method of least squar- relationship. Lagrange wei Orthogonal functions analy	res of signals. Continuous, g. Types of measuring instr ggers. Data acquisition dev opes. Sample rate. dom errors. Quantization en dget of a linear sensor. obability theory. Some imp imiting theorem. Chi squar variable. Linear regression. ty in measurement. es. Linear and nonlinear ghting matrix. vsis of continuous signals.	, discrete uments. ices and rror. ortant e test. . Guide t	2	2 2 2 2 2 2 2		ours 0 0 0 0 0 0 0 0 0
broken down in detail by weekly class schedule	Signals. Division and feature and digital signal recording Analog recorders. Data log interfaces. Digital oscillosc Systematic errors and rand Signal noise ratio.Error but Measurement error and pro- density functions. Central I Two-dimensional random of the expression of uncertain The method of least square relationship. Lagrange wei Orthogonal functions analy Orthogonal polynomial and series.	res of signals. Continuous, <u>g. Types of measuring instr</u> ggers. Data acquisition dev opes. Sample rate. dom errors. Quantization en dget of a linear sensor. obability theory. Some imp imiting theorem. Chi squar variable. Linear regression. nty in measurement. es. Linear and nonlinear ghting matrix. visis of continuous signals. For alysis of discrete signals. For Properties of Dirac and sir	, discrete uments. ices and rror. ortant e test. . Guide t	2	2 2 2 2 2 2 2		ours 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
broken down in detail by weekly class schedule	Signals. Division and feature and digital signal recording Analog recorders. Data log interfaces. Digital oscillosc Systematic errors and rand Signal noise ratio.Error bud Measurement error and pro- density functions. Central I Two-dimensional random v the expression of uncertain The method of least square relationship. Lagrange wei Orthogonal functions analy Orthogonal polynomial ana series. First midterm exam Elementary digital signals. function. Exponential Fouri Fourier transform of aperiod	res of signals. Continuous, g. Types of measuring instr ggers. Data acquisition dev opes. Sample rate. dom errors. Quantization en dget of a linear sensor. obability theory. Some imp imiting theorem. Chi squar variable. Linear regression. ty in measurement. es. Linear and nonlinear ghting matrix. vsis of continuous signals. alysis of discrete signals. For Properties of Dirac and sir ier series.	, discrete uments. ices and rror. ortant e test. . Guide t	2	2 2 2 2 2 2 2 2 2	hc	ours 0 0 0 0 0 0 0 0 0 0 0
broken down in detail by weekly class schedule	Signals. Division and feature and digital signal recording Analog recorders. Data log interfaces. Digital oscillosc Systematic errors and rand Signal noise ratio.Error bud Measurement error and pro- density functions. Central I Two-dimensional random v the expression of uncertain The method of least square relationship. Lagrange wei Orthogonal functions analy Orthogonal polynomial and series. First midterm exam Elementary digital signals. function. Exponential Fouri Fourier transform of aperiod transform of periodic contin Fourier transform of discre	res of signals. Continuous, g. Types of measuring instr ggers. Data acquisition dev opes. Sample rate. dom errors. Quantization en dget of a linear sensor. obability theory. Some imp imiting theorem. Chi squar variable. Linear regression. ty in measurement. es. Linear and nonlinear ghting matrix. vsis of continuous signals. alysis of discrete signals. For Properties of Dirac and sir ier series. odic continuous function. For nuous function. te aperiodic and periodic fu	, discrete uments. ices and rror. ortant e test. . Guide 1 ourier	2	2 2 2 2 2 2 2 2 2 2 2 2	hc	ours 0 0 0 0 0 0 0 0 0 0 0 0 0
broken down in detail by weekly class schedule	Signals. Division and feature and digital signal recording Analog recorders. Data log interfaces. Digital oscillosc Systematic errors and rand Signal noise ratio.Error bud Measurement error and pro- density functions. Central I Two-dimensional random v the expression of uncertain The method of least square relationship. Lagrange wei Orthogonal functions analy Orthogonal polynomial ana series. First midterm exam Elementary digital signals. function. Exponential Fouri Fourier transform of aperiodic contin	res of signals. Continuous, <u>y</u> Types of measuring instr gers. Data acquisition dev opes. Sample rate. dom errors. Quantization end dget of a linear sensor. obability theory. Some imp imiting theorem. Chi squar variable. Linear regression. ty in measurement. es. Linear and nonlinear ghting matrix. vsis of continuous signals. alysis of discrete signals. For Properties of Dirac and sir ier series. odic continuous function. For nuous function. te aperiodic and periodic function. form DTFT. Discrete Fouri	, discrete uments. ices and rror. ortant e test. . Guide t ourier nc ourier unction.	2	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	hc	Durs 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0

	Transfer function an	d Filterii	ng. Harm	onic dis	stortion in	n power	2		0
	system and industria Second midterm exa		es.				_		0
	List of laboratory exe							IF	E hours
	Principles of Matlab								3
	Statistics processing								3
	Least square method		r and non	linear n	roblems				3
	Trigonometric and Ex								3
	Voltage and Current					nverter.			3
	Root mean square R						or.		3
	Using of window fund				P = =				3
	Transfer function and		a.						3
	Practical skills exam		5						2
	⊠ lectures					_			
	□ seminars and wor	rkshons				t assignme	nts		
	\boxtimes exercises	inopo		🛛 mul	timedia				
Format of instruction				🛛 labo	oratory				
	□ on line in entirety			□ wor	k with m	entor			
	□ partial e-learning				(othe	er)			
	☐ field work				(our	,,,			
Student responsibilities	The presence on lect Performed all require				t least 7	0 % of the t	imes sc	hedu	led.
		1				Dractical tr	aining		
Screening student work (name the	Class attendance	I	Researc	FT		Practical tra	aming		
proportion of ECTS	Experimental work		Report			Individual w	vork		3
credits for each	Essay		Semina			Laboratory	exercise	25	0,5
activity so that the total number of	20003		essay			-			0,0
ECTS credits is	Tests	0,5	Oral exa	m		Preparation			0,5
equal to the ECTS	1 0010	0,5		un		laboratory	exercise	S	0,0
value of the course)	Written exam	0,5	Project			(Oth	ner)		
Grading and evaluating student work in class and at the final exam	There are two midte first midterm exam is 6 weeks. Each mid problems and fina problems. In the fin part. The requirement for exercises and 40 % percentage) is forme the activities in perce • LV – laborat • M1, M2 – tes	s after 7 dterm te l tests al exam or pass 6 points ed accor Gra entage: ory ass	weeks o est consist consist ing grad on each rding to th de(%) = 0 essment,	f lecturi sts of t of 10 its that e is th midte ne form	ng and t 5 theoret theoret did not ne posit rm exar ula:	the second etical quest ical quest pass the r ive assess n or the fir	one is a ions and ons and nidterm ment o nal exam	fter t d nu d nu exar f lab	he next merical merical ns take ooratory
Required literature (available in the		Title	9			copies i the libra	n Ava		ility via nedia
library and via other media)	 S. Milun, G. Petri FESB 	ović: Sk	ripta s pr	edavan	ja,		-	e-lear por	ning tal
Optional literature (at the time of submission of study programme proposal)	 HP; The fundame J. G. Proakis, D. Jersey, 1996. 	G. Man	olakis: D	gital Si	gnal Pro	cessing, Pr		all,N	
Quality assurance methods that ensure the acquisition of	 Evaluation of res Feedback from s Self-evaluation of Institutional and 	students of teach	s via surv ers	eys		ve learning	outcome	es	

exit competences	
Other (as the	
proposer wishes to	
add)	

NAME OF THE COURSE	MICROCONTROLLERS	AND NETWORK EMBEDI	DED S'	YSTEN	IS		
Code	FELG24	Year of study	2.				
Course teacher	Mirjana Bonković, Ph.D., Full Professor	Credits (ECTS)	5				
Associate teachers	Ivo Stančić, Ph.D., Assistant Professor	Type of instruction (number of hours)	L 30	S 0	AE 0	LE 30	DE 0
Status of the course	Obligatory	Percentage of application of e-learning	0	-			
	COURSI	E DESCRIPTION					
Course objectives	embedded systemsto develop an understato be familiar with conc	nding for the purpose and nding of basic microcontro ept of microcontroller inter bedded system that comm	oller ard faces	chitectu	ure		
Course enrolment requirements and entry competences required for the course	Finished programming course						
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 the embedded system define and understand program the related m appropriate functionali design the embedded functionality based on apply a procedure that processing unit 	the basic concepts related the interfacing techniques icrocontrollers' peripheral s ty of the embedded system system in the Arduino envi the information processing provides network data tra ch ensures the functionalit	s system ironme g acqui nsmiss	s to e nt that red fro sion fro	stablis reflec m the m ser	t the senso sor to	rs. the
	Course content						L ours
	The purpose of a microcor	troller. Embedded system	desigr	n princi	ples.		2
	Embedded system design	in Arduino environment.	5	•	-		2
	Knowledge and understand design paradigms, archited with respect to software an	ding of fundamental embe ctures, possibilities and cha					2
Course content	Microprocessor peripheral	devices. General purpose	input o	output.			2
broken down in	Serial communication: SPI	, USART, IIC.	-	-			4
detail by weekly	Real time clock. Timers.						2
class schedule	A / D and D / A converters	. Realization of A / D conve	erters.				2
(syllabus)	Interrupts. Programming in	terrupts.					2
	Architecture and functional communication.	microprocessors' compor	nents fo	or netw	ork		2
	Using IP for local and Inter using UDP and TCP, e-ma		nanging	g mess	ages		2
	Using the Web interface.	, -					2
	Optimization of the embed consumption	ded system regarding the	energy	,			2

	List of laboratory or	design e	exercises				LE hours
	Introduction to the Ar				ronmen	t: hardware	2
	components and prog						
	Digital input - output.		vionitor.				2
	Analog input. PWM c	•					2
	Speed control of DC	motors.					2
	Using GPS module.						2
	Using NRF modules. Sensors: OneWire te	moorot		r opole			2
	sensor.				0		2
	Ethernet shild. Excha	5 5	•	0			2
	Web server (with and			,			2
	Optimization of the e	mbedde	ed system	n regard	ing the	energy consumption	2
	Student projects.			1			6
				🗆 inde	epender	nt assignments	
	□ seminars and wor	rkshops			timedia	•	
Format of instruction				🖂 labo	oratory		
	□ <i>on line</i> in entirety □ partial e-learning			\boxtimes wor	k with n	nentor	
	\Box field work				(othe	er)	
Student							
responsibilities			•				
Screening student work (name the	Class attendance	2	Researc	ch		Practical training	
proportion of ECTS	Experimental work		Report			Individual work	0,6
credits for each activity so that the	Essay		Semina essay	ſ	1	Laboratory exercises	0,8
total number of ECTS credits is	Tests	0,2	Oral exa	am		Preparation for laboratory exercises	0,2
equal to the ECTS value of the course)	Written exam	0,2	Project			(Other)	
			-			The first midterm exa	in char
Grading and evaluating student work in class and at the final exam	 7 weeks of lectures presentation and det the final test) is car requirement for pas and 50 % points of Students are allower as long as the final regrade (in percentage) Grade(%) = 0,1L + 0 where: L – laborator M1, M2 – mi According to Article teaching activities a exercises. If students 	and the fense of rried ou sing gra n avera d to hav nidterm e) is for 0,4M1 + cy asses dterm to 65. of 1 attendin does r	e second f the projet in a wr ade is the age midt ve at leas average med acco 0,5M2 ssment, est result Faculty's g at leas not meet	one is a ect assi itten for e positiverm ex- st 45% of is at lea ording to s. Bylaw, st 70% these c	after 13 gnment rmat wi ve asse am ((M of total ast 50% o the for of the for of lect riteria, s	weeks of lectures (in). Each midterm test (th duration of 90 min ssment of laboratory 1 + M2)/2) or the fin points on each midter of total points.	a form of as well as utes. The exercises nal exam. m exams, pate in all laboratory ole to take

	Title	Number of copies in the library	Availability via other media
Required literature (available in the library and via other media)	Steven F. Barrett, Arduino Microcontroller Processing for Everyone!, Synthesis Lectures on Digital Circuits and Systems, Morgan & Claypool Publishers, 2010. David Russeell, Introduction to Embedded Systems Using ANSI C and the Arduino Development Environment, Synthesis Lectures on Digital Circuits and Systems, Morgan & Claypool Publishers, 2010. Michael Predko , Handbook of Microcontrollers, Tab Books, 1998. M. Bonković, J. Musić, I. Stančić, Mikroregulatori i		e-learning
	ugradbeni mrežni sustavi, FESB, 2014. 1. Claus Kuhnel, Klaus Zahnert, BASIC Stamp : An	Introduction to)
Optional literature (at the time of submission of study programme proposal)	 Microcontrollers, Newnes, 2000. Han-Way Huang, PIC Microcontroller, Thomson Jan Axelson: Embedded Ethernet and Internet co LLC, 2003., ISBN: 1-931448-00-0 Microcontroller links http://people.westminstercollege.edu/faculty/reric 	omplete, Lake	view Research
Quality assurance methods that ensure the acquisition of exit competences	 Keeping records of student attendance. Annual analysis of course statistics in terms of Feedback from students via surveys. Teacher self-evaluation. Feedback from graduated students (or senio relevance. Periodic institutional evolution of course teac 	of midterm and r students) on	d finals exams.
Other (as the proposer wishes to add)			

COURSE	MOBILE ROBOTICS						
Code	FELG25	Year of study	2.				
Course teacher	Mirjana Bonković, Ph.D., Full Professor	Credits (ECTS)	5				
	Miroslav Dujmović, BSc	Type of instruction	L	S	AE	LE	DE
Associate teachers	(external collaborator)	(number of hours)	30	0	0	30	0
Status of the course	Elective	Percentage of application of e-learning	0				
	COURS	E DESCRIPTION					
Course objectives	components (actuators - understanding and app	orking principles and limita s, sensors and control units olying number of different to such as control and naviga desired task.	s). echniqu	ues for	solvir	ng prob	
Course enrolment							
requirements and entry competences required for the course	None						
Learning outcomes expected at the level	 explain different modes develop PID controller design algorithms for d 	widely used sensors in mo s of mobile robot control. for mobile robot control. lata fusion based on Kalma					
of the course (4 to 10 learning outcomes)	 navigation. demonstrate applicatio servoing). apply acquired knowled C#, Python, Java). 	path planning, obstacle av n of computer vision in mo dge in higher level program path planning and navigatio	voidanc obile rot nming l	e and bot cor angua	ntrol (v ges (e	risual	sual
10 learning	 navigation. demonstrate applicatio servoing). apply acquired knowled C#, Python, Java). 	n of computer vision in mo dge in higher level program	voidanc obile rot nming l	e and bot cor angua	ntrol (v ges (e	risual e.g. Vis	sual
10 learning	 navigation. demonstrate applicatio servoing). apply acquired knowled C#, Python, Java). evaluate efficiency of p 	n of computer vision in mo dge in higher level program bath planning and navigatio	voidanc obile rot nming l	e and bot cor angua	ntrol (v ges (e	risual e.g. Vis	
10 learning	 navigation. demonstrate applicatio servoing). apply acquired knowled C#, Python, Java). evaluate efficiency of p 	n of computer vision in mo dge in higher level program bath planning and navigation (drone) components.	voidanc obile rot nming l	e and bot cor angua	ntrol (v ges (e	risual e.g. Vis	ours
10 learning	 navigation. demonstrate applications servoing). apply acquired knowled C#, Python, Java). evaluate efficiency of performance content Introduction: mobile robot 	n of computer vision in mo dge in higher level program bath planning and navigatic (drone) components. DE for robot control. ristics, uncertainty represer	voidanc bile rob nming I on algon ntation,	e and pot cor angua rithms.	ntrol (v ges (e	risual e.g. Vis	ours 2
10 learning outcomes)	 navigation. demonstrate application servoing). apply acquired knowled C#, Python, Java). evaluate efficiency of performance content Course content Introduction: mobile robot Microcontrollers. Arduino I Sensors: sensor character types: incremental encode 	n of computer vision in mo dge in higher level program bath planning and navigation (drone) components. DE for robot control. ristics, uncertainty represent ers, position and orientation Drive. Mobile robot control r	voidance bile rob nming I on algor ntation, n senso modes:	e and pot cor angua rithms. sensc rrs, ine	ntrol (v ges (e or rtial	risual e.g. Vis	ours 2 2
10 learning outcomes) Course content	 navigation. demonstrate application servoing). apply acquired knowled C#, Python, Java). evaluate efficiency of performance content Introduction: mobile robot Microcontrollers. Arduino I Sensors: sensor character types: incremental encode sensors, vision sensors. Mobile robot kinematics. Destination of the control of the c	n of computer vision in mo dge in higher level program path planning and navigation (drone) components. DE for robot control. ristics, uncertainty represent ers, position and orientation prive. Mobile robot control re eed and position controller. n, particle and information f	voidance bile rob nming I on algon ntation, n senso modes:	e and pot cor angua rithms. sensc rrs, ine	ntrol (v ges (e or rtial	risual e.g. Vis	2 2 2 4 4 4
10 learning outcomes) Course content broken down in	 navigation. demonstrate application servoing). apply acquired knowled C#, Python, Java). evaluate efficiency of performance content Introduction: mobile robot Microcontrollers. Arduino I Sensors: sensor character types: incremental encode sensors, vision sensors. Mobile robot kinematics. Discontrol, PID controller, specific control, PID controller, specific control, planning and control control	n of computer vision in mo dge in higher level program bath planning and navigation (drone) components. DE for robot control. Fistics, uncertainty represent ers, position and orientation Drive. Mobile robot control re eed and position controller. h, particle and information for control.	voidance bile rob nming I on algon ntation, n senso modes:	e and pot cor angua rithms. sensc rrs, ine	ntrol (v ges (e or rtial	risual e.g. Vis	aours 2 2 4 4 4 2
10 learning outcomes) Course content	 navigation. demonstrate application servoing). apply acquired knowled C#, Python, Java). evaluate efficiency of performance content Introduction: mobile robot Microcontrollers. Arduino I Sensors: sensor character types: incremental encode sensors, vision sensors. Mobile robot kinematics. Decontrol, PID controller, spectime Robot localization: Kalmar Navigation: planning and certification. 	n of computer vision in mo dge in higher level program bath planning and navigation (drone) components. DE for robot control. Fistics, uncertainty represent ers, position and orientation Drive. Mobile robot control re eed and position controller. h, particle and information for control.	voidance bile rob nming I on algon ntation, n senso modes:	e and pot cor angua rithms. sensc rrs, ine	ntrol (v ges (e or rtial	risual e.g. Vis	2 2 4 4 4 2 2
10 learning outcomes) Course content broken down in detail by weekly	 navigation. demonstrate application servoing). apply acquired knowled C#, Python, Java). evaluate efficiency of perficiency of performance control performance performan	n of computer vision in mo dge in higher level program wath planning and navigation (drone) components. DE for robot control. ristics, uncertainty represent ers, position and orientation Drive. Mobile robot control re eed and position controller. n, particle and information for control. for as input.	voidance bile rob nming l on algon ntation, n senso modes: filter.	e and bot cor angua rithms. sensc vrs, ine on-off	ntrol (v ges (e or rtial	risual e.g. Vis	2 2 4 4 4 2 2 2 2
10 learning outcomes) Course content broken down in detail by weekly class schedule	 navigation. demonstrate application servoing). apply acquired knowled C#, Python, Java). evaluate efficiency of performance certain content introduction: mobile robot Microcontrollers. Arduino I Sensors: sensor character types: incremental encode sensors, vision sensors. Mobile robot kinematics. Decontrol, PID controller, sper Robot localization: Kalmar Navigation: planning and certain control with navigation error Visual servoing. 	n of computer vision in mo dge in higher level program bath planning and navigation (drone) components. DE for robot control. ristics, uncertainty represent ers, position and orientation Drive. Mobile robot control re eed and position controller. h, particle and information for control. for as input.	voidance bile rob nming l on algon ntation, n senso modes: filter.	e and bot cor angua rithms. sensc vrs, ine on-off	ntrol (v ges (e or rtial	risual e.g. Vis	2 2 4 4 4 2 2
10 learning outcomes) Course content broken down in detail by weekly class schedule	 navigation. demonstrate application servoing). apply acquired knowled C#, Python, Java). evaluate efficiency of perficiency of performance control performance performan	n of computer vision in mo dge in higher level program bath planning and navigation (drone) components. DE for robot control. ristics, uncertainty represent ers, position and orientation Drive. Mobile robot control re eed and position controller. h, particle and information for control. for as input.	voidance bile rob nming l on algon ntation, n senso modes: filter.	e and bot cor angua rithms. sensc vrs, ine on-off	ntrol (v ges (e or rtial	risual e.g. Vis	2 2 4 4 4 2 2 2 2
10 learning outcomes) Course content broken down in detail by weekly class schedule	 navigation. demonstrate application servoing). apply acquired knowled C#, Python, Java). evaluate efficiency of performance certain content introduction: mobile robot Microcontrollers. Arduino I Sensors: sensor character types: incremental encode sensors, vision sensors. Mobile robot kinematics. Decontrol, PID controller, sper Robot localization: Kalmar Navigation: planning and certain control with navigation error Visual servoing. Selected practical example List of laboratory or design Arduino development environmental environmental certain control provide the sensor control certain c	n of computer vision in mo dge in higher level program wath planning and navigation (drone) components. DE for robot control. ristics, uncertainty represent ers, position and orientation Drive. Mobile robot control re eed and position controller. n, particle and information for control. for as input.	voidance bile rob nming l on algon ntation, n senso modes: filter.	e and bot cor angua rithms. sensc vrs, ine on-off	ntrol (v ges (e or rtial	isual e.g. Vis	2 2 4 4 4 2 2 2 4 hours 2
10 learning outcomes) Course content broken down in detail by weekly class schedule	 navigation. demonstrate application servoing). apply acquired knowled C#, Python, Java). evaluate efficiency of performance certain control contro	n of computer vision in mo dge in higher level program path planning and navigation (drone) components. DE for robot control. ristics, uncertainty represent rist, position and orientation prive. Mobile robot control re eed and position controller. n, particle and information for control. for as input.	voidance bile rob nming l on algon ntation, n senso modes: filter.	e and bot cor angua rithms. sensc vrs, ine on-off	ntrol (v ges (e or rtial	isual e.g. Vis	2 2 4 4 4 2 2 2 4 hours 2 3
10 learning outcomes) Course content broken down in detail by weekly class schedule	 navigation. demonstrate application servoing). apply acquired knowled C#, Python, Java). evaluate efficiency of performance certain content introduction: mobile robot Microcontrollers. Arduino I Sensors: sensor character types: incremental encode sensors, vision sensors. Mobile robot kinematics. Decontrol, PID controller, spee Robot localization: Kalmar Navigation: planning and certain control with navigation error Visual servoing. Selected practical example List of laboratory or design Arduino development enviror Digital I/O – ultrasonic sensors Motor control. Connection of the content of the conte	n of computer vision in mo dge in higher level program path planning and navigation (drone) components. DE for robot control. ristics, uncertainty represent rist, position and orientation prive. Mobile robot control re eed and position controller. n, particle and information for control. for as input.	voidance bile rob nming l on algon ntation, n senso modes: filter.	e and bot cor angua rithms. sensc vrs, ine on-off	ntrol (v ges (e or rtial	risual e.g. Vis	aours 2 2 4 4 4 2 2 2 4 4 5 2 3 3 3
10 learning outcomes) Course content broken down in detail by weekly class schedule	 navigation. demonstrate application servoing). apply acquired knowled C#, Python, Java). evaluate efficiency of performance certain control contro	n of computer vision in mo dge in higher level program path planning and navigation (drone) components. DE for robot control. ristics, uncertainty represent rist, position and orientation prive. Mobile robot control re eed and position controller. n, particle and information for control. for as input.	voidance bile rob nming l on algon ntation, n senso modes: filter.	e and bot cor angua rithms. sensc vrs, ine on-off	ntrol (v ges (e or rtial	risual e.g. Vis	2 2 4 4 4 2 2 2 4 hours 2 3

Format of instruction	 lectures seminars and wo exercises on line in entirety partial e-learning field work 			⊠ mul ⊠ labo	timedia			
Student responsibilities	The presence on lect Performed all require				t least 7	0 % of the time	es schedu	lled.
Screening student	Class attendance	1,5	Researc	h		Practical traini	ng	
work (name the proportion of ECTS	Experimental work		Report			Individual worl	K	2
credits for each activity so that the	Essay		Seminai essay			Laboratory exe	ercises	1
total number of ECTS credits is equal to the ECTS	Tests	0,2	Oral exa	m		Preparation fo laboratory exe		0,1
value of the course)	Written exam	0,2	Project			(Other)		
Grading and evaluating student work in class and at the final exam	During the semester 7 weeks of lectures presentation and de the final test) is car requirement for pas and 50 % points of Students are allowe as long as the final r Grade (in percentag Grade(%) = 0,1L + 0 where: • L – laborato • M1, M2 – m According to Article teaching activities a exercises. If student part in the final exam	and the fense of rried ou sing gra on avera d to hav nidterm e) is for 0,25M1 - ry asses idterm to 65. of l attendin t does r	e second f the proje ade is the age midte ve at leas average med acco + 0,65M2 ssment, est results Faculty's g at leas tot meet	one is a ect assigned tten for positive erm exa t 45% of is at lea ording to s. Bylaw, st 70% these c	after 13 gnment) rmat wit ve asse am ((M of total p ast 50% of the for student of lect riteria, s	weeks of lectu b. Each midtern ch duration of the ssment of labor 1 + M2)/2) or points on each of total points. mula: t is required to ures, and 100 she or he won'	participa porticipa porticipa participa	form of well as es. The cercises exam. exams, te in all poratory to take
		Title	•			Number of copies in the library	Availabi other r	-
	T Siegwart, R., N D., Autonomous 2011.	Mobile	Robots, N	IIT Pres	SS,		teacher/	Internet
Required literature	 Thomas Braunl, robot design and systems, Springe 	applica er, 2006	tions with	embeo	dded		teacher/	
(available in the library and via other	 S. Thrun, W. Bur Robotics, MIT Pr 			babilist	lic		teacher/	Internet
media)	Saeed B. Niku: In Analysis, System 2001.	ntroduct	ion to Ro		e Hall,		teac	her
	 M. Bonković, J. M "Mikroregulatori i Arduino razvojno FESB 	ugradb	eni mreži				e-lear por	
	 J. Musić, M. Bon FESB 	ković: A	uthorised	lecture	e notes,		e-lear por	

Optional literature (at the time of submission of study programme proposal)	 Tadej Bajd: Osnove robotike, Fakulteta za elektrotehniko, Univerza v Ljubljani, 2000. Kovačić, Laci, Bogdan, Osnove robotike, Fakultet elektrotehnike i računarstva, Zagreb, 1999.
Quality assurance methods that ensure the acquisition of exit competences	 Keeping records of student attendance. Annual analysis of course statistics in terms of midterm and finals exams. Feedback from students via surveys. Teacher self-evaluation. Feedback from graduated students (or senior students) on course content relevance. Periodic institutional evolution of course teachers.
Other (as the proposer wishes to add)	/

NAME OF THE COURSE	MODELLING AND CONT	ROL OF VESSELS AND	GROUNE	D VEH	IICLE	S	
Code	FELG27	Year of study	1				
Course teacher	Darko Stipaničev,Ph.D., Full Professor (70%) Damir Krstinić, Ph.D., Associate Professor (30%)	Credits (ECTS)	5				
Associate teachers	Damir Krstinić, Ph.D., Associate Professor	Type of instruction (number of hours)	L 30	S 0	AE 0	LE 30	DE 0
Status of the course	Elective	Percentage of application of e-learning	80				
	COURSE	DESCRIPTION	-				
Course objectives	The aim of the course is ba platforms, underwater vehi automatic control systems	cles) and ground vehicles					
Course enrolment requirements and entry competences required for the course	Basic knowledge of mather To follow the College is ne	matics and principles of au					
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 of transport in relation Apply the mathematical system, kinematic and stability. Describe the vessels (a control. Manageable and Setting up a mathemate Propulsion and steerin the ship. Describe piloting and a automatic stabilization. ship (terrestrial, astronand intelligent auto-pilot Operated Vehicles and control principles. Describe land vehicle a of movement of land vehicles, excav 	proach to automatic contro to the media in which they al modelling of vehicles: loc dynamic equations, linear ship, platform, underwater nd unmanageable freedon tical model of the ship. Hyo g system. Linearized kiner automatic piloting. Stabiliza Navigation and navigation omical, radio and satellite of. Autonomous underwate AUV - Autonomous Under as an object of control. Set ehicles. Drive control struct ators. Remotely operated application of artificial int	I of vehic are movi- cal and gl ization ec- vehicles) n of move drodynam matic and ation of th n systems (GPS) na er vehicle erwater V tting up a stures. Ve vehicles	ing. lobal (quatio) as all ement nic coo l dyna le ves s in th avigati (ROV ehicle math shicles and a	coordi ons of n obje t of the efficient amic m ssel an ion). S / - Ren es) and hematics s with iutono	nate motio ct of ship nts. nodel duct o standa motel d their cal m three mous ic con	n, of of the ard y r odel , four self- htrol
	Course content			b	L ours		.E urs
Course content broken down in detail by weekly class schedule	A systematic approach to a vehicles. Division of means in which they are moving. M movement of vessels and g coordinate sutavi, kinematic linearization equations of m	of vehicles in relation to the Mathematical modeling of t round vehicles: local and c and dynamic equations,	ne media he		4		0
(syllabus)	The vessel (ship, platform, and unmanageable freedon Setting up a mathematical r coefficients. Propulsion and the movement of the ship.	underwater vehicles). Man n of movement of the vess nodel of the vessel. Hydro	el. dynamic		6		0

-	the maritime colleges Mathematical Model (Sodaconstructor - <u>ht</u> Mathematical modeli Simulator) ⊠ ⊠ lectures □ ⊠ seminars and	of the st ttp://sod ing of gr	<u>aplay.co</u> ı ound veh	<u>m</u>) nicles (Rad	cing Ca		0 0 nts	6 6
Format of instruction Student responsibilities	 ☑ ☑ exercises □ o entirety □ partial e-learning □ field work The presence on leo Performed all require 	ctures in	the amo	⊠ ⊠ lab □ work □ unt of at l	oratory with m (othe	entor r)	imes scheo	duled.
Screening student	Class attendance	1,5	Researc			Practical tra	aining	
work (name the proportion of ECTS	Experimental work		Report			Individual v	vork	
credits for each activity so that the	Essay		Semina	r		Laboratory		1,5
total number of	-					Preparatior		
ECTS credits is equal to the ECTS	Tests		Oral exa	am		laboratory		
equal to the ECTS value of the course)	Written exam	2	Project			(Oth	er)	
	Written exam The exam consists the semester will b	of a wri	tten part			y additiona	l oral exar	
activity so that the total number of ECTS credits is equal to the ECTS	Tests Written exam The exam consists the semester will b	of a wri be two t s. A stud	essay Oral exa Project tten part ests. The lent can	am and if ne e first col pass the o who have	ccessar lloquiu course not co	Preparation laboratory ((Oth	n for exercises er) Il oral exar eks of cla ests. In the idequate n	n. During sses, the two final

	autumn periods. All test questions students will be kr	own before th	e exam.						
	These rules apply equally to students who are enroll and to those students who enter college for the seco		e for the first time						
	The final grade is determined as follows: percentage Rating 50% to 61% is sufficient (2) 52% to 74% good (3) 75% to 87% of very good (4) 38% 100% Excellent (5)								
	in all forms of teaching and attend: lectures at least not meet these requirements, the student will not be a signature.	70% of classe	s. If she or he do						
	Title	Number of copies in the library	Availability via other media						
Required literature	 D.Stipaničev, D.Krstinić, Modelling and control of vessels and vehicles, lecturing notes and internal textbook 		e-learning portal						
(available in the library and via other	 Jecić, S.: Mehanika II - kinematika i dinamika, Tehnička knjiga Zagreb, 1989. 								
media)	 Babić, E.; Karmelić, A.: Numeričko modeliranje složenih gibanja, Školska knjiga Zagreb, 1988. 								
	 Fossen, T.I.: Guidance and Control of Ocean Wehicles, J.Wiley, Chicester, 1994 								
Optional literature (at the time of submission of study programme proposal)	AUV Page http://www.transit-port.net/Lists/AUVs.Org The ROV World Gateway http://www.rovworld.com/ ROV Links http://members.chello.nl/rengelsman/ Robotics http://www.nosc.mil/robots/index.html	<u>ı.html</u>							
Quality assurance methods that ensure the acquisition of exit competences	 Evaluation of results in accordance with the above Feedback from students via surveys Self-evaluation of teachers Institutional and non-institutional evaluations 	e learning outo	comes						
Other (as the proposer wishes to add)									

NAME OF THE COURSE	MODERN PHYSICS								
Code	FEMG01 Year of study 1.								
Course teacher	Nikola Godinović, Ph.D., Associate Professor	Credits (ECTS)	4						
A'. (Dunja Polić, Darko Zarić,	Type of instruction	L	S	AE	LE	DE		
Associate teachers	Toni Vrdoljak	(number of hours)	30	0		30	0		
Status of the course	Obligatory	Percentage of application of e-learning	0						
	COURS	E DESCRIPTION							
Course objectives	application in modern eng acquired knowledge serve	aws and concepts of quantu ineering techniques, techno es as a basis for the adoptic ell as preparing for the adop career.	ology an	d info ther e	ormatio xperti	on. Th se thro			
Course enrolment requirements and entry competences required for the course									
	physics on which modern Understanding of the elect	ract thinking and understan technologies are based tric and magnetic propertie	•						
Learning outcomes expected at the level of the course (4 to 10 learning	their atomis structure Understanding the fenomenology of superconductors. Basic understanding of nuclear physics and their aplication for energy generation as well as basic understanding of radioactivity and dosimetry.								
outcomes)	Become familiar with modern diagnostic methods and treatments in medicne: nuclear magnetic resonance (NMR), positron emission tomography (PET), Hadron therapy,								
	Course content			h	L ours		LE ours		
	Special theory of relativity				2				
	General theory of relativity	1			2				
	Particle properties of wave				2				
Course content	Wave properties of particle	9			2				
Course content broken down in	Introduction to wave mech	anics - Schrodinger equati	on		2				
detail by weekly	Application of Schrodinger				2				
class schedule	Schrodinger equation for h			İ	2	1			
(syllabus)	Electrical properties of ma		İ	2					
	Semiconductors				2				
	Magnetic properties of ma	terial		İ	2				
	Phenomenology of superc	onductor		İ	2				
		1	-	-1					
	Atomic nuclei				2				

	List of laboratory or	desian e	exercises				LE hours
	Basics statistics of d						4
	Light interference		19313				2
	Measurement of the	ratio of	electron o	charge	and ma	SS	2
	Photoelectric effect			, nai go			2
	Spectral line of gass	es					2
	Solar cell characteris						2
	Hall effect						2
	Semiconductor phot	o detect	tors				4
	Demonstrations of m	emonstrations of magnetism					
	Demonstration of the	Demonstration of the phenomenology of superconductor					2
	Dosimetry						2
	Measurement of the	gamma	a-rays spe	ctrum			4
Format of instruction	 □ Iectures □ seminars and workshops □ independent assignments □ multimedia □ Iine in entirety □ partial e-learning □ field work □ independent assignments □ multimedia □ work with mentor □ (other) 						
Student responsibilities	The presence on lec	tures in	the amou	int of a	t least 7	0 % of the times sche	eduled.
Screening student work (name the	Class attendance	1,0	Research	h		Practical training	
proportion of ECTS credits for each	Experimental work		Report			Individual work	2,6
activity so that the total number of	Essay		Seminar essay	(Officer)		(Other)	
ECTS credits is equal to the ECTS	Tests	0,2	Oral exa	m		(Other)	
value of the course)	Written exam	0,2	Project			(Other)	
	midterm exam is aft weeks. Each midter questions: The requirement for	er 7 we rm test	eks of leo lasts for g grade a	tures a 90 min t the m	and the nutes a nidterm	d one make-up exan second one is after and consists of the f exams is to have at one of the midterm of	the next 6 ollowing 4 least 50%
	from each of 4 questions. Students that do not pass one of the midterm exams can retake it during the final exams. Final exams lasts 135 minutes each and consist out of the following 6 questions:						
Grading and evaluating student	The requirement for passing grade at the final exam is to have at 50% from each of 6 questions.						
work in class and at the final exam							ave s: 15% of ellent), de B ans are g s have one

	Title	Number of copies in the library	Availability via other media			
Required literature (available in the	 Knapp, V.; Colić, P.: Uvod u električna i magnetska svojstva materijala, Školska knjiga, Zagreb, 1997 					
library and via other media)	 I. Supek, M. Furić: Počela fizike, Školska knjiga, Zagreb, 1994. 					
	 A. Beiser: Concepts of Modern Physics, sixth edition, McGraw-Hill 2003 					
Optional literature (at the time of submission of study programme proposal)	 E.V. Wichmann: Kvantna Fizika, udžbenik fizike S 4., Tehnička knjiga, Zagreb, 1988. D. Halliday, R. Resnick, J. Walker: Fundamentals Wiley & Sons, Inc., 2013. Vladimir Šips, Uvod u fiziku čvrstog stanja, Škols 	of Physics 10t	h edition, John			
Quality assurance methods that ensure the acquisition of exit competences	 Viadimir Sips, 0vod u liziku cvistog stanja, Skolska knjiga 2000. Student evaluation surveys Teacher self-evaluation Institutional and non-institutional evaluations 					
Other (as the proposer wishes to add)						

NAME OF THE COURSE	MULTIVARIABLE CON	TROL									
Code	FELG26	Year of study	2.								
Course teacher	Jadranka Marasović, Ph.D., Full Professor	Credits (ECTS)	5								
		Type of instruction	L	S	AE	LE	DE				
Associate teachers		(number of hours)	30	0	0	30	0				
Status of the course	Elective	Percentage of application of e-learning									
	COUR	SE DESCRIPTION									
Course objectives	everyday life almost there independent work of com physically allowable cont concepts of multivariabel subsystems for which the	stand the possibilities of aut a are no simple systems and plex systems should be the rol. Enable students to acqu control and how to connect whole, joint work is necess	to und result o ire kno t a num	lerstar of thou wledge iber of	nd that ightful e abou differ	the and it the b ent					
Course enrolment requirements and entry competences required for the course	interactions. None.										
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 problems of complex apply mathematical m problems for the auto apply a simulation on calculate the fundame methods of analysis (choose the appropriat tasks and possibilities 	interactions, nodels of multivarible system mated processes design, a digital computer to suppor ental characteristics of the sy time and frequency domain) te methods for the synthesis	ns and ta	to und ontrol by mea king a	evel problems for the automated processes design,						
	Course content					t of the	Э				
					L	-	e \E				
	application. System theorem	tasks, issues and areas of ry. Control. theory Control lo	op.		L nours 2	A hc					
	application. System theor Systems modeling. Single input-single output	ry. Control. theory Control lo	•		nours	A hc	\E ours				
	application. System theor Systems modeling. Single input-single output multi output (MIMO) syste Mathematical models of r model and Laplace transit	ry. Control. theory Control lo t (SISO) system toward mult em. multivarable systems, state s form presentation.	ti input-		nours 2	/ hc	AE ours 0				
Course content	application. System theor Systems modeling. Single input-single output multi output (MIMO) syste Mathematical models of r model and Laplace transf Dynamic systems simula	ry. Control. theory Control lo t (SISO) system toward mult em. multivarable systems, state s form presentation. tion.	ti input-		nours 2 2 2 2 2	/ hc	AE ours 0				
Course content broken down in detail by weekly	application. System theor Systems modeling. Single input-single output multi output (MIMO) syste Mathematical models of r model and Laplace transi Dynamic systems simula ITransfer matrix. Multivar	ry. Control. theory Control lo t (SISO) system toward mult em. multivarable systems, state s form presentation. tion. iable system response in tim	ti input- space		2 2 2 2		AE ours 0 0				
broken down in	application. System theor Systems modeling. Single input-single output multi output (MIMO) syste Mathematical models of r model and Laplace transf Dynamic systems simula ITransfer matrix. Multivar The complex systems an response in time domain:	ry. Control. theory Control lo t (SISO) system toward mult em. multivarable systems, state s form presentation. tion. iable system response in tim alysis. The parts of the syste transient part and steady st	ti input- space ne. ems tate par		nours 2 2 2 2 2		AE ours 0 0 0 0				
broken down in detail by weekly class schedule	application. System theor Systems modeling. Single input-single output multi output (MIMO) syste Mathematical models of r model and Laplace transf Dynamic systems simula ITransfer matrix. Multivar The complex systems an response in time domain: Multivariable system and window.	ry. Control. theory Control lo t (SISO) system toward mult em. multivarable systems, state s form presentation. tion. iable system response in tim alysis. The parts of the syste transient part and steady st matrix of interaction. Opera	ti input- space ne. ems tate par		2 2 2 2 2 2 2		AE ours 0 0 0 0 0				
broken down in detail by weekly class schedule	application. System theor Systems modeling. Single input-single output multi output (MIMO) syste Mathematical models of r model and Laplace transi Dynamic systems simula ITransfer matrix. Multivar The complex systems an response in time domain: Multivariable system and window. Multivariable system stat	ry. Control. theory Control lo t (SISO) system toward mult em. multivarable systems, state s form presentation. tion. iable system response in tim alysis. The parts of the syste transient part and steady st matrix of interaction. Opera	ti input- space ne. ems tate par ting	rt.	2 2 2 2 2 2 2 2 2		AE ours 0 0 0 0 0 0				
broken down in detail by weekly class schedule	application. System theor Systems modeling. Single input-single output multi output (MIMO) syste Mathematical models of r model and Laplace transi Dynamic systems simula ITransfer matrix. Multivar The complex systems an response in time domain: Multivariable system and window. Multivariable system state Basic concepts of matrix	ry. Control. theory Control lo t (SISO) system toward mult em. multivarable systems, state s form presentation. tion. iable system response in tim alysis. The parts of the syste transient part and steady st matrix of interaction. Opera	ti input- space ne. ems tate pai ting for a fu	rt.	nours 2		AE ours 0 0 0 0 0 0 0				
broken down in detail by weekly class schedule	application. System theor Systems modeling. Single input-single output multi output (MIMO) syste Mathematical models of r model and Laplace transi Dynamic systems simula ITransfer matrix. Multivar The complex systems an response in time domain: Multivariable system and window. Multivariable system state Basic concepts of matrix	ry. Control. theory Control lo t (SISO) system toward mult em. multivarable systems, state s form presentation. tion. iable system response in tim alysis. The parts of the syste transient part and steady st matrix of interaction. Opera pility analysis. algebra that are necessary	ti input- space ne. ems tate pai ting for a fu	rt.	nours 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2		AE ours 0 0 0 0 0 0 0 0				
broken down in detail by weekly class schedule	application. System theor Systems modeling. Single input-single output multi output (MIMO) syste Mathematical models of r model and Laplace transi Dynamic systems simula ITransfer matrix. Multivar The complex systems an response in time domain: Multivariable system and window. Multivariable system stat Basic concepts of matrix analysis. Multivariable sy Decoupling control. Feedforward control and	ry. Control. theory Control lo t (SISO) system toward mult em. multivarable systems, state s form presentation. tion. iable system response in tim alysis. The parts of the syste transient part and steady st matrix of interaction. Opera bility analysis. algebra that are necessary to stem controllability and obse	ti input- space ne. ems tate pat ting for a fu	rt.	nours 2		AE ours 0 0 0 0 0 0 0 0 0 0				

	Multivariable control	concep	ts used in	h the ca	e of sin	gle input-		0
	single output tasks.					5 1	2	0
	List of laboratory or	design e	exercises					LE hours
	Dynamic multivariabl							2
	Testing by means of conversions. Transiti							2
	The analysis of the ir several outputs. A sir							2
	The analysis of the m parts of the systems	nultivaria	able first a	and the	second	order syste	ems. The	2
	state part.							
		ultivariabel systems stability. ontrollability and observability used for the simple controller synthesis,						
	Decoupling control a						11118515,	2
	The choice of control						ntrol and	
	the disturbance reject			10 0000	011000		and and	2
	Optimal control.							2
	Kalman filter and sim	ulation	presentat	tion of it	s work.			2
	Seminar essay.							2
				🖂 inde	epender	nt assignme	nts	
	□ seminars and wo	rkshops	i i		timedia			
Format of instruction	exercises				oratory			
	□ on line in entirety				k with m	nentor		
	□ partial e-learning							
	☐ field work					,		
Student	Minimum of 70 perce	ent lectu	ure attend	lance. (Complet	ing all the r	equired lab	oratory
responsibilities	exercises.		1					
Screening student work (name the	Class attendance	1.5	Researc	h		Practical training		
proportion of ECTS credits for each	Experimental work		Report	•		work	0.5	
activity so that the total number of	Essay		Semina essay	-	1	Laboratory	exercises	1
ECTS credits is equal to the ECTS	Tests	0.5	Oral exa	ım		(Other)		
value of the course)	Written exam	0.5	Project			(Other)		
Grading and evaluating student work in class and at the final exam	During semester, there will be two mid-term exams – according to the class schedule. The requirement for the positive grade is the attendance and commitment at the laboratory exercises, minimum of 40 percent correct answers a one mid-term and a final grade is determined with minimum of 50 percent tota correct answers. The final grade is determined based on the total number of points earned, which is calculated as follows: Grade [%] = 0.5 * M1 + 0.5*M2 Percentage Grade 50% to 61% sufficient (2) 62% to 74% good (3) 75% to 87% very good (4) 88% to 100% excellent (5) The final exam encompasses the entire course load or selected parts of it tha students' did not pass at either of mid-term exams. The correction exam encompasses the entire course load. The requirement for passing the exam is minimum of 50 percent correct answers. The exams are held according to the class schedule.							of it that exam is

	Title	Number of copies in the library	Availability via other media
Required literature (available in the library and via other	 J. Marasović; "Basics Steps of Automatic Control" (in Croatian: Temeljni postupci u automatici), FESB, Authorized lectures 		e-learning portal
media)	 J Božičević J.: "Basics of Automatic Control 1" (in Croatian: Temelji automatike 1), Školska knjiga, Zagreb, 1990 		
	 G. Nikolić : "Automatic Control" (in Croatian: Upravljanje), Školske novine, Zagreb 1996. 		
Optional literature (at the time of submission of study programme proposal)	 T. Šurina: " (in Croatian: Automatska regulacija), B. Novaković: " Methods of Technical Systems Covođenja tehničkih sistema), Školska knjiga, Zagre 	ontrol" (in Croa	
Quality assurance methods that ensure the acquisition of exit competences	 Keeping records on class attendance Annual analysis of exam results Student survey on teaching performance Teacher self-evaluation Feedback information from graduates regarding of 	ourse content	relevancy
Other (as the proposer wishes to add)			

NAME OF THE COURSE		SYSTEMS	;						
Code	FELG11 Year of study 1								
Course teacher	Mojmil Cecić, Ph.D., Full Professor	Credits (E		5					
Associate teachers	Ana Kuzmanić Skelin, Ph.D., Assistant Professor	Type of ir (number	S 0	AE 30	LE 0	DE 0			
Status of the course	Obligatory	Percenta applicatio	ge of n of e-learning	0					
	COURSE	DESCRI	PTION						
Course objectives	 Training students for: understanding and app to analyse nonlinear co analysis of the nonlinea analysis of the nonlinea permanent adoption an control systems. 	ntrol syste ir control s ir control s	ms, ystems in the tir ystems in the pl	ne don nase pl	nain, ane,				
Course enrolment requirements and entry competences required for the course	None								
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to: define the fundamental control systems, present various nonline analyse of the nonlinea describe different nonli analyse the stability of analyse the nonlinear of 	earities, ar control s nearities v the nonline	ystems in the til vith describing for ear control syste	me don unction ems,	nain,	of the	nonlin	ear	
	Course content					L	A	١E	
						hours		ours	
-	Fundamentals of nonlinear		eory			2	_	2	
Course content broken down in	Typical nonlinearities,Relay					2		4	
detail by weekly	Transient processes in rela					4		4	
class schedule	Linearization of nonlinear s	-				2		2	
(syllabus)	Method of harmonic lineari Stability of relay systems	zation, De	scribing function	1		4	_	2	
						4		4	
	Phase portraits Phase plane analysis					4		4	
						4		4	
Format of instruction	 ➢ lectures ➢ seminars and workshops ➢ exercises ○ on line in entirety ○ partial e-learning ○ field work ➢ lectures ○ independent assignments ○ multimedia ○ laboratory ○ work with mentor ○ (other) 								
Student responsibilities	The presence on lectures i	n the amo	unt of at least 70) % of 1	the tim	ies scł	nedule	d.	

Screening student	Class attendance	2,0	Research		Practical traini	ng	
work (name the proportion of ECTS	Experimental work		Report		Individual worl	ĸ	2,5
credits for each activity so that the total number of	Essay		Seminar essay	0,2	(Other)		
ECTS credits is	Tests	0,2	Oral exam		(Other)		
equal to the ECTS value of the course)	Written exam	0,1	Project		(Other)		
Grading and evaluating student work in class and at the final exam	 There are two midterms and final exams. The first midterm exam is after 7 we lecturing and the second one is after the next 6 weeks. The requirement for passing grade is 50% points on each midterm exam or the exam. Grade (in percentage) is formed according to the formula: Grade [%] =0,5* (M1 + M2) where M1 and M2 are the results of the midterm exams in percentage. Each midterm test consists of 10 theoretical questions and numerical problem final test also consists of 10 theoretical questions and numerical problems of into two groups (the first and the second part). The requirement for passing is 50% of the total number of questions. The students who did not pass the mexams take part in the final exam. The midterm and final exams are carried written tests. Finally grade is determined as follows: from 50% to 62.5% - dovoljan (2) from 62.5% to 75% - dobar (3) from 75% to 87.5% - vrlodobar (4) from 87.5% to 100% - izvrstan (5) 						
		Title			Number of copies in the library	Availabi other n	-
Required literature (available in the library and via other		larquez Analysi e 2003		Contro sign			
media)	 Jean-Jacques S Nonlinear Control 				1		
	 Mojmil Cecić, I authorized lectur 		• •	sustavi	,	e-lear port	-
Optional literature (at the time of submission of study programme proposal)	 Henk Nijmeijer, Springer Verlag, 	-	an Der Schaft,	Nonline	ar Dynamical (Control Sy	/stems,
Quality assurance methods that ensure the acquisition of exit competences	 Evaluation of results in accordance with the above learning outcomes Feedback from students via surveys Self-evaluation of teachers Institutional and non-institutional evaluations 						
Other (as the proposer wishes to add)							

NAME OF THE COURSE	NUMERICAL ANALYSIS								
Code	FEMK01	Year of study	1						
Course teacher	Ivan Slapničar, Ph.D., Full Professor	Credits (ECTS)	5						
	Lana Periša	Type of instruction	L	S	AE	LE	DE		
Associate teachers	Anita Carević	(number of hours)	30		30				
Status of the course	Elective	Percentage of application of e-learning	20						
	COURSE	E DESCRIPTION							
Course objectives	computer aruthmetics, s interpolation, splines, lea nonlinear equations, sol	and skills of numerical an olving systems of linear ed ast squares method, nume ving digfferential equation e concepts to natural scier	quation erical in s,	s, poly tegrati	nomia on, so	al Iving			
Course enrolment requirements and entry competences required for the course						<u> </u>			
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 stability, estimate duration of the explain main ideas beh derive basic numerical write simple computer languages (Matlab or J find and use computer and critically estimate t 	ibnd numerical methods, mathods and illustrate the programs for numerical me ulia), programs for numerical m heir properties, merical methods and apply	eir prope ethods athods	erties l in som availa	by exa ne of h ble on	mples igler-le Interr compt	, evel net uter		
	Course content				L nours		\E ours		
	1. Computer arithmetic and	d error analysis.			2		2		
	2. Stable and unstable cor		nber.		2		2		
	3. Solving systems of linea and iterative methods.	n	2		2				
	4. Evaluating functions – H	lorner's method.			2		2		
Course content	5. Approximating functions	- interpolation polynomia	ls.		2		2		
broken down in	6. Splines.				2		2		
detail by weekly	7. Least squares method a	and minimax method.			2		2		
class schedule (syllabus)	8. Solving nonlinear equat and secant method.	ions – bisection, Newton's	metho	d	2		2		
())))))))	9. Fixed-point theorem and	d functional iteration.			2		2		
	10. Numerical integration - formula and error estimate		n's		2	2			
	11. Gaussian quadrature, l integration.		adaptive	e	2		2		
	12. Numerical solution of c single-step methods.	ordinary differential equation	ons –		2		2		
	13. Multi-step methods and	d Runge-Kutta methods.			2		2		

	List of laboratory or o	design e	exercises			LE or DE hours
Format of instruction	 x lectures seminars and workshops x exercises on line in entirety partial e-learning field work x independent assignments multimedia laboratory work with mentor (other) 					
Student responsibilities	Regular attendence	to and a	ctive participatic	on in lect	ures and excercises.	-
Screening student					Practical training	
work (name the proportion of ECTS	Experimental work		Report		Self study	2
credits for each activity so that the total number of ECTS credits is equal to the ECTS	Essay		Seminar essay		(Other)	
	Tests	0.5	Oral exam		(Other)	
value of the course)	Written exam	0.5	Project		(Other)	
Grading and evaluating student work in class and at the final exam	weeks of lectures, a term exam students through assignement the course is minimup points. After semeste Students which did exam during final exa Students which did comprehensive cour is 80. The condition and a total of at leas 85 and more points - 75-84 points - very g 60-74 points - good (50-59 points - sufficient Students who did no at leat 10 points, ca number of points is minimum of 40 points	nd the s can ge its durin im 20 pe er, two fi not pas ams. I not p se conte for pas t 50 poir excelle ood (4), (3), and ent (2). t pass t an atten s 80, ar s in the	second in the we t 40 points, whil og lectures and oints on each m nal exams and t as one mid-term ass any mid-ter ent. In that case sing the course nts. The grade is nt (5), he course after t d corrections ex nd the minimun exam and a tota	eek follo e the re excercis id-term (wo corre n exam, masim is minim formed final exa kam. Or n requir l of at le	ims, and have obtaine in the correction exam ement for a passing	each mid- e attained r passing it least 50 art of the xam with ble points hal exam d total of maximal grade is

	Title	Number of copies in the library	Availability via other media
	R. Scitovski, Numerička matematika, drugo izdanje, Sveučilište J. J. Strossmayera, Odjel za matematiku, Osijek, 2004. I.		http://www.math os.hr/~scitowsk/ NM/Num.PDF
library and via other	Lecture materials on FESB e-learning portal.		https://elearni ng.fesb.hr
	FESBMat		https://github.co m/ivanslapnicar/ FESBMat
	Netlib		http://www.netlib .org
Optional literature (at the time of submission of study programme proposal)	 D. Goldberg, What every computer scientist s point arithmetic, <u>http://docs.sun.com/source/8</u> D. Kincaid, W. Cheney, Numerical Analysis-M Computing, Brooks/Cole Publishing Company G. W. Stewart, Afternotes on Numerical Analysis S. Singer, Numerička matematika, Predavanj Zagreb, 2009. S. Singer, Numerička matematika, Vježbe, Sv Zagreb, 2009 	806-3568/ncg lathematics of y, 2002. /sis, SIAM, Ph a, Sveučilište	<u>goldberg.html</u> Scientific iladelphia, 1996. u Zagrebu, FSB,
Quality assurance methods that ensure the acquisition of exit competences	 homework short tests quizzes mid-term exams final exam student questionnaires 		
Other (as the proposer wishes to add)			

NAME OF THE COURSE	OPERATIONS RESEARCH							
Code	FELG14	Year of study	1.					
Course teacher	Jadranka Marasović, Ph.D., Full Professor	Credits (ECTS) 5						
		Type of instruction	L	S	AE	LE	DE	
Associate teachers	Martina Bašić, mag.img.	(number of hours)	30	0	0	30	0	
Status of the course	Elective	Percentage of application of e-learning	0					
	COURSI	E DESCRIPTION						
Course objectives	fastest and organized search for optimal solutions, too. To enable students to acquire practical knowledge, user-oriented, on the need for software solutions and precision interface in order to work independently to obtain optimal solutions.							
Course enrolment requirements and entry competences required for the course	None	Examples from everyday life are used. None						
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 iimplement models of di (graphs, tables, text) models apply mathematical compurpose of these conversion if the solutions and methods describe the difference is search methods and descrisolving, pick and sort out the prosent of the solution solution of the solution of the solution of the solution of the solution of the solution of the solution of the solution is apply the results optimus calculate the strategic of the solution of the solution of the strategic of the solution of the strategic of the	 Students will be able to: 1. iimplement models of different systems, quantitative (math) and qualitative (graphs, tables, text) models, 2. apply mathematical conversion to the original models and to understand the purpose of these conversions in the application of known methods of optimization, if the solutions and methods for the original model do not exist, 3. describe the difference between defined mathematical optimization methods and search methods and describe the impossibility of finding a universal method of solving, 4. pick and sort out the proper method of optimization based on model, 5. apply the results optimum analysis on the appropriate practices, 6. calculate the strategic optimum, 7. solve independently complex tasks of optimizing where it is necessary to 						
	Course content				L		λE	
Course content broken down in	bounded contenthourshourshoursIntroduction: Systems approach and purpose and power of modeling (in the analysis and understanding of systems acting and in the problems with the synthesis of the "living" systems). The model is an approximation of the system.20Modeling is an iterative process during which resolves a compromise between complex models and quality of approximation.20							
detail by weekly class schedule (syllabus)	Quantitative models and differences of the systems characteristics: deterministic, stochastic, static, dynamic, continuous, discrete, linear and nonlinear. The selection of input and output variables and their impact on the complexity of the model. Physical, economic and other laws as a basis for building models. Qualitative models.2							
	The impact of constraints on the behavior of the system and how to add them to the original model - space of solutions. Objective function as an indicator of optimality. Optimal is not perfect - depends on objective function,on2							

constraints and on methods of solving. Multidisciplinary		
approach as the main feature of all tasks optimization.		
Operations research, history and way of thinking with the tasks of optimization.		
Mathematical conversions and mathematical operations -	2	0
basic ideas used through the orientation in space of solutions	2	U
and seeking optimum.		
Linear static models. The standardization of models. Problems		
with unbounded spaces solutions (infinite limits).	2	0
Simplex algorithm - one of 10 the best algorithms of the 20th		
century. Examples of solving. The meaning of optimality	2	0
criteria and feasibility criteria.	2	U
Qualitative models - poorly structured models. Heuristics.		
Search. Branching (Branch and Bound method).	2	0
Transport problem. Methods seeking basic possible solutions		
	2	0
and methods of seeking improved solution to the optimum -	2	0
the basics of search.		
Transport problems with ambiguous warehouses	2	0
(transshipment problem)		
0-1 Programming. Backpack problem (loading / unloading).	2	0
Travelling salesperson.		
Game theory and optimal strategic decisions-making.	2	0
Nonlinear Programming: mathematical procedures that can	2	0
create problems to resolve and seek optimum. It is essential to		
create characteristic search, which can become complicated,		
but can unexpectedly diverge. Basic information are what,		
why and how to keep it under control.		
Graph theory. Modeling events and activities. Optimization	2	0
tasks modeled using graph theory (CPM method - Critical Path		
Method). Software solutions such tasks.		
List of laboratory or design eversions		LE
List of laboratory or design exercises		hours
Postoptimal analysis, the reasons for its implementation to the o	ptimal	2
results from the practice.		Z
Sensitivity analysis of optimal solutions depending on the chang	e of the	2
coefficients of the objective function. Examples.		2
	e of the	
Sensitivity analysis of optimal solutions depending on the chang	e of the	2
Sensitivity analysis of optimal solutions depending on the chang coefficient from the right side of constraints. Examples.		2
Sensitivity analysis of optimal solutions depending on the chang coefficient from the right side of constraints. Examples. Preparing for use of already created software solutions with exa		
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 Sensitivity analysis of optimal solutions depending on the chang coefficient from the right side of constraints. Examples. Preparing for use of already created software solutions with exa linear programming, data for software: input and output Integer programming: the need and ways to search for such solu linear programming. Examples. A simple example of solving linear programming tasks - solving already created software on a digital computer and "hand-made mathematical solutions". Testing problems of parameters sensitivity, solving tasks using a created software on a digital computer and "hand-made mathematics." Solving simple example of dual Simplex, using digital computer graphics solutions. The application of the dual simplex in practice with the example optimal cutting shape, minimization of material thrown. The use of linear programming tasks in automation systems. Solving examples of optimal transport of goods between several Croatia - the basic transport problem. 	mples of itions in using ilready atical and of towns in	2 2 2 2 2 2 2 2 2 2
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Sensitivity analysis of optimal solutions depending on the chang coefficient from the right side of constraints. Examples. Preparing for use of already created software solutions with exa linear programming, data for software: input and output Integer programming: the need and ways to search for such solu linear programming. Examples. A simple example of solving linear programming tasks - solving already created software on a digital computer and "hand-made mathematical solutions". Testing problems of parameters sensitivity, solving tasks using a created software on a digital computer and "hand-made mathem solutions". Solving simple example of dual Simplex, using digital computer graphics solutions. The application of the dual simplex in practice with the example optimal cutting shape, minimization of material thrown. The use of linear programming tasks in automation systems. Solving examples of optimal transport of goods between several Croatia - the basic transport problem. Solving examples of optimal transport of goods between several Croatia - ambiguous warehouses.	mples of Itions in Using Ilready atical and of towns in cities in	2 2 2 2 2 2 2 2 2 2
 Sensitivity analysis of optimal solutions depending on the chang coefficient from the right side of constraints. Examples. Preparing for use of already created software solutions with exa linear programming, data for software: input and output Integer programming: the need and ways to search for such solu linear programming. Examples. A simple example of solving linear programming tasks - solving already created software on a digital computer and "hand-made mathematical solutions". Testing problems of parameters sensitivity, solving tasks using a created software on a digital computer and "hand-made mathematics". Solving simple example of dual Simplex, using digital computer graphics solutions. The application of the dual simplex in practice with the example optimal cutting shape, minimization of material thrown. The use of linear programming tasks in automation systems. Solving examples of optimal transport of goods between several Croatia - the basic transport problem. Solving examples of optimal transport of goods between several Croatia - ambiguous warehouses. 	mples of Itions in Using Ilready latical and of towns in cities in ring	2 2 2 2 2 2 2 2 2 2 2 2 2
 Sensitivity analysis of optimal solutions depending on the chang coefficient from the right side of constraints. Examples. Preparing for use of already created software solutions with exa linear programming, data for software: input and output Integer programming: the need and ways to search for such solu linear programming. Examples. A simple example of solving linear programming tasks - solving already created software on a digital computer and "hand-made mathematical solutions". Testing problems of parameters sensitivity, solving tasks using a created software on a digital computer and "hand-made mathematical solutions". Solving simple example of dual Simplex, using digital computer graphics solutions. The application of the dual simplex in practice with the example optimal cutting shape, minimization of material thrown. The use of linear programming tasks in automation systems. Solving examples of optimal transport of goods between several Croatia - the basic transport problem. Solving examples of optimal transport of goods between several Croatia - ambiguous warehouses. Illustration "the power of models" in the example of problem-solv scheduling (students - classrooms). The problem layout, basical 	mples of Itions in Using Iready atical and of towns in cities in ring y 0-1	2 2 2 2 2 2 2 2 2 2 2 2 2 2
 Sensitivity analysis of optimal solutions depending on the chang coefficient from the right side of constraints. Examples. Preparing for use of already created software solutions with exa linear programming, data for software: input and output Integer programming: the need and ways to search for such solu linear programming. Examples. A simple example of solving linear programming tasks - solving already created software on a digital computer and "hand-made mathematical solutions". Testing problems of parameters sensitivity, solving tasks using a created software on a digital computer and "hand-made mathematical solutions". Solving simple example of dual Simplex, using digital computer graphics solutions. The application of the dual simplex in practice with the example optimal cutting shape, minimization of material thrown. The use of linear programming tasks in automation systems. Solving examples of optimal transport of goods between several Croatia - the basic transport problem. Illustration "the power of models" in the example of problem-solv 	mples of Itions in Using Iready atical and of towns in cities in ring y 0-1	2 2 2 2 2 2 2 2 2 2 2 2 2

	Problem solving trave Croatia.	Problem solving traveling salesman, optimal touring several cities in Croatia.							
Format of instruction	 □ seminars and workshops □ multimedia □ exercises □ on line in entirety □ partial e-learning □ field work □ multimedia ⊠ laboratory □ work with n ⊠ seminar estimation 			nentor ssay (other)					
Student responsibilities	Minimum of 70 perce exercises.	ent lectu	ire attend	lance. (Complet	ting all the requi	ired labo	ratory	
Screening student work <i>(name the</i>	Class attendance	1.5	Researc	h		Practical traini	ng		
proportion of ECTS credits for each	Experimental work		Report			Individual work	(0.5	
activity so that the total number of	Essay		Seminai essay		1	Laboratory exe	ercises	1	
ECTS credits is	Tests	0.5	Oral exa	ım		(Other)			
equal to the ECTS value of the course)	Written exam	0.5	Project			(Other)			
Grading and evaluating student work in class and at the final exam	will be held during cl the end of classes. I 40% correct answers be at least 50% corr It is necessary during recognized (enrolled The final grade is de calculated as follows Percentage Gra 50% to 61% suff 62% to 74% goo 75% to 87% very 88% to 100% exc The final exam end students' did not encompasses the e	50% to 61% sufficient (2) 62% to 74% good (3) 75% to 87% very good (4)							
Required literature (available in the		Title	•			Number of copies in the library	Availab other	ility via media	
library and via other media)	J.Marasović: "Introdu (in Croatian: Uvod u Authorized lectures,	operaci	ijska istra					rning rtal	
Optional literature (at the time of submission of study programme proposal)	 T.B. Boffey: "Gr Kong, 1982. R. Bronson, G. Operations Rese H.A. Taha: "Operations" 	Naadii arch, M	nuthu: "(cGraw H	Operati ill, 1998	ons Re 3.	esearch", Scha	um's Ou		
Quality assurance	Keeping records on class attendance Appual analysis of exam results								
methods that ensure the acquisition of exit competences Other (as the proposer	- Teacher self-eva	luation	• •			course content	relevanc	ÿ	

NAME OF THE COURSE	OPTIMIZATION AND OP	TIMAL SY	STEMS					
Code	FELG23	Year of s	udy	2.				
Course teacher	Mirjana Bonković, Ph.D., Full Professor	Credits (E	ECTS)	5				
		Type of ir	struction	L	S	AE	LE	DE
Associate teachers		(number		30	0	0	30	0
Status of the course	Obligatory	Percenta application	ge of n of e-learning	0				
	COURS	E DESCRI						
Course objectives	Training students for adop optimization procedures fo robot control, production p content.	or solving p	roblems in the f	ields of	engin	eering	, such	as
Course enrolment requirements and entry competences required for the course								
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to: Apply optimization me model, defining an opt exploring the solution a Understand and apply problems, including the descent, Newton's me Understand basic theo Understand and apply exhaustive search and Understand and apply constraints. Have some familiarity 	imization p and interpr unconstra e necessar thod, conju prems of qu discrete al d simulated the simple	roblem, applyin eting results. ned optimizatio y and sufficient gate gradient a asi-Newton me gorithms, incluc annealing. x algorithm for s	g optim n theor conditi nd qua thods. Jing bra solving	nization by for c ons ar si-Nev anch a	ontinu ontinu nd stee vton m	nods, ious epest nethods und,	S.
	Course content							ours
	Introduction. Models of eng	aineering o	ntimization					nours 2
	Mathematical modeling. O		-					2
0	Performance of feedback							2 4
Course content broken down in	Optimization without const			ewton'	s moth	nd		4
detail by weekly	Discrete optimization. Sim							4
class schedule	Optimization with constrair		-	-		thm		4
(syllabus)	Non-linear optimization with				aigon	unii.		4
	The calculus of variations.	un consulai						2
	Case studies: Application	of nonlinea	r optimization m	nethods	s for vi	sual		2
	servoing.	medical in						6
Format of instruction	 ☑ lectures ☑ seminars and workshops ☑ exercises ☑ multimedia 				ps ⊠ multimedia □ laboratory ⊠ work with mentor			
Student responsibilities								

Screening student	Class attendance	2	Research		Practical traini	ng			
work (name the proportion of ECTS	Experimental work		Report		Individual worl	K	1		
credits for each activity so that the	Essay		Seminar essay		Laboratory exe	ercises	0		
total number of ECTS credits is equal to the ECTS	Tests	0,3	Oral exam		Preparation fo laboratory exe		0		
value of the course)	Written exam	0,3	Project	1,4	(Other)				
Grading and evaluating student work in class and at the final exam	During the semester, students receive smaller project tasks that have to be addressed. In addition, there are two midterm exams. The first midterm exam after 7 weeks of lectures and the second one is after 13 weeks of lectures (in form of presentation and defense of the project assignment). Each midterm test (a well as the final test) is carried out in a written format with duration of 90 minute The requirement for passing grade is the positive assessment of project tasks ar 50 % points on average midterm exam ((M1 + M2)/2) or the final exam. Studen are allowed to have at least 45% of total points on each midterm exams, as long a the final midterm average is at least 50% of total points. Grade (in percentage) is formed according to the formula: Grade(%) = 0,5M1 + 0,5M2 where: • M1, M2 – midterm test results. It is possible to be relieved of the midterm exams in case of making extensiv smaller project tasks. According to Article 65. of Faculty's Bylaw, student is required to participate in a teaching activities attending at least 70% of lectures, and 100% of laboratoo exercises. If student does not meet these criteria, she or he won't be able to tak part in the final exam, and will be required to enroll in the course the next year.								
		Number of copies in the library	Availabi other r	-					
Required literature	D. Pierre, Optimizati John Willey & Sons,			e-learnin	g				
(available in the library and via other	M. Bonković: Autoriz			e-learnin	g				
media)	http://apmonitor.com hapters (10.03.2017								
	V. Zanchi, Optimizad	,	učilište u Splitu,	1983.		e-learnin	g		
Optional literature (at the time of submission of study programme proposal)	 bookboon.com (' Numerical Recipe Press, Brian P. F Convex Optimization Stephen Boyd or 	 Kamran Iqubal: Fundamental Engineering Optimization Methods, bookboon.com (19.03.2017.) Numerical Recipes in C (or C++) : The Art of Scientific Computing, by William H. Press, Brian P. Flannery, Saul A. Teukolsky, William T. Vetterling. Convex Optimization, Stephen Boyd & Lieven Vandenberghe, 2004 Stephen Boyd on Convex Optimizations pdfs video lectures 							
Quality assurance methods that ensure the acquisition of exit competences	 Annual analysis of Feedback from s Teacher self-eva 	 Annual analysis of course statistics in terms of midterm and finals exams. Feedback from students via surveys. Teacher self-evaluation. Feedback from graduated students (or senior students) on course content relevance. 							
Other (as the proposer wishes to add)									

NAME OF THE COURSE	OPTOELECTRONIC MEASUREMENT METHODS							
Code	FELG33	Year of study						
Course teacher	Ivo Stančić, Ph.D., Assistant Professor	Credits (ECTS)	5					
Associate teachers		Type of instruction (number of hours)	S	AE	LE 30	DE		
Status of the course	Elective	Percentage of application of e-learning	30 0			00		
	COURSI	E DESCRIPTION	I					
Course objectives	 Training students for: Understand the basic principles of camera and optical lens elements Operate with linear, IR / night and heat cameras Apply camera to control industrial process or use it as a sensor Operate and analyze data from laser range finders and LIDAR 							
Course enrolment requirements and entry competences required for the course								
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to: Have detail knowledge of camera and camera optical elements Apply algorithms for 3D reconstruction of motion Apply algorithm for surface reconstruction Analyze data from laser range finders and create map of area 							
	Course content				L hours		\E ours	
	Introduction to optoelectron	nics			2			
	Machine visiona and comp	uter vision			2			
	Mathematical description c	f cameras and geometry of	of a spac	e	4			
	Lense optical system and o	distorsions			2			
	Color system and photose				2			
	Inudstrial cameras, linear of	-	vstems		2			
	IR cameras and application		<i>jeteme</i>		2			
	Stereovision systems				2			
	3D scanners				2			
Course content	Laser range finders and LI	ΠΔΡ			2			
broken down in	v				2			
detail by weekly class schedule	Night vision cameras and i	maye intensiliers			2	-		
(syllabus)	Future of optoelectronics							
(0)	Introduction to optoelectron	NICS			2			
	List of laboratory or design					hc	_E ours	
	Introduction to Matlab: image						2	
	Introduction to Matlab: vide		ting				2	
	Camera calibration and dist						2	
	Movement reconstruction fr						2	
	Movement reconstruction w	nun stereovision system in	space				2	
	Laser and IR rangefinders 3D scanners and surface re	construction					2 2	
	Lidar and applications in ro						2	
	Cameras in visible and IR s		night opt	ics			2	
			iigin opt				-	

	IR thermal camera a	nd temp	erature c	alculati	on			2		
Format of instruction	 □ lectures □ seminars and workshops □ exercises □ on line in entirety □ partial e-learning □ field work 			nentor						
Student										
responsibilities Screening student	Class attendance	1	Researc	h		Dractical traini	20			
work (name the proportion of ECTS	Experimental work	I	Report	11		Practical traini	•	1,7		
credits for each activity so that the	Essay		Seminal essay	•	1	Laboratory exe	ercises	1		
total number of ECTS credits is	Tests	0,2	Oral exa	ım		(Other)				
equal to the ECTS value of the course)	Written exam	0,1	Project			(Other)				
,	During the semeste or project assignmer									
	The requirement for passing grade is the positive assessment of laboratory exercises and 50 % points on average midterm exam $((M1 + M2)/2)$ or the final exam. Students are allowed to have at least 45% of total points on each midterm exams, as long as the final midterm average is at least 50% of total points. Midterm consists of both theoretical questions and numerical problems. The midterms consist of 4 questions while final exam test consists of 6 questions									
Grading and evaluating student work in class and at	divided into two groups. In determining the final grade (in percentages) each midterm contributes with 30% (or project assignment with 60%), while laboratory exercises contribute with 40%.									
the final exam	Final grade (based on percentages) is formed as follows:									
	Percentage Grade 50% do 62% sufficient (2) 63% do 74% good (3) 75% do 86% very good (4) 87% do 100% excellent (5)									
	In case student does the final exam in v laboratory exercises	which c	ase it co	ontribut						
Required literature		Title				Number of copies in the library	Availab other	-		
(available in the library and via other media)	Hartley, R., Zisserman, A.: 'Multiple view geometry in computer vision' (Cambridge University Press, 2003)									
		 Shapiro, G., Stockman, G.C.: 'Computer vision' (Prentice-Hall, 2001) 								
Optional literature (at the time of submission of study programme proposal)						·				
Quality assurance methods that ensure the acquisition of	 Keeping records Annual analysis Feedback from s 	of cours	e statistic	s in ter	ms of m	nidterm and fina	als exams	6.		

exit competences	- Teacher self-evaluation.
	- Feedback from graduated students (or senior students) on course content relevance.
Other (as the proposer	/
wishes to add)	

NAME OF THE COURSE	PRACTICUM OF AUTOM	ATIC CONTROL							
Code	FELG12	Year of study							
Course teacher	Tamara Grujić, Ph.D., Full Professor	Credits (ECTS)	4						
Associate teachers		Type of instruction		S	AE	LE	DE		
Associate teachers	-	(number of hours)	15	0	0	45	0		
Status of the course	Obligatory	Percentage of application of e-learning	0						
	COURSE	E DESCRIPTION							
	Training students for: - Testing the performance	of the continuous-time cor	ntrol svs	item b	ov mea	asurino	iťs		
Course objectives	time and frequency respon - Design and construction of - Design, construction and - System Identification	se of the controller for automa testing of printed circuit bo	atic con		,				
Course enrolment requirements and entry competences required for the course	- Completed course "Sy	 Analysis of discrete control systems Completed course "System Theory" at the Undergraduate study Completed course 'Linear Control Systems" at the Graduate study 							
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	Students will be able to: - Design the electronic circ - Design and construct a pro- board by using Ki-Cad soft - Test the functionality of P - Implement the laboratory developed PC boards) - Perform the system ident response - Analyse time response ar	rinted circuit board (PCB) a ware CB by measuring the time model of control system w ification based on the mea	and cor e and fre vith PID asured ti	equen contr me a	ve pat cy res oller (l	hs on t ponse pased	on		
	Course content				L		E		
		pontinuous time control	otoma		hours	hc	ours 3		
	Introduction: Designing of Continuous-time control s control	-		ed	1		3		
Course content	Designing of multi-functional electronic circuit (with functions of PID controller and first order system), derivative of transfer functions of the circuit, modeling and simulation of the circuit in Multisim software						3		
Course content broken down in	Design of printed circuit software package Ki-Cad:		cuit in t	he	1		3		
detail by weekly class schedule	Design of printed circuit board of the defined circuit in the software package Ki-Cad: The second part						3		
(syllabus)	Production of PCB by photo-process, drilling holes in the board and soldering of electronic elements						3		
	Testing the function of PCB: Measuring the time and frequency response of the circuit and comparison of the measured responses with the responses simulated in the Simulink								
	First midterm exam	duard DCD c. Dort 4. D.							
	The implementation of pro PCB-s, make the model				1		3		

	control. Measureme system. Selection o the time response and simulated result							
	The implementation PCB-s, make the positioning. Measure the system. Selec improving the time measured and simul	: . 1	3					
	Identification of the measured time response	param	eters of	DC mo		1	3	
	Determination and and sensitivity of transfer function (Vis	analysis discrete	s of trans	sient st	ate, the accuracy		3	
	Determination of the described by discret	e stabilit	y limits o			1	3	
	Modified Z-transfor controllers - discretiz Second midterm exa	mation, zation of	discrete	e state	space, discrete	1	3	
Format of instruction	 ☑ lectures ☑ seminars and workshops ☑ exercises ☑ multimedia 				ents			
Student responsibilities	The presence on lec Performed and posi						eduled.	
Screening student	Class attendance	0.5	Researc	h	Practical t	raining		
work (name the proportion of ECTS	Experimental work		Report		Individual work		0.5	
credits for each activity so that the	Essay		Seminal essay	•	Laboratory	y exercises	2	
total number of ECTS credits is equal to the ECTS	Tests	0.25	Oral exa	al exam Preparation for laboratory exercises and the second secon			0.5	
value of the course)	Written exam	0.25	Project		(Ot	her)		
Grading and evaluating student work in class and at the final exam	Written exam0.25Project(Other)There are two midterms and final exams. The first midterm exam is after 7 weeks of lecturing and the second one is after the next 6 weeks. Each midterm test consists of 5 theoretical questions and numerical problems and final tests consist of theoretical questions and numerical problems. In the final exams students that did not pass the midterm exams take part. The midterm and final exams are carried out as written tests. The requirement for passing grade is the positive assessment of a laboratory exercises and 50 % points on each midterm exam or the final exam Grade (in percentage) is formed according to the formula: Grade(%) = 0.4 LV + 0.3 (M1 + M2) the activities in percentage: 							
	75% do 89,9% 90% do 100%	4 5						
---	--	------------------------------	---	------------------------------	----------------------	--	--	
			Number of copies in the library	Availability via other media				
Required literature (available in the	 Tamara Grujić: " tiskane pločice", 	-	•		e-learning portal			
library and via other media)	 Tamara Grujić: " Identifikacija sus 	laboratorijsku vježbu: SB		e-learning portal				
	 Tamara Grujić: " Diskretni sustavi 		laboratorijske vježbe:		e-learning portal			
Optional literature (at the time of submission of study programme proposal)	Company, 1995.	Marasovi	odern Control Systems ć: Digitalno vođenje on italno_vodjenje		, ,			
Quality assurance methods that ensure the acquisition of exit competences	 Evaluation of results in accordance with the above learning outcomes Feedback from students via surveys Self-evaluation of teachers Institutional and non-institutional evaluations Keeping records of lectures attendance Keeping records of the presence of the laboratory exercises and a review and assessment of submitted reports 							
Other (as the proposer wishes to add)								

NAME OF THE COURSE	PROCESS CONTROL							
Code	FELG21	Year of study	2					
Course teacher	Darko Stipaničev, Ph.D., Full Professor (90%) Ljiljana Šerić, Ph.D., Assistant Professor (10%)	Credits (ECTS)	6	6				
Associate teachers	Darko Stipaničev, Ph.D., Full Professor (100%)	Type of instruction (number of hours)	L 45	S 0	AE 30	LE 0	DE 0	
Status of the course	Obligatory	Percentage of application of e-learning	80					
	COURSE	E DESCRIPTION						
Course objectives	The aim of the course is ba	asic knowledge to process	es mode	elling	and co	ontrol.		
Course enrolment requirements and entry competences required for the course	Completed basic courses of control systems, Identification	ion and Digital control)		l syste	ems, N	Nonline	ear	
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 mathematical model, a Enumerate and describ processes, processes of Build process models b manage to models fluid complex processes (ch Describe the process n measurement and cont Describe and implement scheme of control (ON advanced control sche adaptive and intelligent Describe the principles Alarm, Data Acquisition Describe and perform b and temperature. 	hrough systematic present utomatic control. be the fundamental process of transition, transformatio based on the equation of b dic processes, thermal pro- nemical reactor, distillation, neasurement sensors, con- trol of temperature, flow, p nt different ways of process -OFF, P, PI, PD, PID contri- mes (time - optimal, ratio, t control). of distributed process cor ns). basic procedures for mainter managing complex process	tation, ic ses and palance cesses, oresses, nverters rol, prog cascade ntrol. SC taining f sses.	d their ss. of ma the n and a , leve bl, fror gram (e, fee CADA low, p	mode tter ar nixing actuate I and o m the guidar dforwa (Scan oressu	els: tra nd ene proces orsfor density basic ice) to ard, op i Contu re, lev	nsfer ergy. ss, y. the otimal, rol, rel	
	Course content				or S		λE	
	Introduction. The processe approach to process control. control, open-loop control.	ol. Feedbeck control, feed	lforward		ours 3		ours 0	
Course content broken down in detail by weekly class	The processes and process equipment. Operations and technology operations. The division of technological						0	
schedule (syllabus)	Fluidic systems - basic laws of fluid mechanics, basic fluidic components, modeling fluidic system. Thermal systems - the basic laws of thermodynamics, basic thermal components, modeling of thermal systems. Complex processes and process equipment - mixing, distillation, kemijki reactor912						12	
	Sensors (sensors) and the output and transfer character				9		2	

	flow, level, pressure	and of	her proce	ss varia	ables			
	Actuator (actuators)					ans		
	Basic control schen and P control.						3	4
	Basic control schen	nas: PD	, PI and F	PID con	trol		3	4
	Advanced control schemas: selector control, ratio control,					ontrol,	3	2
	cascade control, fee						Ű	-
	adaptive control, an	The most advanced control schemas: optimal control, adaptive control, and intelligent control.					3	2
	Process industry an	nd auton	natic con	trol.			3	0
Format of instruction	 □ Independent assignm □ Independent assignm □ Independent assignm □ multimedia □ multimedia □ Independent assignm □ multimedia □ (other) 				nents			
Student responsibilities	The presence on le Performed all require					70 % of th	ne times sch	eduled.
Screening student	Class attendance	2,5	Researc			Practical	training	
work (name the proportion of ECTS	Experimental work		Report			Individua	l work	
credits for each activity so that the	Essay		Seminai essay		1,5	Laborato	ry exercises	
total number of ECTS credits is equal to the	Tests		Oral exa				reparation for boratory exercises	
ECTS value of the course)	Written exam	2	Project)ther)	
Grading and evaluating student work in class and at the final exam	The exam consists the semester will b second at 18 weeks exams in June and points through coll condition for taking The exam is complet tasks with auditory student has a total 25% passing the th If a student has less points from the th Students who did r autumn periods. All These rules apply ea and to those studer The final grade is d percentage Rating 50% to 61% is suffi 62% to 74% good (75% to 87% of very 88% 100% Exceller The first colloquium inclusive, and on th	be two f s. A stud I July, s oquia ta the fina rehensive exercis of at lea ecretica s than 2 eoretica s to pass test que etermine cient (2) 3) good (4 ent (5) e will tak	ests. The lent can tudents w ake the w exam is re and in es. The ast 50% of the exam estions st o student enter coll ed as follo 4) e the mai	e first of pass the who have whole s succes cludes condition the ma the ma the ma fithe ma after sudents s who a ege for ows:	colloquin e course ve not o subject o sisfully fin the the con for p exam on terial ar two fina will be i are enro the sec	um in 8 w e by these collected i covered b hished pra pretical pa oositive as when it r ad 25% of e tasks ar again tak al exams o known bef lled this c cond time.	veeks of cla e tests. In the nadequate in by the two the actical lab ex- art of the material sessment in nust have a the deposit nd / or less can pass the fore the exa ourse for the s to the seve	enth week

	in all forms of teaching and attend: lectures at leas do not meet these requirements, the student will no get a signature.	t be able to ta				
Required literature (available in the library and via other media)	Title	Number of copies in the library	Availability via other media			
	D.Stipaničev, Process control, lecturing notes and internal textbook		e-learning portal			
	D.Stipaničev, J.Marasović, Digitalno vođenje on- line, on-line (Web) udžbenik, MZT – Informatički projekt, 2004. <u>http://laris.fesb.hr/digitalno_vodjenje</u> .		e-learning portal			
Optional literature (at the time of submission of study programme proposal)	 Marlin, T.E.: Process Control, McGraw Hill, New Yo Patranabis, D.: Principles of Process Control, McG 		Delchi, 1981.			
Quality assurance methods that ensure the acquisition of exit competences	 Evaluation of results in accordance with the above learning outcomes Feedback from students via surveys Self-evaluation of teachers Institutional and non-institutional evaluations 					
Other (as the proposer wishes to add)						

NAME OF THE COURSE	PROCESS CONTROL LA	BORATORY						
Code	FELG22	Year of study	2.					
Course teacher	Jadranka Marasović, Ph.D., Full Professor	Credits (ECTS)	4	4				
Associate teachers	Ivo Stančić, Ph.D:, Assistant Professor	Type of instruction (number of hours)	L 15	S 0	AE 0	LE 30	DE 0	
Status of the course	Obligatory	Percentage of application of e-learning	0		Ŭ		Ŭ	
	COURSI	E DESCRIPTION	8					
Course objectives	Training students for: Enable students to undersic comprehend how danger of Enable students to undersic the same developed theory chemical processes, in eco- knowledge on the use of com	an be potentially poorly de tand that the system auton y can be used for different pnomy, medicine etc.). Ena	esigned nation i fields (able stu	contr s very techni idents	ol sys difficu cal sy	tems. Ilt task stems,	,	
Course enrolment requirements and entry competences required for the course	Subscribed and coursees of Nonlinear control systems	completed: Linear control s			tem id	entifica	ation,	
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to: 1. describe the importance of automated systems and to identify potentially poorly designed systems, especially where process control is included, 2. recognize that it is necessary to connect the elements of process control physically and that it is important to introduce the compromise of several different subsystems. 3. apply a simulation on a digital computer to support the control theory, taking into account its impact on the results, 4. to decide how and when to apply mathematical approximations for controlled systems design, 5. choose the appropriate methods for systems synthesis depending on the tasks, and introducing different optimization, 						rent j into d	
	Course content	· · ·			L or S hours		∖E ours	
	The impact of "neglected" elements of the mathematical model of the process (nonlinearity) on the quality of the controlled systems. Why we must ignore the elements of the model?						0	
	How to design controllers (linear systems (second orc)-	2		0			
Course content broken down in detail by weekly	The advantages, but also t computer built as a unit for introduced to real-time sys	on	2		0			
class schedule (syllabus)	The nonlinear process models (fluidic, thermal, complex) and						0	
	The sensitivity of the syste parameters change. The ir decision where to instal th	npact of these analyzes to e regulator in control loop	the		2		0	
	Linear static models. Paran algorithm. Preparing for the linear programming. Dual S	e use already created prog			2		0	

	How to simulate the softwares, visually o			ws usir	ng spec	ial	2	0
	List of laboratory or design exercises							LE or DE hours
	Simulation tests of co "neglected" elements controlled systems b	s of the	mathema					2
	Simulation tests of di discretization impact the necessary applic Control) algorithms.	gital col on the (ntrol cysto quality of	system	ns beha	viour). An ex	xample of	2
	nonlinearities on syst	omparison of simulation results (when the impact of neglected onlinearities on systems with digital control quality was tested) with easurements on real systems in the laboratory.						2
	Modeling and simulation of interactive and non-interactive tanks with iquid. Modelling with non-linear models and with the effects of inearization.						2	
	Modeling and simula models and with the				. Modell	ing with nor	n-linear	2
	Simulation verification of controlled process in stable conditions (stability limit). How to decide where to instal the regulator, in direct or in feedback branch?							2
	Linear static models	- linear	programr	ning.				2
	Optimal conditions for							2
	Optimal control with P-controller - minimum integral square error (min ISE).						2	
	Simulation test of mu Simulation test of pro							2
Format of instruction	 seminars and wor exercises on line in entirety partial e-learning field work 			□ mu ⊠ lab □ wo	ltimedia oratory rk with r			
Student responsibilities	Minimum of 70 perce exercises.	ent lectu	ure attend	lance.	Comple	ting all the r	equired la	boratory
Screening student work (name the	Class attendance	1	Researc	h		Practical tr	raining	
proportion of ECTS credits for each	Experimental work		Report			Individual	work	0.5
activity so that the total number of	Essay		Semina essay	r	0.5	Laboratory	/ exercises	s 1
ECTS credits is	Tests	0.5	Oral exa	am		(Other)		
equal to the ECTS value of the course)	Written exam	0.5	Project			(Other)		
Grading and evaluating student work in class and at the final examDuring semester, there will be two mid-term exams – according to schedule. The requirement for the positive grade is the attenda commitment at the laboratory exercises, minimum of 40 percent correct a one mid-term and a final grade is determined with minimum of 50 per correct answers.It is necessary during the semester to resolve seminars to be recognized (score achieved by tests and exams.						ance and answers at crcent total		
	The final grade is de calculated as follows							d, which is

	Grade [%] = 0.25 * M1 + 0.25*M Percentage Grade 50% to 61% sufficient (2) 62% to 74% good (3) 75% to 87% very good (4) 88% to 100% excellent (5) The final exam encompasses the entire course loa students' did not pass at either of mid-term e encompasses the entire course load. The requirer minimum of 50 percent correct answers. The exams schedule.	ad or selected exams. The ment for pass are held accor	correction exam ing the exam is
	Title	Number of copies in the library	Availability via other media
Required literature (available in the library and via other	J. Marasović: "Process Control Laboratory" (in Croatian: Praktikum iz vođenja procesa), FESB, Authorized lectures		e-learning portal
media)	D. Stipaničev, J. Marasović.: "Digital Control" <u>laris.fesb.hr/digitalno vodjenje</u> , on-line udžbenik "Digitalno vođenje", 2004		e-learning portal
	V. Papić "System Theory" (in Croatian: Teorija sustava), FESB, Authorized lectures,		e-learning portal
Optional literature (at the time of submission of study programme proposal)	 B. Novaković: Metode vođenja tehničkih sistema, Š Patranabis, D.: Principles of Process Control, McGr Wolowich, W.A.: Linear Multivariable Systems, Spri Heidelberg- Berlin, 1984. 	aw-Hill Pub. N	lew Delhi 1981.
Quality assurance methods that ensure the acquisition of exit competences	 Keeping records on class attendance Annual analysis of exam results Student survey on teaching performance Teacher self-evaluation Feedback information from graduates regarding compared to the survey on the survey on the survey on the survey on teaching performance 	course content	relevancy
Other (as the proposer wishes to add)			

NAME OF THE COURSE	PRODUCTION MANAGE	MENT						
Code	FETL23	Year of study	2.					
Course teacher	Ivica Veža, Ph.D., Full Professor	Credits (ECTS)	5					
Associate teachers	Marko Mladineo, Ph.D.	Type of instruction (number of hours)	L 30	S 0	AE 30	LE 0	DE 0	
Status of the course	Elective	Percentage of application of e-learning	0					
	COURSI	E DESCRIPTION						
Course objectives	 Training students to: production planning ar making/drafting technol be able to simulate the 	ological oriented investmer	nt proje	cts				
Course enrolment requirements and entry competences required for the course	Competences and skills learning outcomes of undergraduate study in industrial engineering, naval architecture or mechanical engineering.							
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to: Analyze the business model of supply chain management. Analyze the concept of production planning and control. Evaluate management models of production data. Model and simulate the operation of a flexible/intelligent manufacturing system. Recommend software solutions for integrated planning and production management. Apply simulation programs on production problems. Apply acquired knowledge and skills from previous courses on solving the specific task. 					tem.		
	8. Prepare technology orio						L	
	Production function. Produ strategies.	ction management. Produ	ction m	nanage	ement		urs 2	
	Product designs. New proc	fuct developing process					2	
	Supply chain (Supply chair						2	
	Production planning and co	ž /					2	
0	Materials planning and inve						2	
Course content broken down in detail by weekly	Concepts for production pl techniques planning, meth	anning and control: netwo					2	
class schedule	Procedure Just in time – J						2	
(syllabus)	Method for manufacturing						2	
	Optimized production tech numbers. Improvements.	lethods and improvement					2	
	Production systems simula						2	
	Globalization. Social respo			-		2	2	
	Concept of planning busine technology and innovation	in technology.					2	
	Preparing Technology orie and demonstration TIP. TI						2	

							AE	
		-					hours	
	Single production. Pr						2	
	Introduction to the Ne	etwork p	planning tec	hniqu	le.		2	
	Time analysis.						2	
	CPM method.						2	
	PERT method.						2	
	PRECEDENCE meth	nod.					2	
	Cost analysis.	•						
	Resource analysis.						2	
	Introduction to invent		hagement.				2	
	EOQ and ROP methods						2	
	Probability methods a JIT method.	and sale	ety supplies	.			2	
	Introduction to MRP,		EDD				2	
			IERF.				Z	
Format of instruction	 ☑ lectures ☑ seminars and workshops ☑ exercises ☑ on line in entirety ☑ partial e-learning ☑ field work ☑ laboratory ☑ work with mentor ☑ (other) 							
Student	Presence on lecture	s and e	xercises at l	least	70% of	the teaching hours. S	Settled ALI	
responsibilities	provided laboratory							
Screening student	Class attendance	1,0	Research			Practical training		
work (name the proportion of ECTS	Experimental work		Report			Independent work	1,5	
credits for each activity so that the	Essay		Seminar essay			Laboratory exercises	s 0,5	
total number of ECTS credits is equal to the ECTS	Tests	0	Oral exam	I		Preparation for laboratory exercises		
value of the course)	Written exam		Project		2,0	(Other)		
Grading and evaluating student work in class and at the final exam	exam after 7 weeks students take the tes midterm is a written To have a passing g On the other hand, s	of class at with p exam the rade students tudents to first w for labour pints on ercentag	es, the seco parts of matt nat students udents have have a coll written colloc ratory exerc mid-term ex	ond a ter the s write to ga loquiu quium cises xams ed acc	fter the ey did n for 45 ain at le um on th at the cording t		al exam . Every uestions. term. ork	

	Title	Number of copies in the library	Availability via other media			
Required literature	 Dulčić, Ž., Pavić, I., Rovan, M., Veža, I., "Proizvodni management", Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture – Faculty of Economics, Split, 1996. 	5				
(available in the library and via other media)	 Schroeder, R. G., "Upravljanje proizvodnjom", MATE, Zagreb, 1999. 	5				
incula)	 Veža, I., Bilić, B., Gjeldum, N., Mladineo, M., "Upravljanje projektima", Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture, Split, 2011. 		e-learning			
Optional literature (at the time of submission of study programme proposal)	 Slack, N., Chambers, S., Johnston, R., "Operation Hall, Harlow, 2004. Wild, R., "Operations Manage 					
Quality assurance methods that ensure the acquisition of exit competences	 Tracking the presence on classes Academic year analyses-grades and exams success Student survey contain teacher evaluation Teacher self-evaluation Graduated student feedback about the relevance of syllabus content 					
Other (as the proposer wishes to add)						

NAME OF THE COURSE	PROFESSIONAL TRAINING								
Code	FEXX06	Year of s	study	2					
Course teacher	Head of the professional training from the Faculty			5	5				
Associate teachers	Head of the professional training from the private institution	Type of I	nstruction of hours)	L	S	AE	LE	DE	
Status of the course	Elective	Percenta application	ige of on of e-learning						
	COUR	SE DESCR	PTION						
Course objectives	 Training students for: consolidating theoretical knowledge and practical skills in solving highly complex engineering problems acquaintance with the organization, work and business of the receiving institution, solving practical problems, inclusion in the labour market, 								
Course enrolment requirements and entry competences required for the course	- writing technical reports Acquired 120 ECTS credits								
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to: consolidate theoretical knowledge and practical skills in solving problems use literature, databases and other sources of information select appropriate methods and procedures for solving practical problems apply technical knowledge and skills to effectively solve engineering problems prepare a written report on the work results 								
Course content broken down in detail by weekly class schedule (syllabus)	Professional training is the receiving institution in ac the head of the profession professional training from	ne independ cordance w mal training	ent work of the s ith the plan and from the receivi	prograr	nme a	greed	betwe		
Format of instruction	 □ lectures □ seminars and workshops □ exercises □ on line in entirety □ partial e-learning □ field work □ aboratory □ work with m □ (otherwork) 				nentor				
Student responsibilities	Independent work								
Screening student work (name the	Class attendance	Resear	ch	Practic	al trair	ning		4	
proportion of ECTS credits for each	Experimental work	Report		Indepe	ndent	work			
activity so that the total number of	Essay	Semina essay		Report		-		1	
ECTS credits is equal to the ECTS	Tests	Oral ex	am		(Other				
value of the course)	Written exam	Project			(Other	.)			

Grading and evaluating student work in class and at the final exam	Professional training is not evaluated. Student professional training in accordance with the Regulation to write a Professional training report. Professional the head of professional training from the receiving professional training from the Faculty.	on on professi training repor	onal training and t is validated by
Required literature (available in the	Title	Number of copies in the library	Availability via other media
library and via other media)			
Optional literature (at the time of submission of study programme proposal)			
Quality assurance methods that ensure the acquisition of exit competences	 Questionnaire on professional training Self-evaluation of the head of professional training Student survey of the whole study programme]	
Other (as the proposer wishes to add)			

Associate teachers Inform petitry PLD., Assistant Professor Type of matrix dusts Type of matrix dusts Status of the course Obligatory Percentage of application of e-learning 30 30 Course objectives Training students for: - Understanding operating principles of programmable logic controllers. - Programming PLC using ladder programming. - Design and implementation of simple control tasks using PLC. Course enrolment requirements and entry competences required for the course Students also enrolled in courses Nonlinear regulation systems and Digital control. Learning outcomes expected at the level outcomes) Students will be able to: - Explain the operating principle of programmable logic controllers. - Describe the types of input and output devices. - Interpret the functionality of ladder-logic programs. - Describe the types of other course of the course for system using PLC for specified process parameters. - Describe the PLC using adequate software. - Describe the functionality of ladder-logic programs. - Describe the functionality of ladder-logic programs. - Describe the functionality of ladder-logic controllers. L hours Introduction. History of PLCs. Definition, basic operating principles and types of PLC. 2 Number systems and the fundamentals of digital logic. PLC programming languages by IEC 61131-3 standard. Ladder diagrams. Memory organization. Bit-level logic instructions. 2 Programming counters. Programming counters. Programming counters. Programming counters. 2 Programming timeructions. Programming tim	NAME OF THE COURSE	PROGRAMMABLE LOGIC CONTROLLERS								
Course teacher Mojmil Cecic, Ph.D., Full Professor Credits (ECTS) 5 Associate teachers Tihomir Betti, Ph.D., Assistant Professor Type of instruction (number of hours) L S AE LE DE Status of the course Obligatory Percentage of application of e-learning 30 L S AE LE DE Course objectives Training students for: - Understanding operating principles of programmable logic controllers. - Reading relay diagrams and writing equivalent tadder-logic controllers. - Programming PLC using ladder programmable logic controllers. - Design and implementation of simple control tasks using PLC. Course enrolment requirements and entry systems and Digital control. Linear regulation systems. Students also enrolled in courses Nonlinear regulation systems and Digital control. Learning outcomes Students will be able to: - Explain the operating principle of programmable logic controllers. - Design the control system using PLC for specified process parameters. - Design the control system using PLC for specified process relaters. 2 Number systems and the fundamentals of digital logic. - PLC hardware components. - PLC hardware components. - PLC hardware components. - PLC hardware components. - PLC hardware soft in PLC controlled systems: input devices (relays, switches, starters, contactors, sensors) and output devices. - PLC programming languages by IEC 61131-3 standard. Ladder diagrams. Memory organization. Bit-level logic instructions. -	Code	FELG13	Year of study	1						
Associate teachers Inform feeture PRIDE, Assistant Professor Type of manual course Top of manual course Status of the course Obligatory Percentage of application of e-learning 30 30 Course objectives Training students for: - Understanding operating principles of programmable logic controllers. - Programming PLC using ladder programming. - Design and implementation of simple control tasks using PLC. Course enrolment requirements and entry for the course Students also enrolled in courses Nonlinear regulation systems and Digital control. Learning outcomes expected at the level outcomes) Students will be able to: - Explain the operating principle of programmable logic controllers. - Describe the types of input and output devices. - Interpret the functionality of ladder-logic programs. - Describe the types of other course of the course of the course of the course of the course of the course of the course of the course of PLC. L hours - Describe the types of public doder logic controllers. - Describe the types of PLC ontrolled systems input devices. - Describe the types of PLC. L hours - Describe the types of end to the course of t	Course teacher			5						
Status of the course Obligatory application of e-learning COURSE DESCRIPTION Course objectives Training students for: - Understanding operating principles of programmable logic control. - Programming PLC using ladder programming. - Design and implementation of simple control tasks using PLC. Course enrolment requirements and entry competences required or the course Learning outcomes expected at the level of the course (4 to 10 learning outcomes) Students will be able to: - Descipte the types of input and output devices. - Interpret the functionality of ladder-logic programs. - Descipte the programming PLC or specified process parameters. - Descipte the control system using PLC for specified process parameters. - Descipte the functionality of PLCs. Definition, basic operating principles and throduction. History of PLCs. Definition, basic operating principles and throduction. History of PLCs. Definition, basic operating principles and throduction. History of planguages by IEC 61131-3 standard. Ladder diagrams. Memory organization. Brogramming funguages by IEC 61131-3 standard. Ladder diagrams. Memory organization. Programming counters. Programming counters. Programming timers. Programming timers	Associate teachers				S	AE		DE		
COURSE DESCRIPTION Training students for: - Understanding operating principles of programmable logic controllers. - Reading relay diagrams and writing equivalent ladder-logic control. - Programming PLC using ladder programming. - Design and implementation of simple control tasks using PLC. - Course enrolment requirements and entry competences required for the course - Explain the operating principle of programmable logic controllers. Learning outcomes - Explain the operating principle of programmable logic controllers. 0 learning outcomes) - Explain the operating principle of programmable logic controllers. - Interpret the functionality of ladder-logic programs. - - Program the PLC using adequate software. - - Design the control system using PLC for specified process parameters. - Course content Introduction, History of PLCs. Definition, basic operating principles and types of PLC. 2 PLC hardware components. 2 - Number systems and the fundamentals of digital logic. 2 Field devices used in PLC controlled systems: input devices (relays, switches, starters, contactors, sensors) and o	Status of the course	Obligatory				<u> </u>				
Course objectives - Understanding operating principles of programmable logic controllers. - Reading relay diagrams and writing equivalent ladder-logic control. - Programming PLC using ladder programming. - Design and implementation of simple control tasks using PLC. Course enrolment requirements and entry competences required for the course of the course (4 to 10 learning outcomes) Linear regulation systems. Students also enrolled in courses Nonlinear regulation systems and Digital control. Learning outcomes expected at the level of the course (4 to 10 learning outcomes) Students will be able to: - Explain the operating principle of programmable logic controllers. - Design the control system using PLC for specified process parameters. - Design the control system using PLC for specified process parameters. - Design the control system sand the fundamentals of digital logic. PLC brardware components. PLC programming languages by IEC 61131-3 standard. Ladder diagrams. Memory organization. Bit-level logic instructions. Programming timers. Programming timers. Programming torutoris. Program control instructions. 20 Data manipulation instructions. 20 That instructions. 20 The anality of laboratory equipment. List of laboratory or design exercises List of laboratory or design exercises List of laboratory end programming software. Bit-level Introduction to laboratory equipment. Introduction to laboratory equipment. Introduction to laboratory equipment. Introduction to laboratory equipment. Introduction to laboratory equipment.		COURSE	EDESCRIPTION							
Course enrolment requirements and entry competences required Linear regulation systems. Students also enrolled in courses Nonlinear regulation systems and Digital control. Learning outcomes expected at the level of the course (4 to 10 learning outcomes) Students will be able to: - Explain the operating principle of programmable logic controllers. - Describe the types of input and output devices. - Interpret the functionality of ladder-logic programs. - Program the PLC using adequate software. - Design the control system using PLC for specified process parameters. Course content Course content Introduction. History of PLCs. Definition, basic operating principles and types of PLC. 2 PLC hardware components. 2 Number systems and the fundamentals of digital logic. 2 Field devices used in PLC controlled systems: input devices (relays, switches, starters, contactors, sensors) and output devices. 2 PLC programming languages by IEC 61131-3 standard. Ladder diagrams. Memory organization. Bit-level logic instructions. 2 Program control instructions. 2 Program control instructions. 2 Program control instructions. 2 Programming timers. 2 Programming timers. 2 Programming timers. 2 Programming counters. 2 Data communication in PLC systems.	Course objectives	 Understanding operating Reading relay diagram Programming PLC using 	is and writing equivalent lang ladder programming.	dder-lo	ogic co	ontrol.	S.			
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	requirements and entry competences required	Linear regulation systems.	near regulation systems. Students also enrolled in courses Nonlinear regulation							
Introduction. History of PLCs. Definition, basic operating principles and types of PLC.2PLC hardware components.2Number systems and the fundamentals of digital logic.2Field devices used in PLC controlled systems: input devices (relays, switches, starters, contactors, sensors) and output devices.2PLC programming languages by IEC 61131-3 standard. Ladder diagrams. Memory organization. Bit-level logic instructions.2Programming timers.2Programming counters.2Programming counters.2Program control instructions.2Data manipulation instructions.2Sequencer and shift register instructions.2ScADA.2List of laboratory or design exercisesLE hourIntroduction to control and PLC programming software. Bit-level instructions, seal-in circuits.4	expected at the level of the course (4 to 10 learning	Explain the operating principle of programmable logic controllers. Describe the types of input and output devices. Interpret the functionality of ladder-logic programs. Program the PLC using adequate software.								
Timers. Data compare instructions. Traffic lights control using sequencer.4Counters. Realization of conveyor model.4Temperature regulation.4Working with analog values.4PID control.4	broken down in detail by weekly class schedule	Introduction. History of PLC types of PLC. PLC hardware components Number systems and the fu Field devices used in PLC switches, starters, contacto PLC programming languag diagrams. Memory organiz Programming timers. Programming counters. Program control instruction Data manipulation instruction Data manipulation instruction Data communication in PLC SCADA. List of laboratory or design Introduction to laboratory ed Introduction to control and F instructions, seal-in circuits. Timers. Data compare instr Counters. Realization of co Temperature regulation. Working with analog values	Introduction. History of PLCs. Definition, basic operating principles and types of PLC. PLC hardware components. Number systems and the fundamentals of digital logic. Field devices used in PLC controlled systems: input devices (relays, switches, starters, contactors, sensors) and output devices. PLC programming languages by IEC 61131-3 standard. Ladder diagrams. Memory organization. Bit-level logic instructions. Programming timers. Programming counters. Program control instructions. Data manipulation instructions. Math instructions. Sequencer and shift register instructions. Sequencer and shift register instructions. SCADA. List of laboratory or design exercises ntroduction to laboratory equipment. ntroduction to control and PLC programming software. Bit-level nstructions, seal-in circuits. Fimers. Data compare instructions. Traffic lights control using sequencer. Counters. Realization of conveyor model.							

Format of instruction	$\Box \text{ exercises} \qquad \Box \text{ on line in entirety} \qquad \Box Interval of the second sec$			⊠ mul ⊠ labo □ wor □	lependent assignments Iltimedia poratory rk with mentor (other)				
Student responsibilities	At least 70% of lectu presentation of two			Comple	eted all la	aboratory assig	nments a	ind the	
Screening student work (name the	Class attendance	1	Researc	h		Practical traini	ng		
proportion of ECTS	Experimental work		Report			Individual work	K	2	
credits for each activity so that the total number of ECTS credits is equal to the ECTS value of the course)	Essay		essay		Laboratory exe	ercises	1		
	Tests	0.05	Oral exa	ım		Preparation fo laboratory exe		0.3	
	Written exam	0.05	Project		0.6	(Other)			
Grading and evaluating student work in class and at the final exam	the following 6 weel midterm exams take last for 90 minutes laboratory work, as using following form Grade(%)=0 where:	 M1, M2 – grade from midterm exams given in percentage, 							
	Title				Number of copies in the library	Availabi other r	-		
	T. Betti: Programabi	lni logičl	ki regulat	ori, pree	davanja		E-learning portal		
Required literature (available in the library and via other	(prezentacije) F. D. Petruzella: Programmable logic controllers, 5th edition, McGraw-Hill, 2016.						ροι	lai	
media)	SIMATIC S7-1200 P Siemens, 2015.	rogramı	mable co	ntroller,					
	SIMATIC STEP 7 Ba				2014.				
	K. Kamel, E. Kamel: Programmable Logic Controllers – Industrial Control, McGraw-Hill, 2014.								
Optional literature (at the time of submission of study programme	 W. Bolton: Programmable logic controllers, 6th edition, Elsevier, 2015. E.A. Parr, Programmable Controllers – An engineer's guide, Newnes, 2003. G.K. McMillan, D.M. Considine: Process/industrial instruments and controls handbook, McGraw-Hill, 1999. 								
proposal)	 G.K. McMillan, I handbook, McG 	D.M. Cor raw-Hill,	nsidine: F 1999.	llers – A Process	/industri	al instruments			
proposal) Quality assurance methods that ensure the acquisition of exit competences	- G.K. McMillan, I	D.M. Con raw-Hill, er of stu sults in a students valuatior	nsidine: F 1999. Idents att accordan s via stud n	llers – A Process ending ce with ent surv	/industri the clas expecte /eys	al instruments	and contr		

NAME OF THE COURSE	PROGRAMMING AGENTS							
Code	FELG19	Year of study	1					
Course teacher	Maja Štula, Ph.D., Full Professor	Credits (ECTS)	5					
		Type of instruction	L	S	AE	LE	DE	
Associate teachers		(number of hours)	30			30		
Status of the course	Elective	Percentage of application of e-learning	20%					
	COURS	E DESCRIPTION						
Course objectives	on multi-agent systems - Acquiring deep knowle development - Acquiring basic knowle	dge on programming frame dge necessary for design,	eworks	for m	ulti-ag	ent sys	stems	
Course enrolment requirements and entry competences required for the course	of multi-agent systems							
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Implement multi-agent programming paradigm Use JADE and NetLogo frameworks Solve complex user requirements to multi-agent systems Explain pros of using multi-agent approach in developing applications 							
	Course content L hours							
	Agents. Examples of agents, intelligent agents, agents and 2 objects.						0	
	Using JADE framework				8		0	
	Using agent-based models (ABM) 2						0	
	Agent types and architectu				2		0	
	Knowledge presentation a languages.	nd formalization, ontologie	s, conte	ent	2		0	
	Using NetLogo framework				4		0	
Course content broken down in detail by weekly	Agent communication language. Communication definition and models. Interaction protocols.						0	
class schedule (syllabus)	Multi-agent systems applic and interaction	1	2		0			
(Syllabus)	List of laboratory or design exercises						nours	
	Simple JADE application						4	
	Developing ABM in JADE						4	
	Implementing different agent types						4	
	Building own ontology						4	
	Simple NetLogo application						2	
							2	
	Design multi-agent system Define multi-agent system	organisation and interactio	'n				2 2	

Format of instruction	 □ seminars and workshops □ multimedia □ multimedia □ laboratory □ work with r □ field work □ (oth 			nentor er)				
Student responsibilities		e presence on lectures in the amount of at least 70 % of the times schedu formed and uploaded on e-learning portal all required laboratory exercise ne works.						
Screening student work (name the	Class attendance	2	Researc	h		Practical traini	ng	1
proportion of ECTS credits for each	Experimental work		Report			(Other)		
activity so that the total number of	Essay		Seminal essay	•	1	(Other)		
ECTS credits is	Tests	0,5	Oral exam 0,5		(Other)			
equal to the ECTS value of the course)	Written exam		Project			(Other)		
Grading and evaluating student work in class and at the final exam	exam is after 7 wee the final exams stu requirement for pas exam. Grade (in per the activities in perc	 here are two midterms and final exams duration of 90 minutes. The first midter for a safet of lecturing and the second one is after the next 6 weeks be final exams students that did not pass the midterm exams take part. equirement for passing grade is 50 % points on each midterm exam or the kam. Grade (in percentage) is formed according to the formula: Grade(%) = (M1 + M2)/2 e activities in percentage: M1, M2 – test results. 						
		Title	9			Number of copies in the library	Availabi other r	-
Required literature (available in the library and via other media)	(available in the library and via other Theory and Practice, Knowledge Engineering				1			
Optional literature (at the time of submission of study programme proposal)								
Quality assurance methods that ensure the acquisition of exit competences	- Students' su - Students att - Annual stati	tendanc stic on p	e track bassed ex	am		-11.994		
Other (as the proposer wishes to add)	Feedback from pote	ntial em	ployers c	n stude	ents em	pioyability		

NAME OF THE COURSE	PROJECT MANAGEMENT								
Code	FETG01	Year of study	2.						
Course teacher	Ivica Veža, Ph.D., Full Professor	Credits (ECTS)	5						
Associate teachers	Marko Mladineo, Ph.D.	Type of instruction (number of hours)	L 30	S 0	AE 30	LE	DE		
Status of the course	Elective	Percentage of application of e-learning	0)					
	COURS	E DESCRIPTION							
Course objectives	Training students for: - planning and mana - calculating profitab	aging projects vility of the project and retu	ırn of in	vestm	ent (R	OI)			
Course enrolment requirements and entry competences required for the course	None								
	Students will be able to:								
		uirements (VOC)							
	 analyze customer requirements (VOC) formulate the main goals of the project and rank them 								
Learning outcomes expected at the level	•	ect activities and the struct		listribu	ition o	f work	_		
of the course (4 to	 plan the time (to deterior) 	,							
10 learning		ne bottlenecks and balanc	e activit	ies)					
outcomes)	- plan costs and risks		o dolivi						
	•	dge and skills from conten	ts of co	mplete	ed cou	rse to	solve		
	- combine and apply ad	opted knowledge and skills	s in teai	mworł	K				
	Course content		L hours		\E ours				
	Introduction and basic concepts						2		
	The concept and definition		2		2				
	Projects - vision, strategy, shipbuilding industries)	k	2		2				
	The strategy and project management. Multi-project management.						2		
	Basics of organization. The				2	_	2		
Course content broken down in	The phases of the project (initiation of project, project selection, project planning, project management and end of project)						2		
detail by weekly	Methods for project planni	าต.			2		2		
class schedule (syllabus)	Quality management (plan control)		quality		2		2		
	Control) Cost management. Continuous Improvement - Kaizen.						2		
	Risk management.				2		2		
	Psychological and social c Project manager.	omponent of project mana	igemen	t.	2		2		
	Teamwork.				2		2		
	Communication and motiva stimulating creativity.		2		2				

Format of instruction	 ☑ seminars and workshops ☑ exercises ☑ on line in entirety ☑ partial e-learning ☑ work with 			timedia pratory	y mentor			
Student responsibilities	The presence on lect Performed all require				t least 7	0 % of the time	es schedu	lled.
Screening student work (name the	Class attendance	2,0	Researc	h		Practical traini	ng	
proportion of ECTS	Experimental work		Report			Individual work	<	1,0
credits for each activity so that the	Essay		Semina essay			laboratory exe	rcises	0,5
total number of ECTS credits is equal to the ECTS	Tests	0	Oral exa	am		Preparation fo laboratory exe		
value of the course)	Written exam		Project		1,5	(Other)		
Grading and evaluating student work in class and at the final exam	During the semester the stages of project managem parallel they attend lectures and laboratory exercises is project work team and the minimum number of number is three. During the course they determine to main targets. Students develop the main activities distribution of work (WBS). They plan the time for e critical path. Students also plan capacities and dete capacities. At the end they determine the costs, cald and analyze risks. On test students present their w M). On the other side students have one test in the techniques (LV) at the end of the semester. • LV - grade of laboratory exercises, • M - points achieved from the project. The final grade (in percentage) is formed according to Grade (%) = 0,30 LV + 0,70 M				s to develop the of students is the content of of project and each activity ar ermine bottlene culate project p work which is e the field of N	eir project two, ma their proj the struct ad determ cks and l profitabilit evaluated	t. There aximum ect and cture of nine the balance y (ROI) (grade	
		Title	9			Number of copies in the library	Availabi other r	
Required literature (available in the	 Veža, I., Bilić, B. "Upravljanje projustrojarstva i brodu 	ektima", ogradnj	Fakultet e, Split, 2	elektro 011.			e-lear por	-
library and via other media)	 Majstorović, V. P Sveučilište u Mos 	-				5		
		Sveučilište u Mostaru, Mostar, 2010. Omazić, M.A. Projektni menadžment, Sinergija, Zagreb, 2005.			5			

Optional literature (at the time of submission of study programme proposal)	 "A Guide to the Project Management Body of Knowledge, PMBOK Guide", Project Management Institute, Newtown Square, 2004. Wysocki, R. K., McGary, R., "Effective Project Management: Traditional, Adaptive, Extreme", John Wiley & Sons, 2003.
Quality assurance methods that ensure the acquisition of exit competences	 Evidence about class attendance The annual analysis of performance of the examinations Student survey in order to evaluate teachers Self-evaluation of teachers Feedback from students who have already graduated about the relevance of the course content
Other (as the proposer wishes to add)	

NAME OF THE COURSE	SOLAR CELLS								
Code	FELH35	Year of study	1						
Course teacher	Tihomir Betti, Ph.D., Assistant Professor Ivan Marasović, Ph.D., Assistant Professor	Credits (ECTS)	5						
Associate teachers		Type of instruction (number of hours)	L S 30	AE LE 30	DE				
Status of the course	Elective	Percentage of application of e-learning							
	COURSI	COURSE DESCRIPTION							
Course objectives	 Modeling solar cells us Calculating solar radia Understanding differer Designing simple stand 	nental operating principles sing equivalent electrical ci tion on the plane of arbitra at PV technologies and cor d-alone and grid-connecte sity production of a photovy	rcuits. ry tilt and orie nparison betw d PV systems	een them.					
Course enrolment requirements and entry competences required for the course	None.	Calculating the electricity production of a photovoltaic system.							
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to: Calculate the components of solar radiation on the plane of arbitrary tilt and orientation. Explain the physical operating principles of a solar cell. Compare different solar cell technologies. Design simple grid-connected and stand-alone photovoltaic system. Calculate the electricity production of a photovoltaic system. 								
	Course content Introduction. Solar radiation: irradiance and irradiation. Basic solar								
	geometry parameters. Solar radiation components. Measurement of solar radiation. Calculating								
	the beam, diffuse and reflected solar radiation. Physical principles of solar cell operation. Current-voltage characteristic and basic solar cell parameters. Series and shunt resistance.								
	Solar cell models. Dependence of solar cell parameters on irradiance and temperature.								
	Amorphous silicon solar ce	ells.			2				
Course content	Crystalline silicon solar cells.								
broken down in detail by weekly class schedule	High-efficiency III-V multijunction solar cells. Other semiconductor materials for solar cells.								
(syllabus)	Organic solar cells.								
(-)	Third generation solar cells based solar cells.				2				
	Photovoltaic systems: stand-alone and grid-connected. Photovoltaic system components: inverters, charge regulators, batteries, mounting structures, cables.								
	Design of grid-connected and stand-alone photovoltaic system. Shading and mismatch losses. Hot spot heating.								
	and mismatch losses. Hot	spot heating.							
	and mismatch losses. Hot Estimation of electricity pro		system.		2				

photovoltaic system. Photovoltaics in the smart grid.									
	List of laboratory or				C		LE hours		
	Solar radiation. Meas						3		
	Calculating global ho						3		
	Estimation of solar ra					It and orientation.	6		
	Shade measurement						<u>3</u> 6		
		esign of grid-connected photovoltaic system.							
		mating electricity production of a photovoltaic system.							
		Sting photovoltaic system on the roof of the faculty building.3sting photovoltaic modules and systems. Photovoltaic system in the art energy systems (smart home and smart grid).3							
	01								
		s (smar	t nome a	na sma	rt gria).				
	⊠ lectures			🖂 inde	epender	nt assignments			
	□ seminars and wo	rksnops		🛛 mul	timedia	-			
Format of instruction	⊠ exercises			⊠ labo	oratory				
	□ on line in entirety				k with n	nentor			
	□ partial e-learning				(othe				
	☑ field work					•			
Student				Comple	eted all I	aboratory assignment	ts and the		
responsibilities	presentation of two	projects.	1						
Screening student work (name the	Class attendance	1	Researc	ch		Practical training			
proportion of ECTS credits for each	Experimental work		Report	Individual work			2		
activity so that the total number of	Essay		Semina essay	r	Laboratory exercise		5 1		
ECTS credits is	Tests	0.15	Oral exa	am (Other)					
equal to the ECTS value of the course)	Written exam	0.1	Project		0.75	(Other)			
Grading and evaluating student work in class and at the final exam	Students work in groups of two on two projects: the first project involves calculation of global solar radiation from sunshine duration, the evaluation of the model used and calculation of solar energy on slope of arbitrary tilt and orientation. The first project is presented during the first midterm exam (after 7 weeks of classes). The second project is design of a photovoltaic system and students must complete it and present the results during the second midterm exam (after the following 6 weeks of classes). Apart from presentation of student projects, there will be two midterm quizzes. The requirement for passing the course is to score at least 40% at each quiz, complete all laboratory work and successfully present the projects The final grade (in percentage) is formed using following formula: Grade(%)=0.3(M1+M2)+0.4P, where: • M1, M2 – grade from midterm exams given in percentage, • P – grade from projects given in percentage. Students not passing the midterm exams take part in the final exams. For passing the final exam, students must score at least 50% as well as have a positive assesment of the laboratory exercises. The grade on final exams is determined by the formula: Grade(%) = 0.65F+0.35P, where:								
	 P – grade free 	om proje	ects give	n in per	centage				

	Title	Number of copies in the library	Availability via other media					
Required literature (available in the library and via other	 T. Betti, I. Marasović: Sunčane ćelije – autorizirana predavanja (prezentacije), FESB 		E-learning portal					
media)	 P. Kulišić, J. Vuletin, I. Zulim: Sunčane ćelije, Školska knjiga, Zagreb, 1994. 							
	 Planning and Installing Photovoltaic Systems, 2nd edition, Earthscan, 2010. 							
Optional literature (at the time of submission of study programme proposal)	 and Applications, Elsevier, 2003. M.A. Green: Solar cells: operating principles, tec applications, Prentice-Hall, 1982. A. Luque, S. Hegedus: Handbook of Photovoltaic Wiley, 2003. 	 M.A. Green: Solar cells: operating principles, technology, and system applications, Prentice-Hall, 1982. A. Luque, S. Hegedus: Handbook of Photovoltaic Science and Engineering, Wiley, 2003. S.M. Sze, K.K. Ng: Physics of Semiconductor Devices, Wiley, 2006. 						
Quality assurance methods that ensure the acquisition of exit competences	 Record of number of students attending the classes Evaluation of results in accordance with expected learning outcomes Feedback from students via student surveys Teachers self-evaluation Institutional and non-institutional evaluations 							
Other (as the proposer wishes to add)								

NAME OF THE COURSE	SYSTEM IDENTIFICATION								
Code	FELG03	Year of study	1.						
Course teacher	Jadranka Marasović, Ph.D., Full Professor	Credits (ECTS)	5						
Associate teachers	Tea Marasović, Ph.D., Assistant Professor	Type of instruction (number of hours)	L 30	S 0	AE 0	LE 30	DE 0		
Status of the course	Obligatory Percentage of application of e-learning 0								
	COURSE	DESCRIPTION	-						
Course objectives	Training students for: To enable students through the system parameter iden understand that there are r parameters identification is appropriate mathematical r the different methods, in pa that take place outside the during working process (or of the measuring equipment	tification for engineering p to universal identification p necessary to implement t models. To enable studen articular to explain the diffe working process (off-line) n-line). To provide an unde	ractice procedu heoreti ts acqu erences and the	and re ures an cal kn uire kn betwo ose that	esearc nd for owled owled een th at take	h. To systen ge and ge abo e meth e place	n I put nods		
Course enrolment requirements and entry competences required for the course		of the measuring equipment on the quality of results. The basis of knowledge of Mathematics.							
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to: 1. describe the importance of system parameters identification for automated systems and to recognize the danger of potentially bad selected procedures, 2. decide when is need to apply the procedures for the parameters identification during the working process (off-line), and when to apply the procedures simultaneously with the process work (on-line), 3. recognize that the parameters identification is always an approximation procedure and this should be taken into account in applications, 4. apply the simulation on a digital computer to support the theory, taking into account its impact on the results, 5. decide how and when to apply one or more possible methods, depending on the tasks and the available equipment, 6. recognize the exceptional importance of measuring equipment on the quality of the results, 								
	Course content				L		١E		
	Introduction: Systems appr the analysis and understan problems with the synthesi The model is an approxima	۱	hours 2		ours 0				
Course content broken down in detail by weekly class schedule (syllabus)	Quantitative models, difference of the systems characteristics: deterministic, stochastic, static, dynamic, continuous, discrete, linear and nonlinear mathematical models. The selection of input and output variables and their impact on the complexity of the model.20						0		
	The meaning and the need for system oarameters identification. Introduction to different methods of parameters identification of deterministic systems						0		
	The impact of disturbances results. The impact of the u		ation		2		0		

		aritian a			dentification	<u> </u>	
	unexpected) nonline results.	arities c	on the qua	ality of 10	dentification		
	Parameters Identific response is recogni system with one input	zed as t ut and o	the respo	nse of t t.	he first order	2	0
	Parameters Identific response is recogni system with one input	zed as t	the respo	nse of t		2	0
	Parameters Identific control loop with one	ation of	the contr	olled sy	stem closed in	2	0
	Application of param system in the process system.				5	2	0
	Parameters identification systems.	ation of	the contro	olled m	ultivariable	2	0
	Parameters identification discrete model was			ere the	equivalent	2	0
	Parameters identification process where the linear regression 2					2	0
	the tasks of adaptive	The need for identification systems in tasks of forecasting and the tasks of adaptive and intelligent control.					
	to the quality of the i laboratory work. para	equired measuring equipment and the impact of their quality the quality of the identified parameters. Preparation for boratory work. parameter identification of the actual system sing the existing measuring equipment.					
	List of laboratory or	design e	exercises				LE hours
	Modeling system (tra linear, state space) –			fferentia	al equations: linear	r or non-	2
	Analysis based on th characteristics useful	e syster	m model,			n.	2
	Parameters identifica synthesis of new con	ation of t	he contro				2
	Parameters identifica			lled see	cong order system.		2
				tercises 1. and 2 in the tasks when is stems in an entirely new working			
	Parameters Identifica	ation of t	the secon	d oredr	e controlled system	n closed	2
	Synthesis of the clos exercise.	ed loop	controlle	r applie	ed in 4.	2	
	Parameters identifica	ation of t	he contro	lled mu	Iltivariable systems	-	2
	Parameters identifica was introduced.				·		2
	Parameters identifica was introduced.	ation pro	cess whe	ere the l	inear regression m	ethod	2
	System identification	using n	neasurem	ients in	the laboratory.		2
	Seminar essay.						2
Format of instruction	 ☑ lectures ☑ seminars and workshops ☑ exercises ☑ on line in entirety ☑ partial e-learning ☑ field work ☑ independent assignments ☑ multimedia ☑ laboratory ☑ work with mentor ☑ seminar essay (other) 						
Student responsibilities	Minimum of 70 perce	ent lectu	ure attend	ance. C	Completing all the re	equired lab	oratory
Screening student	Class attendance	1.5	Researc	h	Practical tr	aining	

work (name the proportion of ECTS	Experimental work		Report		Individual work	(0.5
credits for each activity so that the	Essay		Seminar essay	1	Laboratory exe	ercises	1
total number of ECTS credits is	Tests	0.5	Oral exam		(Other)		
equal to the ECTS value of the course)	Written exam	0.5	Project		(Other)		
	will be held during cl the end of classes. In 40% correct answers be at least 50% correct	During the semester there will be two mid-term exams (tests). The first mid-term will be held during class (according to the calendar), and the other colloquium after the end of classes. Individual colloquium will be considered passed if it achieved 40% correct answers, or total points achieved that give a positive evaluation must be at least 50% correct. It is necessary during the semester to resolve homework and seminars to be					
Grading and	The final grade is de calculated as follows					earned, v	vhich is
evaluating student			%] = 0.45 * M1 -		. ,		
work in class and at the final exam	Percentage Gra 50% to 61% suff 62% to 74% goo 75% to 87% very	PercentageGrade50% to 61%sufficient (2)62% to 74%good (3)75% to 87%very good (4)					
	The final exam encompasses the entire course load or selected parts of it that students' did not pass at either of mid-term exams. The correction exam encompasses the entire course load. The requirement for passing the exam is minimum of 50 percent correct answers. The exams are held according to the class schedule.						
Required literature		Title	•		Number of copies in the library	Availabi other r	-
(available in the	J. Marasović: "Syste		•			e-lear	v
library and via other	Identifikacija sustava), FESB, Authorized lectures					por	
media)	D. Stipaničev, J. Marasović.: "Digital Control" <u>laris.fesb.hr/digitalno_vodjenje</u> , on-line udžbenik "Digitalno vođenje", 2004.					e-lear por	-
Optional literature	 L. Ljung: System Identification - Theory for the User, Prentice Hall, 1998. J. Nan-Yuang: Applied System Identification, Prentice Hall, 1993. O. Nelles: Nonlinear System Identification: From Classical Approaches to Neural Networks and Fuzzy Models, Springer –Verlag, 2000. R. Pintelon, J. Schoukens: System Identification: A Frequency Domain Approach, IEEE Press, 2001. 						
(at the time of submission of study programme proposal)	Neural Networks - R. Pintelon, J. S	s and Fu	izzy Models, Sp ns: System Iden	ringer –'	Verlag, 2000.		0
submission of study programme	 Neural Networks R. Pintelon, J. S Approach, IEEE Keeping rec Annual analy Student surv Teacher self 	s and Fu chouker <u>Press, 1</u> ords on ysis of e /ey on te f-evalua	izzy Models, Sp ns: System Iden 2001. class attendanc exam results eaching perform	ringer –' tification æ	Verlag, 2000. : A Frequency	Domain	

NAME OF THE COURSE	TELEMEDICINE AND BIOCYBERNETICS						
Code	FELG32	Year of study	1.				
Course teacher	Mojmil Cecić, Ph.D., Full Professor Josip Musić, Ph.D., Assistant Professor	Professor Josip Musić, Ph.D., Credits (ECTS) 5					
Associate teachers	Tea Marasović, Ph.D., Assistant Professor	ea Marasovic, FILD., Type of instruction				LE 30	DE 0
Status of the course	Elective	Percentage of application of e-learning	0				
	COURS	E DESCRIPTION					
Course objectives	Training students for: - understanding basic p biocybernetics.	rinciples and techniques ir	the ar	ea of te	eleme	dicine	and
Course enrolment requirements and entry competences required for the course	None						
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to: explain computer and telecommunication basis for telemedicine. evaluate properties of algorithms for image processing in telemedicine. rate clinical application of telemedicine. choose sources of medical information in light of distant learning paradigm. evaluate systems for biomechanical human analysis. analyze joint forces and moments in correlation with muscle activity. experiment with measurement systems in biocybernetics based on EMG sensors, inertial sensors and optoelectronic sensors. evaluate measurement results in light of possible future application and system limitations. 						
	Course content					ha	L
	Introduction to telemedicine. Historical development of telemedicine.						ours 2
	Computer and telecommunication basis for telemedicine.						2
	Equipment and services in telemedicine.						2
	Distant learning, searching through sources of medical information.						2
	Image processing in telemedicine.						2
Course content	Ethics and telemedicine.						2
broken down in	Clinical application.						2
detail by weekly class schedule (syllabus)	Introduction to biocybernetics; overview of technical systems for measurement of human biomechanical parameters; measurement methods in biomechanics.						2
	Human anthropometric pa terminology and measurer	nents.					2
	Gait parameter measurem and balance during gate; r	neasuring ground reaction	forces	during	gait.		2
	Electromyography, measu		humar	n move	ment.		2
	Inverse kinematics for mus						2
	Machine vision in biocybernetics.						2

List of laboratory or design exercises	LE hours
Introductory lecture on laboratory safety procedures, laboratory	2

Format of instruction 1 Grading and evaluating statematic parameters during gait using fast cameras. 4 Measuring ground reaction forces during gait using force plate. 3 Measuring EMG muscle signals during gait. 4 Calculation of muscle signals during gait. 4 Calculation of muscle signals during gait. 4 Calculation of muscle signals. 4 Measuring cervical spine range of motion using inertial motion sensors. 3 Application of machine vision in classification and automatic translation of translation of translation of translation of translation of translation of translation of translation of translation of translation of translation of using indication translation of translation or translation of translation of translation of translation of translation of translation of translation of translation of translation of translation of translation of translation of traditranslation of transla		measurement systems, and measurement procedures.						
Measuring kinematic parameters during gait using fast cameras. 4 Measuring EMG muscle signals during gait. 4 Measuring EMG muscle signals during gait. 4 Calculation of muscle forces and moments during gait based on measured kinematical parameters and floor reaction forces. Comparison 4 with recorded EMG signals. 4 Measuring cervical spine range of motion using inertial motion sensors. 3 Application of machine vision in classification and automatic translation of 4 4 Augorithms for image processing in telemedicine. 3 Bectures Independent assignments Bernard and workshops Independent assignments Brand and work Report Independent assignments Independent assignments Brand and work Image processes. Student Class attendance Research Practical training Individual work proportion of ECTS Class attendance Research Practical training Essay Seminar Laboratory exercises Cast attendance Research Practical training work (name the total number of ECTS Experimental work Report Individual work ECTS credits is oreact is is equal t		Measuring human anthropometric parameters using finite element					finite element	3
Measuring ground reaction forces during gait using force plate. 3 Measuring EMG muscle signals during gait. 4 Calculation of muscle forces and moments during gait based on measured kinematical parameters and floor reaction forces. Comparison 4 Measuring cervical spine range of motion using inertial motion sensors. 3 Application of machine vision in classification and automatic translation of croatian signed alphabet. 4 Algorithms for image processing in telemedicine. 3 Vision of inerin entirety independent assignments Seminars and workshops multimedia I partial e-learning independent assignments Student The presence on lectures in the amount of at least 70 % of the times scheduled Porportion of ECTS credits is Experimental work Report Individual work Report Individual work Cass attendance 1 Research Practical training Experimental work Report Individual work Report Individual work Essay Essay Laboratory exercises 1 Cass attendance 1 Research Preparation for laboratory exercises 1 Caster foredits is Essay			parame	eters duri	na aait	using fa	st cameras	4
Measuring EMG muscle signals during gait. 4 Calculation of muscle forces and moments during gait based on measured kinematical parameters and floor reaction forces. Comparison with recorded EMG signals. 4 Measuring cervical spine range of motion using inertial motion sensors. 3 Application of machine vision in classification and automatic translation of Croatian signed alphabet. 3 Application of machine vision in classification and automatic translation of Croatian signed alphabet. 3 Application of machine vision in classification and automatic translation of Croatian signed alphabet. 3 Bornation of muscle spine range of motion using inertial motion sensors. 3 Application of machine vision in classification and automatic translation of Croatian signed alphabet. 3 Bornation of muscle spine range of motion using inertial motion sensors. 3 Class attendance independent assignments Student exercises Individual work with mentor Improviduation of ECTS Class attendance Research Practical training work (name the proportion of ECTS readits for each activity so that the total number of ECTS credits is equal to the ECTS value of the course) 1 Oral exam Preparation for laboratory exercises 1 During the semester there are two midterm exams. The first midterm exam vactics is as and								3
Calculation of muscle forces and moments during gait based on measured kinematical parameters and floor reaction forces. Comparison 4 Measuring cervical spine range of motion using inertial motion sensors. 3 Application of muscle forces and moments during gait based on with recorded EMG signals. 4 Measuring cervical spine range of motion using inertial motion sensors. 3 Application of muscle forces and moments during inertial motion sensors. 4 Application of muscle forces and moments during inertial motion sensors. 3 Application of muscle forces and moments during inertial motion sensors. 4 Application of muscle forces and moments during inertial motion sensors. 4 Application of muscle forces and workshops independent assignments Seminar and workshops independent assignments 2 Impact and the exercises work with mentor 2 Impact and the exercises work with mentor 2 Impact and the exercises work with mentor 2 Streening student Class attendance 1 Research Practical training Voit (name the proportion of ECTS credits is equal to the ECTS value of the course Seminar Laboratory exercises 1 Essay Essay Seminar								4
with recorded EMG signals. Measuring cervical spine range of motion using inertial motion sensors. 3 Application of machine vision in classification and automatic translation of translation of machine vision in classification and automatic translation of translation of machine vision in classification and automatic translation of translation of machine vision in classification and automatic translation of translation of machine vision in classification and automatic translation of translation of machine vision in classification and automatic translation of translation of machine vision in classification and automatic translation of translation of machine vision in classification and automatic translation of translation of machine vision in classification and automatic translation of translation of machine vision in classification and automatic translation of translation of machine vision in classification and automatic translation of translation of machine vision in classification and automatic translation of translation of machine vision in classification and automatic translation of translation of machine vision in classification and automatic translation of translation of machine vision in classification and automatic translation of machine vision in classification and automatic translation of machine vision in classification and automatic translation of translation of a machine vision in classification and automatic translation of the partial elearning indication of the translation of the translation of the translation of the elearning indication of a translation of a machine vision in classification and automatic translation of the translation of the translation of the translation of the translation of the properties of tectors of the translation of a translation of the translation of the translation of the translation of the translation of the trease of telemedicine in a form of a project assignmetication of the						uring ga	it based on	
Measuring cervical spine range of motion using inertial motion sensors. 3 Application of machine vision in classification and automatic translation of Croatian signed alphabet. 4 Algorithms for image processing in telemedicine. 3 Measuring and exercises independent assignments exercises independent assignments partial e-learning on line in entirety partial e-learning (other) Student The presence on lectures in the amount of at least 70 % of the times scheduled Performed all required laboratory exercises. Screening student Class attendance 1 Research Practical training work (name the proportion of ECTS credits is equal to the ECTS value of the course) Viriten exam 0,1 Oral exam Preparation for laboratory exercises 1 ELTS credits is equal to the ECTS value of the course) Written exam 0,1 Project (Other) 1 During the semester there are to midterm exams. The first midterm exam is a vertex of significant on 40 minutes. It consists of both theoretical questions and nume problems. The final exam students that did not pass the midterm exams is part. The final exam students that did not pass the midterm exams is part. The final exam students are allowed to have at least 45% of total points on e midterm exams, as long as the final midterm average is at least 50% of total poin Grade (in percentage) is								
Application of machine vision in classification and automatic translation of Croatian signed alphabet. 4 Algorithms for image processing in telemedicine. 3 Seminars and workshops independent assignments Seminars and workshops independent assignments Portial e-learning independent assignments Image: processing in telemedicine. 3 Student partial e-learning Image: processing student independent assignments Work (name the proportion of ECTS Class attendance Essay Seminar EctTS credits is equal to the ECTS Seminar ECTS credits is equal to the ECTS 0,1 Oral exam During the semester there are two midterm exams. The first midterm exam is at 7 weeks of lectures (in the area of blocybernetics) and the second one is afte weeks of lectures (in the area of blocybernetics) and the second one is afte weeks of lectures (in the area of blocybernetical questions and nume problems. In the final exam students are allowed to have at least 50% of total point Grading and evaluating student work in class and at the final exam. Students are allowed to have at least 50% of total points on emidterm exams, as long as the final midterm examge is at least 50% of total points on emidterm exams, as long as the final midterm exams (MI + M2/Z the final exam. Students are allowed to have at least 50% of total points on emidterm exams, as long as the final midterm exarege is at least 50% of total points on emidterm exams, as								
Croatian signed alphabet. 4 Algorithms for image processing in telemedicine. 3 Format of instruction Iscletures Image processing in telemedicine. 3 Image processing in telemedicine. 1 Image processing in tel								
Algorithms for image processing in telemedicine. 3 Format of instruction Image: seminars and workshops Image: independent assignments Format of instruction Image: seminars and workshops Image: independent assignments Image: seminars and workshops Image: independent assignments Image: independent assignments Image: seminars and workshops Image: independent assignments Image: independent assignments Image: seminar independent assignments Image: independent assignments Image: independent assignments Student The presence on lectures in the amount of at least 70 % of the times scheduled Performed all required laboratory exercises. Screening student Class attendance 1 Research Practical training work (name the proportion of ECTS credits is equal to the ECTS Class attendance 1 Research Preparation for laboratory exercises 1 ECTS credits is equal to the ECTS Tests 0,1 Oral exam Preparation for laboratory exercises 1 Value of the course Written exam 0,1 Project (Other) 1 Stadent During the semester there are two midterm exams. The first midterm exams is a 7 weeks of lectures (in the area of biocybernetics) and the second one is afte week								4
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75% do 86% very good (4) 87% do 100% excellent (5) According to Article 65. of Faculty's Bylaw, student is required to participate in	evaluating student work in class and at	During the semester there are two midterm exams. The first midterm exam is afte 7 weeks of lectures (in the area of biocybernetics) and the second one is after 13 weeks of lectures (in the area of telemedicine in a form of a project assignment) Each midterm test (as well as the final test) is carried out in a written format with duration of 90 minutes. It consists of both theoretical questions and numerical problems. In the final exams students that did not pass the midterm exams take part. The final exam test consists of 8 theoretical questions and numerical problems. The requirement for passing grade is the positive assessment of laboratory exercises and 50 % points on average midterm exam ((M1 + M2)/2) of the final exam. Students are allowed to have at least 45% of total points on each midterm exams, as long as the final midterm average is at least 50% of total points. Grade (in percentage) is formed according to the formula: Grade(%) = 0,25L + 0,25M1 + 0,5M2 where: • L – laboratory assessment, • M1, M2 – midterm test results. Final grade (based on percantages) is formed as follows: Percentage Grade 50% do 62% sufficient (2) 63% do 74% good (3) 75% do 86% very good (4)						

	teaching activities attending at least 70% of lectures, and 100% of laboratory exercises. In accordance with that student is required to solve and turn over for grading 100% of all laboratory exercises. If student does not meet these criteria, she or he won't be able to take part in the final exam, and will be required to enroll in the course the next year.				
	Title	Number of copies in the library	Availability via other media		
	 I. Klapan, I. Čikeš:; Telemedicina u Hrvatskoj, Medika, Zagreb, 2001. 	3	teacher		
Required literature (available in the library and via other media)	 R. J. Jagacinski, J. M. Flach: Control Theory for Humans: Quantitative Approaches to Modeling Performance, Lawrence Erlbaum Associates Inc., 2003 		teacher		
	 T. Marasović, Guidelines for laboratory exercises, FESB 		e-learning portal		
	M. Cecić, J. Musić: Authorized lecture notes, FESB		e-learning portal		
Optional literature (at the time of submission of study programme proposal)	 Winter D.A.: The Biomechanics and Motor Control of Human Gait, University of Waterloo Press, Waterloo, 1991. Zanchi V., Cecić M., Grujić T., Kuzmanić A., Papić V. : Laboratory for Identification of Human Movement with LaBACS Software Support, International Congress on Computational Bioengineering, ICCB'03, 24-26 September 2003., Zaragoza, Spain, p.p. 155-161 I. Kaplan, I Čikeš (editors): "Telemedicine", Telemedicine Association, Zagreb, 2005. V. Štambuk: "Kibernetika s informatikom", 1989. V. R. Milačić : "Tehnička kibernetika", 1981. N. Wiener: "Kibernetika ili upravljanje i komunikacija kod živih bića i mašina", 1972. 				
Quality assurance methods that ensure the acquisition of exit competences	 Keeping records of student attendance Annual analysis of course statistics in terms of midterm and finals exams Feedback from students via surveys teacher self evaluation Feedback from graduated students (or senior students) on course content relevance Periodic institutional evolution of course teachers 				
Other (as the proposer wishes to add)	/				

NAME OF THE COURSE	DIPLOMA THESIS							
Code	FEXX02	Year of s	tudy	2				
Course teacher		Credits (ECTS) 30						
Associate teachers		Type of instruction (number of hours)			S	AE	LE	DE
Status of the course	Mandatory	Percenta applicatio	ge of on of e-learning		-			-
	COURS	E DESCRI	PTION					
Course objectives	Training students for: - consolidating theo complex engineer - being independer - applying scientific - writing and preser	ring problen at in solving -research a	ns, problems unde and ethical prin	er the gi				ly
Course enrolment requirements and entry competences required for the course	Acquired 60 ECTS credits							
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	 Students will be able to: To consolidate theoretical knowledge and practical skills in solving highly complex engineering problems To use literature, databases and other sources of information To select appropriate methods and procedures for solving the most complex engineering problems To apply scientific and technical knowledge and skills to effectively solve engineering problems To apply scientific research methodology and ethical principles in the science To give oral public presentation, to prepare written report and present project 				nce			
Course content broken down in detail by weekly class schedule (syllabus)	results Diploma thesis is the inde task and instructions give research methodology and	n by the su	pervisor, and a	•			•	he
Format of instruction	 □ lectures □ seminars and workshops □ exercises □ on line in entirety □ partial e-learning □ field work □ independent assignments □ multimedia □ laboratory □ work with mentor □ (other) 			5				
Student responsibilities	Independent work							
Screening student work (name the	Class attendance	Researc	h	Practic	al trair	ning		
proportion of ECTS	Experimental work	Report		Individ	ual wo	rk		30
credits for each activity so that the	Essay	Seminal essay	r		(Other	.)		
total number of ECTS credits is	Tests	Oral exa	am		(Other	.)		
equal to the ECTS value of the course)	Written exam	Project			(Other	.)		

Grading and evaluating student work in class and at the final exam	Producing of the diploma thesis is evaluated by the supervisor based on the student's achievements during the process of preparing the diploma thesis. Commission for defence of the diploma thesis gives an assessment, representing an average grade for the preparation and defence of the thesis.				
	Title	Number of copies in the library	Availability via other media		
Required literature (available in the library and via other media)	 Etički kodeks Fakulteta elektrotehnike, strojarstva i brodogradnje u Splitu Zelenika, Ratko: Metodologija i tehnologija izrade znanstvenog i stručnog djela, Pisana djela na stručnim i sveučilišnim studijima, knjiga peta, Ekonomski fakultet u Rijeci, Rijeka, 2011. Žugaj, Miroslav; Dumičić, Ksenija; Dušak, Vesna: Temelji znanstvenoistraživačkog rada, Metodologija i metodika, Fakultet organizacije iinformatike, Varaždin, 2006. Literature depends on the given problem. The literature list may be given by the supervisor or the student should find the appropriate literature to help solve the problem. 		Web site of the Faculty		
Optional literature (at the time of submission of study programme proposal)					
Quality assurance methods that ensure the acquisition of exit competences	 Self-evaluation of teachers Student survey of the whole study programme 				
Other (as the proposer wishes to add)					

STUDY PERFORMANCE CONDITIONS

2.14. Places of the study performance

Buildings of the constituent part (name existing, under construction and planned buildings)		
Identification of building		
Location of building		
Year of completion		
Total square area in m ²		
Identification of building		
Location of building		
Year of completion		
Total square area in m ²		

2.15. List of teachers and associate teachers

CODE	Course	Teachers and associate teachers
	List the courses in alphabetical order	
FENG02	Adaptive control	Ozren Bego, Ph.D., Associate Professor Danijel Jelovski, Ph.D., Assistant Professor
FELH11	Artificial intelligence	Darko Stipaničev, Ph.D., Full Professor Ljiljana Šerić, Ph.D., Assistant Professor Toni Jakovčević, Ph.D., Assistant Professor
FELG17	Bioelectrical systems and equipment	Mirjana Bonković, Ph.D., Full Professor Zoran Valić, Ph.D., Full Professor
FELG15	CAD in automatic control	Mojmil Cecić, Ph.D., Full Professor Ana Kuzmanić Skelin, Ph.D., Assistant Professor
FELG18	Computational intelligence (neuro- fuzzy-genetic systems)	Darko Stipaničev, Ph.D., Full Professor Toni Jakovčević, Ph.D., Assistant Professor Marin Bugarić, Ph.D. Dunja Gotovac, Teaching Assistant
FELG29	Computer aided process control	Betti Tihomir, Ph.D., Assistant Professor Ivan Marasović, Ph.D., Assistant Professor
FELK04	Computer graphics	Vladan Papić, Ph.D., Full Professor Denis Štajduhar, Teaching Assistant
FELG20	Computer methods in bioengineering	Vladan Papić, Ph.D., Full Professor Josip Musić, Ph.D., Assistant Professor
FELG02	Computer systems	Maja Štula, Ph.D., Full Professor Toni Jakovčević, Ph.D., Assistant Professor
FELG10	Digital control	Darko Stipaničev, Ph.D., Full Professor Josip Musić, Ph.D., Assitant Professor
FELG09	Digital image processing and analysis	Damir Krstinić, Ph.D., Associate Professor Darko Stipaničev, Ph.D., Full Professor Maja Braović, Ph.D.
FELG16	Digital instrumentation 2	Tihomir Betti, Ph.D., Assistant Professor Ivan Marasović, Ph.D., Assistant Professor

FELG13	Programmable logic controllers	Tihomir Betti, Ph.D., Assistant Professor Maja Štula, Ph.D., Full Professor
FEXX06	Professional Training	Mojmil Cecić, Ph.D., Full Professor
FETL23	Production management	Ivica Veža, Ph.D., Full Professor Marko Mladineo, Ph.D.
FELG22	Process control laboratory	Jadranka Marasović, Ph.D., Full Professor Ivo Stančić, Ph.D., Assistant Professor
FELG21	Process control	Darko Stipaničev, Ph.D., Full Professor Ljiljana Šerić, Ph.D., Assistant Professor
FELG12	Practicum of automatic control	Tamara Grujić, Ph.D., Full Professor
FELG33	Optoelectronic measurement methods	Ivo Stančić, Ph.D., Assistant Professor
FELG23	Optimization and optimal systems	Mirjana Bonković, Ph.D., Full Professor
FELG14	Operations research	Jadranka Marasović, Ph.D., Full Professor Martina Bašić, Teaching Assistant
FEMK01	Numerical analysis	Ivan Slapničar, Ph.D., Full Professor Lana Periša, Anita Carević
FELG11	Nonlinear control systems	Mojmil Cecić. Ph.D., Full Professor Ana Kuzmanić Skelin, Ph.D., Assistant Professor
FELG26	Multivariable control	Jadranka Marasović, Ph.D., Full Professor
FEMG01	Modern physics	Nikola Godinović, Ph.D., Associate Professor Dunja Polić, Darko Zarić, Toni Vrdoljak
FELG27	Modelling and control of vessels and ground vehicles	Darko Stipaničev, Ph.D., Full Professor Damir Krstinić, Ph.D., Associate Professor
FELG25	Mobile robotics	Mirjana Bonković, Ph.D., Full Professor Miroslav Dujmović, Teaching Assistant
FELG24	Microcontrollers and network embedded systems	Mirjana Bonković, Ph.D., Full Professor Ivo Stančić, Ph.D., Assistant Professor
FENI03	Measurements and signal processing	Goran Petrović, Ph.D., Associate Professor Juraj Alojzije Bosnić, Teaching Assistant
FELG01	Linear control systems	Tamara Grujić, Ph.D., Full Professor
FELG30	Introduction to machine learning	Tamara Grujić, Ph.D., Full Professor Ivo Stančić, Ph.D., Assistant Professor
FELG05	Industrial robotics	Mojmil Cecić, Ph.D., Full Professor Stanko Kružić, Teaching Assistant
FETG02	Hydraulic and pneumatic systems	Jani Barle, Ph.D., Full Professor Alen Kovač, Teaching Assistant
FEOG01	English language for academic purposes	Daniela Matić, Ph.D., Assistant Professor
FENG01	Engineering economy	Ranko Goić, Ph.D., Associate Professor Damir Jakus, Ph.D., Assistant Professor Josip Vasilj, Ph.D. Stipe Vodopija, Teaching Assistant
FENG04	Energy storage systems	Ozren Bego, Ph.D., Associate Professor Danijel Jolevski, Ph.D., Assistant Professor
FELH13	Electronic circuits	Ivan Marinović, Ph.D., Full Professor Duje Čoko, Ph.D., Assistant Professor
FELG07	Electronic and virtual instrumentation	Ivo Mateljan, Ph.D., Full Professor
FENG03	Electric servo drives	Božo Terzić, Ph.D., Full Professor Goran Majić, Ph.D.
FELH07	Digital systems projecting - Projektiranje digitalnih sustava	Vesna Pekić, Ph.D. Ante Kristić, Ph.D.

		Ivan Marasović, Ph.D., Assistant Professor
FELG03	System Identification	Jadranka Marasović, Ph.D., Full Professor
T LLG03	System Identification	Tea Marasović, Ph.D., Assistant Professor
		Mojmil Cecić, Ph.D., Full Professor
FELG32	Telemedicine and biocybernetics	Josip Musić, Ph.D., Assistant Professor
		Tea Marasović, Ph.D., Assistant Professor
FEXX02	Diploma thesis	

3.4. Curriculum vitae of the course teacher

First and last name and title of teacher	Jani Barle, Ph.D., Full Professor
The course he/she teaches in the proposed study programme	Hydraulic and pneumatic systems
GENERAL INFORMATION ON COU	RSE TEACHER
Address	Žnjanska 4, 21000 Split, HR a
Telephone number	+385 (21) 305930
E-mail address	Jani.Barle@fesb.hr
Personal web page	https://nastava.fesb.hr/nastava/nastavnici/detalji/barle
Year of birth	1964
Scientist ID	186172
Research or art rank, and date of	
last rank appointment	Scientific Adviser, May 2011.
Research-and-teaching, art-and-	
teaching or teaching rank, and date	Senior Full Professor, September 2016.
of last rank appointment	
Area and field of election into research or art rank	Mechanical engineering, mechanical construction engineering
INFORMATION ON CURRENT EMP	LOYMENT
Institution where employed	University of Split, Faculty of Electrical Engineering, Mechanical
	Engineering and Naval Architecture
Date of employment	July 1991.
Name of position (professor,	Professor
researcher, associate teacher, etc.)	
Field of research	Process Automation, System Maintenance Management
Function	Education and research
INFORMATION ON EDUCATION - H	Highest degree earned
Degree	Ph.D.
Institution	University of Zagreb, Faculty of Mechanical Engineering and Naval Architecture
Place	HR - Zagreb
Date	January 1998.
INFORMATION ON ADDITIONAL TR	AINING
Year	1996.
Place	IT - Padua
Institution	Dipartimento di Ingegneria Meccanica
Field of training	Research on experimental methods
MOTHER TONGUE AND FOREIGN	LANGUAGES
Mother tongue	Croatian
Foreign language and command of	
foreign language on a scale from 2 (sufficient) to 5 (excellent)	English - 5
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	German - 3
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	Italian - 3

COMPETENCES FOR THE COURSE	
	On Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Earlier experience as course teacher of similar courses (name title of course, study programme where it is/was offered, and level of study programme)	<u>Undergraduate study:</u> - Industrial process control (FETC06)
	<u>Master's degree study:</u> - Hydraulics and pneumatics(FETL17) - Maintenance management (FETL04) - Product life management (FETM06)
	<u>Doctorate degree study:</u> - Experimental methods (FETU24) - Reliability engineering (FETU14)
Authorship of university/faculty textbooks in the field of the course	Barle, J.: Hydraulics and pneumatics, (student handbook and workbook in Croatian: <i>Hidraulika i pneumatika</i>), FESB, Split, 2010.
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	 Barle, Jani; Đukić, Predrag; Ban, Dario. Verification of Number of Cycles for Fatique Life Estimation of Wind-Sensitive Structures // 7th ICCSM / Croatian Society of Mechanics, 2012. 233-234. Barle, Jani; Wolf, Hinko; Đukić, Predrag. Experimental verification of the dynamic model for a wind turbine tower // 30th Danubia-Adria: Symposium on Advances in Experimental Mechanics / Croatian Society of Mechanics, 2013. 219-220 Grubišić, Vatroslav; Barle, Jani. Procedure for the Service Strength Approval of the Drillship Derricks. // Rad Hrvatske akademije znanosti i umjetnosti. Tehničke znanosti. 521 (2015), 17; 51-62. Đukić, Predrag; Wolf, Hinko; Jani, Barle. Simple dynamic model of wind turbine tower with experimental verification. // International journal for engineering modelling. 28 (2015), 1-4; 49-59
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	 Barle, Jani; Franulović, Marina; Jurčević Lulić, Tanja; Kladarić, Ivica; Markučič, Damir; Radica, Gojmir. <i>Izrada</i> <i>kataloga znanja, vještina i kompetencija za studije strojarstva u</i> <i>Republici Hrvatskoj //</i> Zbornik radova međunarodne stručne konferencije ME4CataLOgue / Kozak, D., Barle, J., Markučič, D., Pavletić, D., Matičević, G, Vranešević M. N., Rosandić, Ž, Damjanović, D. (ur.)., SI.Brod 2015. "Hrvatski katalog znanja, vještina i kompetencija za studije strojarstva zasnovan na ishodima učenja (za preddiplomski, diplomski i doktorski studij)", Strojarski fakultet u Slavonskom Brodu Sveučilišta J. J. Strossmayera u Osijeku, 2015., Kozak, D., Barle, J., Boras, I., Franulović, M., Jurčević-Lulić, T., Kladarić, I., Lelas, D., Markučić, D., Matičević, G., Pavletić, D., Vranešević-Marinić, N.(ur.), ISBN 978-953-6048-78-6
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences	IPA IV project ME4CataLOgue "Further development and implementation of the Croatian Qualifications Framework (CQF)", 2013-2015.

PRIZES AND AWARDS, STUDENT EVALUATION	
Prizes and awards for teaching and scholarly/artistic work	
Results of student evaluation taken	
in the last five years for the course	
that is comparable to the course	
described in the form (evaluation organizer, average grade, note on	
grading scale and course	
evaluated)	
First and last name and title of	
--	---
teacher	Ozren Bego, Ph.D., Associate Professor
The course he/she teaches in the	Adaptive control
proposed study programme	Energy Storage Systems
GENERAL INFORMATION ON COU	
Address	Trondheimska 4C, 21000 Split, Croatia
Telephone number	+385 21 305605
E-mail address	obego@fesb.hr
Personal web page	
Year of birth	1966.
Scientist ID	186161
Research or art rank, and date of	
last rank appointment	Research Scientist, November 2017.
Research-and-teaching, art-and-	
teaching or teaching rank, and date	Associate Professor, December 2017.
of last rank appointment	
Area and field of election into	
research or art rank	Technical Sciences, Field Automation and Robotics
INFORMATION ON CURRENT EMP	LOYMENT
	Faculty of Electrical Engineering, Mechanical Engineering and
Institution where employed	Naval Architecture
Date of employment	1991.
Name of position (professor,	
researcher, associate teacher, etc.)	Associate Professor
Field of research	Automation, Digital Control Systems
Function	
INFORMATION ON EDUCATION - H	Highest degree earned
Degree	PhD
Institution	Faculty of Electrical Engineering and Computing
Place	Zagreb
Date	24. 2. 2005.
INFORMATION ON ADDITIONAL TR	
Year	
Place	
Institution	
Field of training	
MOTHER TONGUE AND FOREIGN	
Mother tongue Foreign language and command of	Croatian
foreign language on a scale from 2	English (4)
(sufficient) to 5 (excellent)	
Foreign language and command of	
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	
Foreign language and command of	
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	
COMPETENCES FOR THE COURS	
Earlier experience as course	
teacher of similar courses (name	
title of course, study programme	Elements of industrial automation, Undergraduate study:
	Electrical Engineering and Information Technology.
where it is/was offered, and level of study programme)	
study programme)	
study programme) Authorship of university/faculty	
study programme) Authorship of university/faculty textbooks in the field of the course	Jolevski, Danijel: Bego, Ozren: Sarajcev, Petar: Control
study programme) Authorship of university/faculty	Jolevski, Danijel; Bego, Ozren; Sarajcev, Petar: Control structure design and dynamics modelling of the organic

years in the field of the course (5 works at most)	Rankine cycle system // Energy (Oxford). 121 (2017) ; 193- 204. Jolevski, Danijel; Bego, Ozren. Model predictive control of gantry/bridge crane with anti-sway algorithm. // Journal of mechanical science and technology. 29 (2015) , 2; 827-834 Jolevski, Danijel; Bego, Ozren; Grgat, Frano. GA Optimized AVR Controller with Higher Degree of Freedom of Tuning of Wanted Response. // International Review of Automatic Control (IREACO). 8 (2015) , 1; 72-79
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	Nacional research project: Safer and more efficient cogeneration / trigeneration plants, 20152016., project financed from the EU fond. Development project: Control system for small hydro power plants, project leader, 20102017., project realized for Sintaksa d.o.o.
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?-pedagoške kompetencije? PRIZES AND AWARDS, STUDENT I	
Prizes and awards for teaching and	
scholarly/artistic work Results of student evaluation taken	
in the last five years for the course	
that is comparable to the course	
described in the form (evaluation organizer, average grade, note on	
grading scale and course	
evaluated)	

Tihomir Betti, Ph.D., Assistant Professor
Computer aided process control Digital instrumentation 2 Programmable logic controllers
Solar cells
RSE TEACHER
Kaštelanska 2, HR-21000, Split
091 4305 889
betti@fesb.hr
1977
248722
Assistant research fellow, 22.11.2012.
Assistant professor, 18.09.2013.
Technical sciences, electrical engineering
LOYMENT
Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
08.06.2001.
Assistant professor
'
Electronics, Nanoelectronics, Photovoltaics
Highest degree earned
PhD
Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Split
04.12.2009.
RAINING
2013. (7 weeks)
Freiburg, Germany
Fraunhofer ISE
Photovoltaics
2011. (3 weeks)
Ljubljana, Slovenia
Institute "Jožef Stefan"
Hybrid polymer solar cells
2007-2009. (several visits, 4 weeks in total)
Munich, Germany
Walter Schottky Institute
Application of semiconductor nanostructures in third generation photovoltaics
LANGUAGES
Croatian
English, 5
-
Italian, 2

COMPETENCES FOR THE COURS	E
Earlier experience as course teacher of similar courses (name title of course, study programme where it is/was offered, and level of study programme)	Programmable logic controllers, Graduate study of Control Engineering and Automation, Optoelectronics, Graduate study of Electronic and Computer Engineering Solar cells, Graduate study of Electronic and Computer Engineering and Control Engineering and Automation
Authorship of university/faculty textbooks in the field of the course	
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	 I. Marasović, Ž. Milanović, T. Betti, "Resistance Fluctuations in GaAs Nanowire Grids", Journal of Nanomaterials, (2014), 428390 I. Marasović, T. Garma, T. Betti, "Modelling a nanowire grid for light- sensing applications", Journal of Physics D: Applied Physics 45 (2012)
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?	
PRIZES AND AWARDS, STUDENT	EVALUATION
Prizes and awards for teaching and scholarly/artistic work	
Results of student evaluation taken in the last five years for the course that is comparable to the course described in the form (evaluation organizer, average grade, note on grading scale and course	
evaluated)	

First and last name and title of	
teacher	Mirjana Bonković, Ph.D., Full Professor
The course he/she teaches in the proposed study programme	Bioelectrical systems and equipment Microcontrollers and network embedded systems Mobile robotics Optimization and optimal systems
GENERAL INFORMATION ON COU	RSE TEACHER
Address	R. Boškovića 32, 21 000 Split, HR
Telephone number	+385 91 4 305 641
E-mail address	mirjana.bonkovic@fesb.hr
Personal web page	
Year of birth	
Scientist ID	190481
Research or art rank, and date of	
last rank appointment	
Research-and-teaching, art-and- teaching or teaching rank, and date of last rank appointment	Full professor, 2016.
Area and field of election into research or art rank	Technical Sciences, Field Electrical engineering
INFORMATION ON CURRENT EMP	LOYMENT
Institution where employed	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Date of employment	01/7/1991
Name of position (professor,	Full professor, 2016.
researcher, associate teacher, etc.)	
Field of research	3D modelling, robotics, computer vision, optimization
Function	
INFORMATION ON EDUCATION - I	Highest degree earned
Degree	PhD
Degree Institution	PhD Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture Split
Institution	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Institution Place Date	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture Split 10/3/2000.
Institution Place	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture Split 10/3/2000.
Institution Place Date INFORMATION ON ADDITIONAL TR	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture Split 10/3/2000. RAINING
Institution Place Date INFORMATION ON ADDITIONAL TF Year	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture Split 10/3/2000. RAINING 1995
Institution Place Date INFORMATION ON ADDITIONAL TR Year Place	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture Split 10/3/2000. RAINING 1995 Oxford, UK
Institution Place Date INFORMATION ON ADDITIONAL TR Year Place Institution	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture Split 10/3/2000. AINING 1995 Oxford, UK Robotics Research Group Robot production lines optimization
Institution Place Date INFORMATION ON ADDITIONAL TR Year Place Institution Field of training MOTHER TONGUE AND FOREIGN	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture Split 10/3/2000. RAINING 1995 Oxford, UK Robotics Research Group Robot production lines optimization LANGUAGES
Institution Place Date INFORMATION ON ADDITIONAL TR Year Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture Split 10/3/2000. AINING 1995 Oxford, UK Robotics Research Group Robot production lines optimization
Institution Place Date INFORMATION ON ADDITIONAL TR Year Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture Split 10/3/2000. RAINING 1995 Oxford, UK Robotics Research Group Robot production lines optimization LANGUAGES Croatian
Institution Place Date INFORMATION ON ADDITIONAL TF Year Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of foreign language on a scale from 2	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture Split 10/3/2000. AINING 1995 Oxford, UK Robotics Research Group Robot production lines optimization LANGUAGES Croatian English (5)
Institution Place Date INFORMATION ON ADDITIONAL TF Year Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of foreign language and command of foreign language and command of foreign language on a scale from 2	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture Split 10/3/2000. AINING 1995 Oxford, UK Robotics Research Group Robot production lines optimization LANGUAGES Croatian English (5) German (2)
Institution Place Date INFORMATION ON ADDITIONAL TF Year Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent)	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture Split 10/3/2000. AINING 1995 Oxford, UK Robotics Research Group Robot production lines optimization LANGUAGES Croatian English (5) German (2)

textbooks in the field of the course	Zbirka riješenih zadataka iz programiranja u Cu, upute za laboratorijske vježbe, Interna skripta, FESB Split Mikroregulatori i ugradbeni mrežni sustavi, Interna skripta, FESB Split, 2014
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	 Kuzmanić Skelin, Ana; Grujić, Tamara; Bonković, Mirjana, Visual Peoplemeter: A Vision-based Television Audience Measurement System. // Advances in Electrical and Computer Engineering. 14 (2014), 4; 73-80 Mazić Igor, Bonković Mirjana, Džaja Barbara. Two-Level Coarse-to-Fine Classification Algorithm for Asthma Wheezing Recognition in Children's Respiratory Sounds. //Biomedical Signal Processing and Control. 5 (2015) ; 105-118 (članak, znanstveni). Džaja, Barbara; Bonković, Mirjana; Malešević, Ljubomir. Solving a two-colour problem by applying probabilistic approach to a full-colour multi- frame image super-resolution. // Signal processing. Image communication. 28 (2013) , 5; 509-521 (članak, znanstveni). Čić, Maja; Šoda, Joško; Bonković, Mirjana. Automatic classification of infant sleep based on instantaneous frequencies in a single-channel EEG signal. // Computers in biology and medicine. 43 (2013) , 12; 2110-2117 (članak, znanstveni). Musić, Josip; Bonković, Mirjana; Cecić, Mojmil. Comparison of uncalibrated model-free visual servoing methods for small amplitude movement: a simulation study. //International journal of advanced robotic systems. 11 (2014) , 108; 1-16 (članak, znanstveni).
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	Provjera inovativnog koncepta, Alarm astmatičnog napada, projekt HAMAG-BICRO, agencija za malo gospodarstvo, inovacije i investicije., 2014. /2015. "Virtual CulTourist - Razvoj korisničkog sučelja za virtualno predstavljanje kulturne baštine kroz integraciju inovativnih 3D tehnologija", 2016-2017. Programa tehnološkog razvoja, istraživanja i primjene inovacija (20142017.), SDŽ "Napredne metode 3D virtualizacije – na putu prema virtualnom turizmu i digitalizaciji splitske kulturne baštine", 2015-2016. Programa tehnološkog razvoja, istraživanja i primjene inovacija (20142017.), SDŽ
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences	
PRIZES AND AWARDS, STUDENT I Prizes and awards for teaching and	EVALUATION
scholarly/artistic work	
Results of student evaluation taken in the last five years for the course	
that is comparable to the course described in the form (evaluation organizer, average grade, note on	

grading scale and course evaluated)	
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First and last name and title of teacher	Mojmil Cecić, Ph.D., Full Professor
The course he/she teaches in the proposed study programme	CAD in automatic control Industrial Robotics Nonlinear Control Systems Telemedicine and Biocybernetics
GENERAL INFORMATION ON COU	RSE TEACHER
Address	Slavonska 6, Split
Telephone number	091 4 305 828
E-mail address	mcecic@fesb.hr
Personal web page	-
Year of birth	1960.
Scientist ID	122922
Research or art rank, and date of last rank appointment	Scientific Adviser, 20 th November, 2007.
Research-and-teaching, art-and- teaching or teaching rank, and date of last rank appointment	Full professor; 20 th March, 2014.
Area and field of election into research or art rank	Technical Science, Electrotehnics
INFORMATION ON CURRENT EMP	LOYMENT
Institution where employed	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Date of employment	15 th January, 1985.
Name of position (professor, researcher, associate teacher, etc.)	Professor
Field of research	Control Systems, Robotics
Function	Head of the Department of Electronics and Computer Science
INFORMATION ON EDUCATION - H	lighest degree earned
Degree	PhD.
Institution	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Place	Split
Date	25 th June, 1999.
INFORMATION ON ADDITIONAL TR	AINING
Year	1988.
Place	Budapest, Hungary
Institution	Budepest University of Technology and Economics
Field of training	Industrial robotics
MOTHER TONGUE AND FOREIGN	LANGUAGES
Mother tongue	Croatian
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	English (4)
COMPETENCES FOR THE COURSE	
Earlier experience as course teacher of similar courses (name title of course, study programme where it is/was offered, and level of study programme)	 Nonlinear Control Systems (Graduate Study Programme) Industrial robotics (Graduate Study Programme) Programmable logic controllers (PLC), (Graduate Study Programme)
Authorship of university/faculty textbooks in the field of the course	1. V. Zanchi, M. Bonković, M. Cecić, Programska podrška linearnoj teoriji automatskog upravljanja, FESB, Split.

Professional, scholarly and artistic	1. Stančić, Ivo; Cecić, Mojmil; Ljubičić, Ante; Identification of
articles published in the last five	UAV Engine Parameters. // WSEAS TRANSACTIONS ON

years in the field of the course (5 works at most)	 SYSTEMS AND CONTROL. 10 (2015) ; 179-185 (članak, znanstveni). Musić, Josip; Bonković, Mirjana; Cecić, Mojmil; Comparison of uncalibrated model-free visual servoing methods for small amplitude movement: a simulation study. // International journal of advanced robotic systems. 11 (2014) , 108; 1-16 (članak, znanstveni) Cecić, Mojmil; Papić, Vladan; Bonković, Mirjana; Grujić, Tamara; Musić, Josip; Kuzmanić Skelin, Ana; Stančić, Ivo; Marasović, Tea; Čić, Maja; Pleština, Vladimir; Science and Technology in Biomedical Engineering: LaBACS Case Example. // Physical Medicine and Rehabilitation - International. 1 (2014) , 2; 1-11 (članak, znanstveni). Stančić, Ivo; Musić, Josip; Cecić, Mojmil; A Novel Low-Cost Adaptive Scanner Concept for Mobile Robots. // Ingeniería e Investigación. 34 (2014) , 3; 37-43 (članak, znanstveni). Cecić, Mojmil; Krajči, Vesna; Bonković, Mirjana; Optimization of Model-Reference Variable-Structure Controller Parameters for Direct-Current Motor. // Journal of Computations and Madelling. 2 (2014) . 2: 20 (2014) . 2: 20 (2014) .
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	 Modelling. 2 (2012.), 3; 67-88 (članak, znanstveni). Stančić, Ivo; Cecić, Mojmil; Ljubičić, Ante; Identification of UAV Engine Parameters. // WSEAS TRANSACTIONS ON SYSTEMS AND CONT ROL. 10 (2015); 179-185 (članak, znanstveni). Musić, Josip; Bonković, Mirjana; Cecić, Mojmil; Comparison of uncalibrated model-free visual servoing methods for small amplitude movement: a simulation study. // International journal of advanced robotic systems. 11 (2014), 108; 1-16 (članak, znanstveni) Cecić, Mojmil; Papić, Vladan; Bonković, Mirjana; Grujić, Tamara; Musić, Josip; Kuzmanić Skelin, Ana; Stančić, Ivo; Marasović, Tea; Čić, Maja; Pleština, Vladimir; Science and Technology in Biomedical Engineering: LaBACS Case Example. // Physical Medicine and Rehabilitation - International. 1 (2014), 2; 1-11 (članak, znanstveni). Stančić, Ivo; Musić, Josip; Cecić, Mojmil; A Novel Low-Cost Adaptive Scanner Concept for Mobile Robots. // Ingeniería e Investigación. 34 (2014), 3; 37-43 (članak, znanstveni). Cecić, Mojmil; Krajči, Vesna; Bonković, Mirjana; Optimization of Model-Reference Variable-Structure Controller Parameters for Direct-Current Motor. // Journal of Computations and Modelling. 2 (2012.), 3; 67-88 (članak, znanstveni).
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	 Projekt 0023022: Biomechanics of Human Walking, Control and Rehabilitation, MZT RH, 20082013. Computer Intelligence in Recognition and Support of Human Activities (RIPrePAkt), project FESB.
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?	

PRIZES AND AWARDS, STUDENT EVALUATION	
Prizes and awards for teaching and	
scholarly/artistic work	
Results of student evaluation taken in	
the last five years for the course that is	

comparable to the course described in	
the form (evaluation organizer, average	
grade, note on grading scale and	
course evaluated)	

First and last name and title of	Nikola Godinović, Ph.D., Associate Professor	
teacher	Nikola Obullović, Th.D., Associate Troicssof	
The course he/she teaches in the proposed study programme	Modern Physics	
GENERAL INFORMATION ON COU	RSE TEACHER	
Address	Omiška 20, 21000 Split	
Telephone number	0915195314	
E-mail address	nikola.godinovic@fesb.hr	
Personal web page		
Year of birth	1959	
Scientist ID	129696	
Research or art rank, and date of	123030	
last rank appointment		
Research-and-teaching, art-and-		
teaching or teaching rank, and date	Associate Professor, 11.3.2016.	
of last rank appointment	ASSociate Froiesson, 11.3.2010.	
Area and field of election into		
research or art rank	Area of natural sciences, field of physics	
INFORMATION ON CURRENT EMP		
	University of Split	
	Faculty of Electrical Engineering, Mechanical Engineering and	
Institution where employed	Naval Architecture	
	R. Boškovića 32	
	21000 Split	
	Croatia	
Date of employment	1.1.1985.	
Name of position (professor,	professor	
researcher, associate teacher, etc.)		
Field of research	Physics	
Function	Head of the Department of Mathematichs and Physics	
INFORMATION ON EDUCATION - H	Highest degree earned	
Degree	PhD	
Institution	University of Zagreb	
Place	Croatia, Zagreb	
Date	30.11.2003.	
INFORMATION ON ADDITIONAL T		
Year	1995. – 2017. god.	
Place	Geneva	
Institution Field of training	CERN Experimenetal Elementary Partiala Physica	
Field of training	Experimenatal Elementary Particle Physics	
MOTHER TONGUE AND FOREIGN		
Mother tongue	Croatian	
Foreign language and command of		
foreign language on a scale from 2	English 5	
(sufficient) to 5 (excellent)		
Foreign language and command of		
foreign language on a scale from 2	Italian 4	
(sufficient) to 5 (excellent)		
Foreign language and command of		
foreign language on a scale from 2	German 2	
(sufficient) to 5 (excellent)		
COMPETENCES FOR THE COURS	COMPETENCES FOR THE COURSE	
Earlier experience as course teacher of	Nuclear physcis, Experimtnal Methods of Moderan Physics,	
similar courses (name title of course,	graduate program, University of Split, Fcaulty of Scince.	
study programme where it is/was offered, and level of study programme)		

Authorship of university/faculty textbooks in the field of the course	Faculty text book: Instructions for laboratory exercises in Physics 1 Instructions for laboratory exercises in Physics 1	
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	 Teraelectronvolt pulsed emission from the Crab Pulsar detected by MAGIC, MAGIC Collaboration, Ansoldi, S.; et al., . (Authors: MAGIC collaboration), Astronomy and Astrophysics 585, Article Number: A133 (2016) IF: 4.479. The major upgrade of the MAGIC telescopes, Part I: The hardware improvements and the commissioning of the system, (Authors: MAGIC Collaboration,) Astroparticle Physics 72, pages: 61-75 (2016) IF: 3.584. The major upgrade of the MAGIC telescopes, Part II: A performance study using observations of the Crab Nebula, (Authors: MAGIC Collaboration), Astroparticle Physics 72, pages: 76-94 (2016) IF: 3.584. Measurement of the properties of a Higgs boson in the four-lepton final state, By: Chatrchyan, S.; Khachatryan, V.; Sirunyan, A. M.; et al., Group Author(s): CMS Collaboration, Physical Review D 89, Issue: 9, Article Number: 092007 (2014) IF: 4.506 Study of the Mass and Spin-Parity of the Higgs Boson Candidate via Its Decays to Z Boson Pairs, S. Chatrchyan et al. (CMS Collaboration), Physical Review Letters 110, 081803 – Published 21 February 2013; Erratum Phys. Rev. Lett. 110, 189901 (2013). IF: 7.512. 	
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	None	
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	<i>HRZZ Research Projects</i> (IP-11-2013), Croatian Sicnece Foundation zaklada za znanost (1.10.2014. god. – 30.9.2018. god.). <i>HRZZ Research Projects</i> (Very high energy gamma ray astronomy with the MAGIC telescopes), Croatian Sic nece Foundation zaklada za znanost (1.7.2012. god. – 31.12.2016.).	
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?		
PRIZES AND AWARDS, STUDENT EVALUATION		
Prizes and awards for teaching and scholarly/artistic work	Slobodna Dalmacija "Science Award"	
Results of student evaluation taken in the last five years for the course that is comparable to the course described in the form (evaluation organizer, average grade, note on grading scale and course evaluated)		
First and last name and title of		

First and last name and title of teacher	Ranko Goić, Ph.D., Full Professor
The course he/she teaches in the	Engineering Economy

proposed study programme		
GENERAL INFORMATION ON COU	RSE TEACHER	
Address	Put Žnjana 14G, 21000 Split, HR	
Telephone number	+385 21 305604	
E-mail address	rgoic@fesb.hr	
Personal web page	www.fesb.hr/~rgoic	
Year of birth	1969.	
Scientist ID	207263	
Research or art rank, and date of last rank appointment	Senior scientific associate, 2011	
Research-and-teaching, art-and- teaching or teaching rank, and date of last rank appointment	Associate Professor, 2011	
Area and field of election into research or art rank	Technical Sciences, Field Electrical engineering	
INFORMATION ON CURRENT EMP	LOYMENT	
Institution where employed	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture	
Date of employment	1993	
Name of position (professor, researcher, associate teacher, etc.)	Professor	
Field of research	Transmission and distribution networks, Power system analysis, Energy economics	
Function	Head of Chair of Electrical Networks and Substations	
INFORMATION ON EDUCATION – H		
Degree	PhD	
Institution	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture	
Place	Split	
Date	11/July/2002	
INFORMATION ON ADDITIONAL TR		
Year	2002	
Place	Tokyo, Japan	
Institution	JICA	
Field of training	Energy efficiency	
MOTHER TONGUE AND FOREIGN		
Mother tongue	Croatian	
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	English (4)	
Foreign language and command of foreign language on a scale from 2		
(sufficient) to 5 (excellent) Foreign language and command of		
foreign language on a scale from 2		
(sufficient) to 5 (excellent) COMPETENCES FOR THE COURSE		
Earlier experience as course	Electrical matrix des (angles and lester). D'at " at a second	
teacher of similar courses (name	Electrical networks (undergraduate), Distribution networks	
title of course, study programme where it is/was offered, and level of study programme)	(undergraduate), Fundamentals of power engineering (undergraduate)	
Authorship of university/faculty textbooks in the field of the course		
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	 Sarajčev, Petar; Goić, Ranko: Assessment of the backflashover occurrence rate on HV transmission line towers, European transactions on electrical power (2011) Vasilj, Josip; Sarajcev, Petar; Goic, Ranko: Modeling of 	

	 current-limiting air-core series reactor for transient recovery voltage studies, Electric power systems research, 117 (2014) 3. Jakus, Damir; Goić, Ranko; Krstulović Opara, Jakov: The impact of wind power plants on slow voltage variations in distribution networks, Electric power systems research 81 (2011), 2 4. Parida, B.; Iniyan, S.; Goić, Ranko: A review of solar photovoltaic technologies, Renewable & sustainable energy reviews 15 (2011), 3 5. Goić, Ranko; Krstulović-Opara, Jakov; Jakus, Damir: Simulation of aggregate wind farm short-term production variations, Renewable energy 35 (2010), 11
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	 Development of mid-voltage distribution grid for next 20 years for Zadar county, 2014 Engineering studies (short circuit, load flow, overvoltage protection, earthing system). – basis for design of new submarine cable 110 kV Dugi rat – Postire and reconstruction of substation Dugi rat", 2014 Energy-economic analysis of construction of small HPP Peruća, 2013 Engineering studies (short circuit, load flow, overvoltage protection, earthing system) – basis for design of refurbishment of HPP Ozalj 1, 2013 Optimal technical solution for grid connection of refurbished HPP Zakučac 4x140 MW, 2013
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?-pedagoške kompetencije?	
PRIZES AND AWARDS, STUDENT	EVALUATION
Prizes and awards for teaching and scholarly/artistic work	
Results of student evaluation taken in the last five years for the course that is comparable to the course described in the form (evaluation organizer, average grade, note on grading scale and course evaluated)	4,6/5

Lirat and loot name and title of	
First and last name and title of teacher	Tamara Grujić, Ph.D., Full Professor
	Introduction to machine learning
The course he/she teaches in the	Linear Control Systems
proposed study programme	Practicum of Automatic Control
GENERAL INFORMATION ON COL	
Address	Dinka Šimunovića 5, 21000, Split
Telephone number	++38591-4305-642
E-mail address	tamara.grujic@fesb.hr
Personal web page	
Year of birth	1973.
Scientist ID	248770
Research or art rank, and date of	
last rank appointment	Scientific Adviser, 06. June, 2013.
Research-and-teaching, art-and-	
teaching or teaching rank, and	Full Professor, 23. Februar, 2017.
date of last rank appointment	
Area and field of election into	Taskainal Osianana, Field Flagting and a site
research or art rank	Technical Sciences, Field Electrical engineering
INFORMATION ON CURRENT EMI	PLOYMENT
	Faculty of Electrical Engineering, Mechanical Engineering
Institution where employed	and Naval Architecture – FESB, University of Split
Date of employment	01. September, 2000.
Name of position (professor,	
researcher, associate teacher,	Professor
etc.)	
Field of research	Electrical Engineering, Biomedical Engineering
Function	Head of Chair of Automatic Control and Systems
INFORMATION ON EDUCATION -	Highest degree earned
Degree	Dr. sc. (Ph.D.)
Institution	Faculty of Electrical Engineering, University of Ljubljana,
Institution	Faculty of Electrical Engineering, University of Ljubljana, Slovenia
Place	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia
	Faculty of Electrical Engineering, University of Ljubljana, Slovenia
Place	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006.
Place Date INFORMATION ON ADDITIONAL T	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during
Place Date	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING
Place Date INFORMATION ON ADDITIONAL T	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia
Place Date INFORMATION ON ADDITIONAL T Year Place	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia Faculty of Electrical Engineering, University of Ljubljana,
Place Date INFORMATION ON ADDITIONAL T Year	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia Faculty of Electrical Engineering, University of Ljubljana, Slovenia
Place Date INFORMATION ON ADDITIONAL T Year Place	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia Faculty of Electrical Engineering, University of Ljubljana,
Place Date INFORMATION ON ADDITIONAL T Year Place Institution Field of training	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia Faculty of Electrical Engineering, University of Ljubljana, Slovenia Electrical Engineering, Biomedical Engineering
Place Date INFORMATION ON ADDITIONAL T Year Place Institution Field of training Year	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia Faculty of Electrical Engineering, University of Ljubljana, Slovenia Electrical Engineering, Biomedical Engineering 2003.g. (three months stay)
Place Date INFORMATION ON ADDITIONAL T Year Place Institution Field of training	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia Faculty of Electrical Engineering, University of Ljubljana, Slovenia Electrical Engineering, Biomedical Engineering 2003.g. (three months stay) Reading, UK
Place Date INFORMATION ON ADDITIONAL T Year Place Institution Field of training Year	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia Faculty of Electrical Engineering, University of Ljubljana, Slovenia Electrical Engineering, Biomedical Engineering 2003.g. (three months stay) Reading, UK University of Reading, Department of Cybernetics, School of
Place Date INFORMATION ON ADDITIONAL T Year Place Institution Field of training Year Place	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia Faculty of Electrical Engineering, University of Ljubljana, Slovenia Electrical Engineering, Biomedical Engineering 2003.g. (three months stay) Reading, UK
Place Date INFORMATION ON ADDITIONAL T Year Place Institution Field of training Year Place Institution Field of training Institution	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia Faculty of Electrical Engineering, University of Ljubljana, Slovenia Electrical Engineering, Biomedical Engineering 2003.g. (three months stay) Reading, UK University of Reading, Department of Cybernetics, School of Systems Engineering Biomedical Engineering
Place Date INFORMATION ON ADDITIONAL T Year Place Institution Field of training Year Place Institution Field of training Year Place Institution Field of training MOTHER TONGUE AND FOREIGN	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia Faculty of Electrical Engineering, University of Ljubljana, Slovenia Electrical Engineering, Biomedical Engineering 2003.g. (three months stay) Reading, UK University of Reading, Department of Cybernetics, School of Systems Engineering Biomedical Engineering
Place Date INFORMATION ON ADDITIONAL T Year Place Institution Field of training Year Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia Faculty of Electrical Engineering, University of Ljubljana, Slovenia Electrical Engineering, Biomedical Engineering 2003.g. (three months stay) Reading, UK University of Reading, Department of Cybernetics, School of Systems Engineering Biomedical Engineering
Place Date INFORMATION ON ADDITIONAL T Year Place Institution Field of training Year Place Institution Field of training Year Place Institution Field of training MOTHER TONGUE AND FOREIGN	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia Faculty of Electrical Engineering, University of Ljubljana, Slovenia Electrical Engineering, Biomedical Engineering 2003.g. (three months stay) Reading, UK University of Reading, Department of Cybernetics, School of Systems Engineering Biomedical Engineering
Place Date INFORMATION ON ADDITIONAL T Year Place Institution Field of training Year Place Institution Field of training Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia Faculty of Electrical Engineering, University of Ljubljana, Slovenia Electrical Engineering, Biomedical Engineering 2003.g. (three months stay) Reading, UK University of Reading, Department of Cybernetics, School of Systems Engineering Biomedical Engineering
Place Date INFORMATION ON ADDITIONAL T Year Place Institution Field of training Year Place Institution Field of training Mother tongue Foreign language and command of foreign language and command of science Year	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia Faculty of Electrical Engineering, University of Ljubljana, Slovenia Electrical Engineering, Biomedical Engineering 2003.g. (three months stay) Reading, UK University of Reading, Department of Cybernetics, School of Systems Engineering Biomedical Engineering LANGUAGES Croatian English language (5)
Place Date INFORMATION ON ADDITIONAL T Year Place Institution Field of training Year Place Institution Field of training Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	Faculty of Electrical Engineering, University of Ljubljana, Slovenia Ljubljana, Slovenia 24. November, 2006. RAINING Additional trainings (Visiting stays in total of 5 months, during the time period since 2003. to 2006.) Ljubljana, Slovenia Faculty of Electrical Engineering, University of Ljubljana, Slovenia Electrical Engineering, Biomedical Engineering 2003.g. (three months stay) Reading, UK University of Reading, Department of Cybernetics, School of Systems Engineering Biomedical Engineering

COMPETENCES FOR THE COURSE	
Earlier experience as course teacher of similar courses (name title of course, study programme where it is/was offered, and level of study programme)	 Signals and Systems, Undergraduate study programme, Multimedia Systems, Graduate study programme, Signals and Systems in Biomedical Engineering, Postgraduate (PhD) study programme
Authorship of university/faculty textbooks in the field of the course	 Faculty textbook for Linear Control Systems course: Tamara Grujić: "Linearni regulacijski sustavi – Predavanja sa zadacima", Interna skripta, FESB, Split, 2011. Faculty textbook for Practicum of Automatic Control
	course: Tamara Grujić: "Razvoj, izrada i testiranje tiskane pločice", Interna skripta, FESB, Split, 2008.
	Scientific papers published in international journals cited by CC or SCI-Expanded:
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	1. Grujić Tamara; Kuzmanić Skelin, Ana; Čić, Maja. Design, Development and Testing of a Low-Cost sEMG System and Its Use in Recording Muscle Activity in Human Gait. // <i>Sensors</i> . 14 (2014), 5; 8235-8258
	2. Kuzmanić Skelin, Ana; Grujić, Tamara; Bonković, Mirjana. Visual Peoplemeter: A Vision-based Television Audience Measurement System. // Advances in Electrical and Computer Engineering. 14 (2014), 4; 73-80
	3. Stančić, Ivo; Grujić, Tamara; Panjkota Ante. Design, Development, and Evaluation of Optical Motion- Tracking System Based on Active White Light Markers. // IET science measurement & technology. 7 (2013), 4; 206-214
	4. Stančić, Ivo; Grujić, Tamara; Bonković, Mirjana. New Kinematic Parameters for Quantifying Irregularities in the Human and Humanoid Robot Gait. // International Journal of Advanced Robotic Systems. 9 (2012) ; 215-1-215- 8
	5. Grujić Šupuk, Tamara; Bajd, Tadej; Kurillo, Gregorij. Assessment of Reach-to-Grasp Trajectories Toward Stationary Objects. // <i>Clinical biomechanics</i> . 26 (2011), 8; 811-818
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most) The name of the programme and	 Project: "Advanced Methods of 3D Visualization - Towards Virtual Tourism and Cultural Heritage Digitalization of Town of Split", 2015-2016. Tamara Grujić is project researcher. Project: Biomechanics of Human Movements, Control and Rehabilitation", 2007-2014. Tamara Grujić was project researcher. Program: Biomechanics of Human Movements – BioPok, 2007-2014. Tamara Grujić was project researcher. Tamara Grujić was project researcher.

the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?	(the year 2000) continuously lead a range of courses at The Undergraduate Study in Electrical Engineering and Information Technology, Undergraduate Study in Computer Science, Graduate Study in Automation and Systems, and Postgraduate (Ph.D.) Study in Electrical Engineering and Information Technology. Also, she is giving lectures as a visiting professor, at The Undergraduate Study of Physiotherapy, at the Department of Health Studies, University of Split, Croatia, and at The Faculty of Mechanical Engineering and Computer Science, University of Mostar, Bosnia and Herzegovina. Total so far she held more than 5,000 hours of lectures, auditory and laboratory exercises, as an research assistant (2000-2007), and as professor (2007 -)
PRIZES AND AWARDS	
Prizes and awards for teaching and scholarly/artistic work	
Results of student evaluation taken in the last five years for the course that is comparable to the	Results of student evaluation taken in the last five years for the course "Linear Control Systems": 4.76 / 5
course described in the form (evaluation organizer, average grade, note on grading scale and	Results of student evaluation taken in the last five years for the course "Practicum of Automatic Control": 4.72 / 5
course evaluated)	Evaluation organizer: University of Split

First and last name and title of	Toni Jakovčević, Ph.D., Assistant Professor
teacher	
The course he/she teaches in the	Computer systems
proposed study programme	
GENERAL INFORMATION ON COU	RSE TEACHER
Address	Getaldićeva 25, Split
Telephone number	0914305832
E-mail address	toni.jakovcevic@fesb.hr
Personal web page	http://laris.fesb.hr/toni.htm
Year of birth	1982
Scientist ID	292313
Research or art rank, and date of	Scientific associate, March 2014.
last rank appointment	
Research-and-teaching, art-and-	
teaching or teaching rank, and date	Assistant professor, May 2014.
of last rank appointment Area and field of election into	
research or art rank	Technical sciences, Field: Computer science
INFORMATION ON CURRENT EMP	
Institution where employed	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Data of omployment	2007.
Date of employment	2007. Professor
Name of position (professor, researcher, associate teacher, etc.)	FIDIESSO
Field of research	Computer science, Artificial intelligence
Function	
INFORMATION ON EDUCATION - H	Lighest degree earned
	Ph.D.
Degree	Faculty of Electrical Engineering, Mechanical Engineering and
Institution	Naval Architecture
Place	Split, Croatia
Date	10.1.2011.
INFORMATION ON ADDITIONAL TR	
Year	
Place	
Institution	
Field of training	
MOTHER TONGUE AND FOREIGN	
Mother tongue Foreign language and command of	Croatian English 5
foreign language on a scale from 2	ะแข่างกว
(sufficient) to 5 (excellent)	
Foreign language and command of	
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	
Foreign language and command of	
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	

COMPETENCES FOR THE COURS	=
Earlier experience as course	-
teacher of similar courses (name	
title of course, study programme	
where it is/was offered, and level of	
study programme)	
Authorship of university/faculty	
textbooks in the field of the course	
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	 Bugarić, Marin; Jakovčević, Toni; Stipaničev, Darko. Adaptive Estimation of Visual Smoke Detection Parameters Based on Spatial Data and Fire Risk Index. // Computer vision and image understanding. 118 (2014) ; 184-196 Jakovčević, Toni; Stipaničev, Darko; Krstinić, Damir. Visual spatial-context based wildfire smoke sensor. // Machine vision and applications. 24 (2013) , 4; 707-719 Bugarić, Marin; Jakovčević, Toni; Stipaničev, Darko. Computer Vision Based Measurement of Wildfire Smoke Dynamics. // Advances in Electrical and Computer Engineering. 15 (2015) , 1; 55-62 Stipaničev, Darko; Bugarić, Marin; Krstinić, Damir; Šerić, Ljiljana; Jakovčević, Toni; Braović, Maja; Štula, Maja. New generation of automatic ground based wildfire surveillance systems // Advances in forest fire research. Coimbra, Portugal : Imprensa da Universidade de Coimbra, 2014. 1455-1466 Stipaničev, Darko; Šerić, Ljiljana; Braović, Maja; Krstinić, Damir; Jakovčević, Toni; Štula, Maja; Bugarić, Marin; Maras, Josip. Vision Based Wildfire and Natural Risk Observers // Proc. of 3rd International Conference on Image Processing Theory, Tools and Applications, OS1: Special session on Image Processing for Natural Risks (IPNR) / Khalifa Djemal (France), Mohamed Deriche (KSA), Istanbul, 2012. P271
Professional and scholarly articles	
published in the last five years in	
subjects of teaching methodology	
and teaching quality (5 works at	
most)	
Professional, science and artistic	AgISEco – Agent-oriented intelligent systems for environmental
projects in the field of the course	survaillance and protection
carried out in the last five years (5 at most)	
The name of the programme and	
the volume in which the main	
teacher passed exams in/acquired	
the methodological-psychological-	
didactic-pedagogical group of	
competences?	
PRIZES AND AWARDS, STUDENT	EVALUATION
Prizes and awards for teaching and	
scholarly/artistic work Results of student evaluation taken in	
the last five years for the course that is	
comparable to the course described in	
the form (evaluation organizer, average	
grade, note on grading scale and	
course evaluated)	

First and last name and title of teacherDamir Krstinić, Ph.D., Associate ProfessorThe course he/she teaches in the proposed study programmeDigital image processing and analysis Modelling and control of vessels and ground vehiclesGENERAL INFORMATION ON COURSE TEACHER AddressSlobode 43, Split 21000	
The course he/she teaches in the proposed study programmeDigital image processing and analysis Modelling and control of vessels and ground vehiclesGENERAL INFORMATION ON COURSE TEACHER	
proposed study programme Modelling and control of vessels and ground vehicles GENERAL INFORMATION ON COURSE TEACHER	
GENERAL INFORMATION ON COURSE TEACHER	
Telephone number +385 (0) 21 305 895	
E-mail address damir.krstinic@fesb.hr	
Personal web page http://www.fesb.hr/~dkrst	
Year of birth 1975	
Scientist ID 248812	
Research or art rank, and date of senior research associate, 2011.	
last rank appointment	
Research-and-teaching, art-and- Associate professor, 25. 01. 2017.	
teaching or teaching rank, and	
date of last rank appointment	
Area and field of election into Computer science, Information systems	
research or art rank	
INFORMATION ON CURRENT EMPLOYMENT	
Institution where employed FESB, University of Split	
Date of employment 01. 02. 2000.	
Name of position (professor, Associate professor	
researcher, associate teacher,	
etc.)	
Field of research Computer science	
Function Associate professor	
INFORMATION ON EDUCATION – Highest degree earned	
Degree dr. sc.	
Institution FESB, University of Split	
Place Split	
Date 2008.	
INFORMATION ON ADDITIONAL TRAINING	
Year	
Place	
Institution	
Field of training	
MOTHER TONGUE AND FOREIGN LANGUAGES	
Mother tongue Croatian	
Foreign language and command of English 4	
foreign language on a scale from 2	
(sufficient) to 5 (excellent) Foreign language and command of Italian 2	
Foreign language and command of foreign language on a scale from 2	
(sufficient) to 5 (excellent)	
Foreign language and command of	
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	
COMPETENCES FOR THE COURSE	
Earlier experience as course teacher	
of similar courses (name title of course, study programme where it	
is/was offered, and level of study	
programme)	
Authorship of university/faculty	
textbooks in the field of the course	

	 Krstinić, Damir; Kuzmanić Skelin, Ana; Milatić, Ivan, Laser Spot Tracking Based on Modified Circular Hough Transform and Motion Pattern Analysis, Sensors, Vol. 14, no. 11, 2014., pp. 20112-20133 Jakovčević, Toni; Stipaničev, Darko; Krstinić, Damir, "Visual spatial-context based wildfire smoke sensor", Machine vision and applications (ISSN 1387-8092), Vol. 24(2013), No. 4, pp. 707-719, 2013. 	
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	 Šerić, Ljiljana; Krstinić, Damir; Braović, Maja; Milatić, Ivan; Mirčevski, Aljoša; Stipaničev, Darko, "Holonic Multi Agent System for Data Fusion in Vehicle Classification", in Proc. Of 10th KES International Conference, KES-AMSTA 2016.; pp- 151-161; Puerto de la Cruz, Tenerife, Spain, June 15 17. 2016. 	
	 Stipaničev, Darko; Šerić, Ljiljana; Krstinić, Damir; Bugarić, Marin, "Wildfire video observers network with phyisical an d virtual sensors", 10th EARSel Forest Special Interest Group Workshop – Sensors, Multi-Sensor Integration, Large Volumes: New Oportunities and Chalenges in Forest Fire Research, Limassol, Cyprus, November 2 5. 2015. 	
	 Štula, Maja; Krstinić, Damir; Šerić, Ljiljana, "Intelligent forest fire monitoring system", Information System Frontiers (ISSN 1387-3326), Vol. 14(2012), No. 3; pp- 725-739, 2012. 	
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)		
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)		
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological-didactic-pedagogical group of competences?		
PRIZES AND AWARDS, STUDEN	PRIZES AND AWARDS, STUDENT EVALUATION	
Prizes and awards for teaching and scholarly/artistic work		
Results of student evaluation	Digital image processing and analysis:	
taken in the last five years for the	 2015/2016 – overall average 4.7 	
course that is comparable to the	 2014/2016 – overall average 4.6 	
course described in the form	 2013/2014 – overall average 4.6 	
(evaluation organizer, average	 2012/2013 – overall average 4.7 	
grade, note on grading scale and course evaluated)	• 2011/2012 – overall average 4.6	

First and last name and title of	
teacher	Ana Kuzmanić Skelin, Ph.D., Assistant Professor
The course he/she teaches in the	CAD in Automatic Control
proposed study programme	
GENERAL INFORMATION ON COU	
Address	R. Boškovića 32, 21 000 Split, HR
Telephone number	+385-91-4305-652
E-mail address	akuzmani@fesb.hr
Personal web page	
Year of birth	054000
Scientist ID	254392
Research or art rank, and date of	Research associate (Electrical Engineering), 11/7/2014
last rank appointment	Research associate (Computer Science), 6/11/2015
Research-and-teaching, art-and- teaching or teaching rank, and date	Assistant professor 11/6/2016
of last rank appointment	Assistant professor, 14/6/2016
Area and field of election into	Technical Sciences, Field Electrical engineering
research or art rank	Technical Sciences, Field Computer Science
INFORMATION ON CURRENT EMP	
Institution where employed	Faculty of Electrical Engineering, Mechanical Engineering and
manution where employed	Naval Architecture
Date of employment	15/6/2002
Name of position (professor,	Assistant professor
researcher, associate teacher, etc.)	
Field of research	control systems, computer vision, adaptive learning methods
Function	
INFORMATION ON EDUCATION - H	Highest degree earned
Degree	PhD
Institution	Faculty of Electrical Engineering, Mechanical Engineering and
	Naval Architecture
Place	Split
Date	4/7/2013
INFORMATION ON ADDITIONAL TR	RAINING
Year	2006
Place	Surrey, UK
Institution	Centre for Vision, Speech and Signal Processing
Field of training	Wide-baseline image correspondences
MOTHER TONGUE AND FOREIGN	LANGUAGES
Mother tongue	Croatian
Foreign language and command of	English (5)
foreign language on a scale from 2	/
(sufficient) to 5 (excellent)	
Foreign language and command of	German (3)
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	
Foreign language and command of	
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	

COMPETENCES FOR THE COURSE	
Earlier experience as course teacher of similar courses (name title of course, study programme where it is/was offered, and level of study programme)	Nonlinear Control Systems, Graduate study program Automatic Control, Undergraduate professional study program
Authorship of university/faculty textbooks in the field of the course	Automatika - upute za laboratorijske vježbe, Interna skripta, FESB Split
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	 Grujić Tamara; Kuzmanić Skelin, Ana; Čić, Maja, Design, Development and Testing of a Low-Cost sEMG System and Its Use in Recording Muscle Activity in Human Gait. // Sensors. 14 (2014), 5; 8235-8258 Ante Palac; Ana Kuzmanić Skelin; Mirjana Bonkovic, Design and Development of a Low-Cost Hen Eggs Incubator// Proc. of the 1st International Multidisciplinary Conference on Computers and Energy Science, SpliTech, 2016
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	Biomehanika ljudskih pokreta, upravljanje i rehabilitacija, 023- 0232006-1655, 2007-2014., MZOŠ
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?	
PRIZES AND AWARDS, STUDENT EVALUATION	
Prizes and awards for teaching and scholarly/artistic work	
Results of student evaluation taken in the last five years for the course that is comparable to the course described in the form (evaluation organizer, average grade, note on grading scale and course evaluated)	4,8 (grading scale: 1-5); Nonlinear control systems

First and last name and title of	
teacher	Ivan Marasović, Ph.D., Assistant Professor
The course he/she teaches in the	Solar cells
proposed study programme	Computer aided process control
GENERAL INFORMATION ON COU	
Address	Jurja Šižgorića 14, 21000 Split
Telephone number	+385 21 305826
E-mail address	Ivan Marasovic@fesb.hr
Personal web page	
Year of birth	1983.
Scientist ID	297561
Research or art rank, and date of	Assistant research fellow, 07.07.2015.
last rank appointment	
Research-and-teaching, art-and-	
teaching or teaching rank, and date	Assitant professor, 01.10.2015.
of last rank appointment Area and field of election into	Technical Sciences, Field electrical Engineering, Branch
research or art rank	Electronics
INFORMATION ON CURRENT EMP	
Institution where employed	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Date of employment	01/09/2007
Name of position (professor,	Professor
researcher, associate teacher, etc.)	
Field of research	Electronics, Micro and nano electronics, Solar cells and
Function	photovoltaics, Embedded systems
INFORMATION ON EDUCATION - I	
Degree	PhD Foculty of Electrical Engineering, Machanical Engineering and
Institution	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Place	Split
Date	11/05/2012
INFORMATION ON ADDITIONAL TR	•
Year	2011. (1 weeks)
Place	Freiburg, Germany
Institution	Fraunhofer ISE
Field of training	Photovoltaics
Year	2011. (2 weeks)
Place	Ljubaljana, Slovenia
Institution	Fakultet za elektrotehniko
Field of training	Semiconductor nanoelectronics
MOTHER TONGUE AND FOREIGN	LANGUAGES
Mother tongue	Croatian
Foreign language and command of	English (4)
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	
Foreign language and command of	
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	
Foreign language and command of	
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	

COMPETENCES FOR THE COURS	COMPETENCES FOR THE COURSE	
Earlier experience as course teacher of similar courses (name title of course, study programme where it is/was offered, and level of study programme)	Electronic devices and circuits, Undergraduate study of Electrical Engineering and Information Technology Basic electronics, Undergraduate study in Computing Digital instrumentation 1, Undergraduate study of Control Engineering and Automation, Electronic and Computer Engineering and Communication	
Authorship of university/faculty textbooks in the field of the course		
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	 L. Mainetti, I. Marasović, L. Patrono, P. Šolić, M.L. Stefanizzi, R. Vergallo "A Novel IoT-aware Smart Parking System based on the integration of RFID and WSN technologies., (2016), 833257 I. Marasović, Ž. Milanović, I. Zulim, "Modelling and detection of failure in medical electrodes", (2015), 789296 S. Nižetić, I. Marasović, D. Čoko, "Experimental study on a hybrid energy system with small-and medium-scale applications for mild climates., (2014), 694087 I. Marasović, Ž. Milanović, T. Betti, "Resistance Fluctuations in GaAs Nanowire Grids", Journal of Nanomaterials, (2014), 428390 I. Marasović, T. Garma, T. Betti, "Modelling a nanowire grid for light- sensing applications", Journal of Physics D: Applied Physics 45 (2012) 	
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)		
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)		
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences		
	PRIZES AND AWARDS, STUDENT EVALUATION	
Prizes and awards for teaching and scholarly/artistic work Results of student evaluation taken in the last five years for the course that is comparable to the course described in the form (evaluation organizer, average grade, note on grading scale and course evaluated)	4,0	

First and last name and title of teacher	Jadranka Marasović, Ph.D., Full Professor
	Multivariable control
The course he/she teaches in the	Operations Research
proposed study programme	Process Control Laboratory
proposed study programme	System Identification
GENERAL INFORMATION ON COU	
Address	Split, Zagrebačka 21
Telephone number	385 021 305 830 (institution)
E-mail address	jmar@fesb.hr
Personal web page	1
Year of birth	1955.
Scientist ID	080633
Research or art rank, and date of last rank appointment	Senior Research Scientist, 09. July 2007.
Research-and-teaching, art-and-	
teaching or teaching rank, and date	Full professor, 01. March 2009.
of last rank appointment	
Area and field of election into	Technical science, field of electrical engineering
research or art rank	recifical science, field of electrical engineering
INFORMATION ON CURRENT EMP	LOYMENT
Institution where employed	Faculty of Electrical Engineering, Machine Engineering and
	Naval Architecture, University of Split
Date of employment	04. May 1978.
Name of position (professor,	Professor
researcher, associate teacher, etc.)	
Field of research	Science and Education
Function	1
INFORMATION ON EDUCATION - H	lighest degree earned
Degree	Doctor of science
Institution	Faculty of Electrical Engineering, Machine Engineering and
	Naval Architecture, University of Split
Place	Split
Date	11. July 1997.
INFORMATION ON ADDITIONAL TR	
Year	
Place	
Institution	
Field of training	
MOTHER TONGUE AND FOREIGN	
Mother tongue	Croatian
Foreign language and command of	English (availlant E)
foreign language on a scale from 2	English (excellent -5)
(sufficient) to 5 (excellent)	
Foreign language and command of	Italian (aufficient 2)
foreign language on a scale from 2	Italian (sufficient-2)
(sufficient) to 5 (excellent)	
Foreign language and command of	
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	

COMPETENCES FOR THE COURSE	
	Undergraduate studies: Measurements and Process Control
	Industrial Process Control
	Graduate studies:
Earlier experience as course	Automatic ControlSystem Identification
teacher of similar courses (name	Process Control Laboratory
title of course, study programme where it is/was offered, and level of	Optimization Methods
study programme)	 Operations Research Automation
	Postgraduate study:
	 Optimization Techniques for Environmental Studies
	(Wessex Institute of Tecnology, UK i FESB)
	Game theory and optimization methods (FESB)
	 Complex systems modelling and simulation (FESB) (autor) Kvantitativno i kvalitativno modeliranje i simuliranje
	(Quantitative and Qualitative Modelling and Simulation) (
	ISBN 953-6114-67-4), - (koautor) On-line (web) udžbenik, Informatički projekt MZT-
Authorship of university/faculty	a, http://laris.fesb.hr/digitalno_vodjenje (Digital Control)
textbooks in the field of the course	- (autor) Predavanja iz kolegija Metode optimizacije
	 (Lessons for Optimizaion Methods) (FESB, e-learning). (autor) Predavanja iz kolegija Modeliranje i simuliranje
	sustava (Lessons for Modelling and Simulations) (FESB, e-
	 learning). Marasović, Tea; Papić, Vladan; Marasović, Jadranka.
	Motion-based Gesture Recognition Algorithms for Robot
	Manipulation. // International Journal of Advanced Robotic Systems. 12 (2015), 51; 1-13, doi: 10.5772/60077.
	- Marasović, Jadranka; Marasović, Tea; Đapić, Marija. Fair
Professional, scholarly and artistic articles published in the last five	Division Methods Approach as the Option of Learning Process Modeling. // Proceedings of 18th IEEE
years in the field of the course (5	International Symposium on Computers and
works at most)	Communications (ISCC). 2013; 735-739. - Mance, Davor; Marasović, Jadranka . <i>EMC in Electronic</i>
	System Developed to Support Measurements in Space
	Environment. // Proceedings of 20th International Conference on Software, Telecommunications and
	Computer Networks (SoftCOM). 2012; 1-5.
Professional and scholarly articles	
published in the last five years in subjects of teaching methodology	
and teaching quality (5 works at most)	
	Associated member in scientific projects:
	 Računalna inteligencija za prepoznavanje i potporu ljudskih aktivnosti (RIPrePAkt),
Professional, science and artistic	- GRS Front End Electronics Characterization for LISA,
projects in the field of the course	- Agentski orijentirani inteligentni sustavi za nadzor i zaštitu
carried out in the last five years (5 at most)	okoliša (Agents Oriented Intelligent Systems for Environment Control and Protection),
	- Inteligentni agenti u modeliranju i vođenju kompleksnih
	sustava (Intelligent Agents used for Complex Systems Modelling and Control),
	wodening and Control),

	 Vođenje složenih sustava inteligentnim metodama (Intelligent Methods for Complex Systems Control).
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?	
PRIZES AND AWARDS, STUDENT	EVALUATION
Prizes and awards for teaching and scholarly/artistic work	/
Results of student evaluation taken in the last five years for the course that is comparable to the course described in the form (evaluation organizer, average grade, note on grading scale and course evaluated)	

First and last name and title of	
First and last name and title of teacher	Ivan Marinović, Ph.D., Full Professor
The course he/she teaches in the proposed study programme	Electronic circuits
GENERAL INFORMATION ON COL	IRSE TEACHER
Address	Butor dolac 13, 21405 Milna, o. Brač
Telephone number	098 1835911
E-mail address	imarin@fesb.hr
Personal web page	www.fesb.hr/~imarin
Year of birth	1966.
Scientist ID	200263
Research or art rank, and date of	
last rank appointment	Scientific Advisor, 20.06.2016.
Research-and-teaching, art-and- teaching or teaching rank, and	Full Professor, 15.07.2016.
date of last rank appointment Area and field of election into	
research or art rank	Technical Sciences, Electrical Engineering
INFORMATION ON CURRENT EMP	
Institution where employed	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture – Split
Date of employment	21.02.1991.
Name of position (professor,	Professor
researcher, associate teacher,	
etc.)	
Field of research	Electronics, Radiocommunications
Function	Head of Cathedra for Radiocommunication Circuits and Systems
INFORMATION ON EDUCATION -	Highest degree earned
Degree	PhD
Institution	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture – Split
Place	Split
Date	12.05.2005.
INFORMATION ON ADDITIONAL T	
Year	
Place	
Institution	
Field of training	
MOTHER TONGUE AND FOREIGN	LANGUAGES
Mother tongue	Croatian
Foreign language and command of	
foreign language on a scale from 2	English (4)
(sufficient) to 5 (excellent)	
Foreign language and command of	
foreign language on a scale from 2	Italian (4)
(sufficient) to 5 (excellent)	
Foreign language and command of	
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	

COMPETENCES FOR THE COURSEEarlier experience as course teacher of similar courses (name title of course, study programme where it is/was offered, and level of study programme)Electronic Circuits and Measurements, Graduate study programme)Authorship of university/faculty textbooks in the field of the courseMarinović, Ivan; Čoko, Duje, Electronički sklopovi-Upute za laboratorijske vježbe, FESB-SplitProfessional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)Marinović, Ivan; Čoko, Duje, Electronički sklopovi-Upute za laboratorijske vježbe, FESB-Split
teacher of similar courses (name title of course, study programme where it is/was offered, and level of study programme)Electronic Circuits and Measurements, Graduate study programmeAuthorship of university/faculty textbooks in the field of the courseMarinović, Ivan; Čoko, Duje, Electronički sklopovi-Upute za laboratorijske vježbe, FESB-SplitProfessional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)Marinović, Ivan; Čoko, Duje, Electronički sklopovi-Upute za laboratorijske vježbe, FESB-SplitProfessional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works atFestival
title of course, study programme where it is/was offered, and level of study programme)programmeAuthorship of university/faculty textbooks in the field of the courseMarinović, Ivan; Čoko, Duje, Electronički sklopovi-Upute za laboratorijske vježbe, FESB-SplitProfessional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)Marinović, Ivan; Čoko, Duje, Electronički sklopovi-Upute za laboratorijske vježbe, FESB-SplitProfessional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works atFestival
where it is/was offered, and level of study programme) Marinović, Ivan; Čoko, Duje, Electronički sklopovi-Upute za laboratorijske vježbe, FESB-Split Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most) Marinović, Ivan; Čoko, Duje, Electronički sklopovi-Upute za laboratorijske vježbe, FESB-Split Professional and scholarly and artistic auticles published in the last five years in the field of the course (5 works at most) Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at
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Authorship of university/faculty textbooks in the field of the course Marinović, Ivan; Čoko, Duje, Electronički sklopovi-Upute za laboratorijske vježbe, FESB-Split Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most) Marinović, Ivan; Čoko, Duje, Electronički sklopovi-Upute za laboratorijske vježbe, FESB-Split Professional and scholarly and artistic published in the last five years in subjects of teaching methodology and teaching quality (5 works at Marinović, Ivan; Čoko, Duje, Electronički sklopovi-Upute za laboratorijske vježbe, FESB-Split
textbooks in the field of the course Iaboratorijske vježbe, FESB-Split Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most) Iaboratorijske vježbe, FESB-Split Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at Iaboratorijske vježbe, FESB-Split
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most) Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at
articles published in the last five years in the field of the course (5 works at most) Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at
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Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at
published in the last five years in subjects of teaching methodology and teaching quality (5 works at
subjects of teaching methodology and teaching quality (5 works at
and teaching quality (5 works at
most
Professional, science and artistic
projects in the field of the course
carried out in the last five years (5
at most)
The name of the programme and
the volume in which the main
teacher passed exams in/acquired
the methodological-psychological-
didactic-pedagogical group of
competences
PRIZES AND AWARDS, STUDENT EVALUATION
Prizes and awards for teaching
and scholarly/artistic work
Results of student evaluation taken 4.8
in the last five years for the course
that is comparable to the course
described in the form (evaluation
organizer, average grade, note on
grading scale and course
evaluated)

Ivo Mateljan, Ph.D., Full Professor
Electronic and virtual instrumentation
RSE TEACHER
J. Rodina 4, 21215 Kaštel Lukšić
+395 21 305 860
ivo.mateljan@fesb.hr
marjan.fesb.hr/~mateljan/
1953
76394
Scientific Adviser, 2007
Senior Full Professor, 2011
Technical Sciences, Electrical engineering
LOYMENT
Faculty of Electrical Engineering, Mechanical Engineering and
Naval Architecture
1/1/1977
Professor
Programming, Virtual Instrumentation, Electroacoustics
Head of Electroacoustic Laboratory
lighest degree earned
PdD
University of Zagreb, Faculty of Electrical Engineering
Zagreb, Croatia
1992.
AINING
LANGUAGES
Croatian
English (4)
E
Programming, OOP, Electronic circuit
Ivo Mateljan: Programiranje jezikom C, book published by University of Split, 2010.
Ivo Mateljan: Electronic and Virtual Instrumentation, FESB, internal script,, 2004

	1. Sikora, Marjan; Mateljan, Ivo.: A Method for Speeding up Beam-tracing Simulation Using Thread-level Parallelization. // Engineering with computers. 30 , 2014.
	2. Sikora M., Mateljan I., Bogunovic, N.: <i>Beam Tracing with Refraction,</i> Archives of Acoustics Vol.37, 2012.
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	3. Mateljan I., Sikora M.: <i>Estimation of loudspeaker drivers parameters</i> , Proc. of 5th Congress of the Alps Adria Acoustics Association Zadar, 2012.
	 4. Slamka M., Mateljan I., Howes M.: Virtual Surround for Headphones and Earbuds Headphone Externalization System, US patent 8270616, US class: 381/17; 381/1; 381/309, Assignee: Logitech Europe S.A., Sept. 18,2012.
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	Ivo Mateljan: ARTA software, Artalabs, 2004-2017.
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?-pedagoške kompetencije?	
PRIZES AND AWARDS, STUDENT	EVALUATION
Prizes and awards for teaching and scholarly/artistic work	
Results of student evaluation taken in the last five years for the course that is comparable to the course described in the form (evaluation organizer, average grade, note on	4.6/5
grading scale and course evaluated)	

First and last name and title of teacher	Daniela Matić, Ph.D., Assistant Professor
The course he/she teaches in the proposed study programme	English Language for Academic Purposes
GENERAL INFORMATION ON COU	
Address	Matice hrvatske 23, 21000 Split
Telephone number	098/ 1766010
E-mail address	daniela.matic@fesb.hr
Personal web page	/
Year of birth	1967
Scientist ID	332846
Research or art rank, and date of last rank appointment	1
Research-and-teaching, art-and- teaching or teaching rank, and date	Assistant professor; January 23, 2013
of last rank appointment	
Area and field of election into research or art rank	Humanities; philology
INFORMATION ON CURRENT EMP	
Institution where employed	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Date of employment	November 11, 2005
Name of position (professor,	English teacher
researcher, associate teacher, etc.)	Ŭ
Field of research	ESP, pragmatics, discourse analysis, contact linguistcs
Function	
INFORMATION ON EDUCATION - H	Highest degree earned
Degree	Ph.D.
Institution	Faculty of Humanities and Social Sciences, University of Zagreb
Place	Zagreb
Date	December 12, 2011
INFORMATION ON ADDITIONAL TR	
Year Place	1998 Barnstaple, Velika Britanija
Institution	Services for Open Learning, Barnstaple, Inservice Course in Teacher Training
Field of training	English language teaching methodology
Year	2002.
Place	Gyula, Hungary
Institution	A.S.Hornby International Trust, British Council, "Teaching English through Culture"
Field of training	English language teaching methodology
Year	2003
Place	Krakow, Poland
Institution	A.S.Hornby International Trust, British Council, "Intercultural Studies on the Web: Methodology and Materials"
Field of training	English language teaching methodology
MOTHER TONGUE AND FOREIGN	
Mother tongue	Croatian
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	English; 5
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	French; 5

Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	Italian; 3
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent	German; 2
COMPETENCES FOR THE COURS	E
Earlier experience as course teacher of similar courses (name title of course, study programme where it is/was offered, and level of study programme)	 Course teacher of : English Language 1, 2 and 3 courses at undergraduate studies of Computer Science, Electrical Engineering and IT and Naval Architecture; English Language 1 and 2 courses at professional studies of Computer Science, Electrical Engineering and IT and Naval Architecture; English Language for Academic purposes at graduate studies of Mechanical Engineering.
Authorship of university/faculty textbooks in the field of the course	/
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	 Matić, Daniela. (2012). Zamjenice u hrvatskim političkim govorima. <i>Filolog: časopis za jezik, književnost i kulturu</i>. V/2012, Univerzitet u Banjoj Luci, Filološki fakultet, ISSN 1986- 5864. Matić, Daniela. (2012). Jezične igre moći u drami Who's Afraid of Virginia Woolf? Edwarda Albeeja. <i>LINGUA</i> <i>MONTENEGRINA časopis za jezikoslovna, književna i kulturna pitanja</i>, god. V/2, br. 10. (2012). Podgorica: Institut za crnogorski jezik i književnost. ISSN 1800-7007. Matić, Daniela. (2012). Ideological Discourse Structures in Political Speeches. <i>Komunikacija i kultura online. Elektronski časopis za jezik, komunikacija i kultura online. Elektronski časopis za jezik, komunikacija i kulturu</i>. Godina III. Broj 3. http://www.komunikacijaikultura.org/KK3.html Beograd: FOKUS – Forum za interkulturnu komunikaciju. e-ISSN 2217-4257 (Online) UDC 8:008:316.7 Matić, Daniela. (2013). Pronouns in American Political Speeches. <i>LINGUA MONTENEGRINA časopis za jezikoslovna, književna i kulturna pitanja</i>, god. VI/1 br. 11. (2013). Podgorica: Institut za crnogorski jezik i književnost. ISSN 1800-7007. Matić, Daniela, Nataša Stojan. (2013). Rodne oznake u oglasima za posao. Kroz jezike i kulture ; Across Languages and Cultures - <i>Zbornik radova sa Treće međunarodne konferencije Institut za strane jezike (ICIFL3) i Treće međunarodne konferencije o interkulturnoj komunikaciji / Lakić, Igor ; Kostić, Nataša (ur.) Podgorica : Institut za strane jezike / Institute of Foreign Languages, 2013. 59-69 ISBN: 978-86- 85263-10-1.</i> Matić, Daniela. (2014). Ideology Hidden in the Form of Croatian and American Political Speeches. <i>Teme. Časopis za društvene nauke</i>. Br.3 (2014). Niš: Univerzitet u Nišu. ISSN 0353-7919.

Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	 Matić, Daniela. (2014). Attitudes of computer science students to the English element in Croatian ICT magazines. <i>ESP Today. Journal of English for Specific Purposes at Tertiary</i> <i>Level.</i> Volume 2, Issue 2 (2014). http://www.esptodayjournal.org/index.html e-ISSN 2334-9050. Matić, Daniela. (2015). Percepcija hrvatskih studenata računarstva o prihvatljivosti engleskoga elementa u glagolima, glagolskim imenicama i jukstaponiranim leksičkim segmentima u hrvatskim tekstovima iz područja računalnih i komunikacijskih tehnologija. <i>Od teorije do prakse u jeziku struke - Zbornik radova s 3.</i> <i>stručno-znanstvenog skupa Udruge nastavnika jezika struke na visokoškolskim ustanovama.</i>/ Cigan, Vesna; Omrčen, Darija (ur.) – Zagreb: Udruga nastavnika jezika struke na visokoškolskim ustanovama, 2015. 65-81.
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	Students' attitudes toward the English element in ICT terminology
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?-pedagoške kompetencije?	Regular four-year studies of the English language and literature and the French language and literature at Zagreb University.
PRIZES AND AWARDS, STUDENT EVALUATION	
Prizes and awards for teaching and scholarly/artistic work	/
Results of student evaluation taken in the last five years for the course that is comparable to the course described in the form (evaluation organizer, average grade, note on grading scale and course evaluated)	Positive

First and last name and title of	Josip Musić, Ph.D., Assistant Professor	
teacher The course he/she teaches in the		
proposed study programme	Telemedicine and Biocybernetics	
GENERAL INFORMATION ON COU		
Address	Ruđera Boškovića 32, Split	
Telephone number	+ 385 (0)21 305 829	
E-mail address	jmusic@fesb.hr	
Personal web page	http://marjan.fesb.hr/~jmusic	
Year of birth	1980	
Scientist ID	272932	
Research or art rank, and date of last rank appointment	Senior research associate (February 2013)	
Research-and-teaching, art-and-		
teaching or teaching rank, and date of last rank appointment	Assistant professor (July 2014)	
Area and field of election into research or art rank	Technical sciences, Electrical engineering	
INFORMATION ON CURRENT EMPLOYMENT		
Institution where employed	Faculty of electrical engineering, mechanical engineering and naval architecture, University of Split	
Date of employment	September 2014	
Name of position (professor, researcher, associate teacher, etc.)	Assistant professor	
Field of research	Robotics and automatization	
Function	1	
INFORMATION ON EDUCATION -	Highoet degree earned	
	PhD	
Degree Institution	Faculty of electrical engineering, mechanical engineering and	
	naval architecture, University of Split	
Place	Split	
Date	28.04.2010.	
INFORMATION ON ADDITIONAL TRAINING		
Year	2012	
Place	Glasgow, Scotland, UK	
Institution	School of Computing, University of Glasgow	
Field of training	human-computer interaction (HCI), signal processing	
Year	2008	
Place	Glasgow, Scotland, UK	
Institution	Department of Computing, University of Glasgow	
Field of training	human-computer interaction (HCI), signal processing	
Year	2005.	
Place	Ljubljana, Slovenia	
Institution	Faculty of electrical engineering, University of Ljubljana	
Field of training	robotics, biomechanics	
MOTHER TONGUE AND FOREIGN		
Mother tongue	Croatian	
Foreign language and command of	English (5)	
foreign language on a scale from 2		
(sufficient) to 5 (excellent)		
Foreign language and command of	Italian (2)	
foreign language on a scale from 2 (sufficient) to 5 (excellent)		
COMPETENCES FOR THE COURSE		
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Earlier experience as course teacher of similar courses (name title of course, study programme where it is/was offered, and level of study programme)	Automation (412/512), Automatic control 2 (910,11), Digital electronics (110), Digital control (210), Sensors and transducers (512), Biomechanics Practicum (412/512), Programing mobile robots and drones (221/222/242/250), Computer methods in biomechanics (111), Computers and computer methods in biomechanics (310/330), Telemedicine and biocybernetics (210/220/242)m Introduction to system theory (330)	
Authorship of university/faculty textbooks in the field of the course	M. Bonković, J. Musić, I. Stančić, Microcontrollers and embedded network systems based on Arduino development environment, faculty script, 2014	
	 Musić, Josip; Bonković, Mirjana; Cecić, Mojmil: "Comparison of uncalibrated model-free visual servoing methods for small amplitude movement: a simulation study", International Journal of Advanced Robotic Systems, 2014 (DOI: dx.doi.org/10.5772/58822) Stančić, Ivo; Musić, Josip; Cecić, Mojmil: "A Novel Low- Cost Adaptive Scanner Concept for Mobile Robots", Ingenieria e Investigacion, 34 (2014), 3; 37-43 	
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	3. Stančić, Ivo; Musić, Josip; Zanchi, Vlasta: "Improved structured light 3D scanner with application to anthropometric parameter estimation", Measurement, 46 (2013), 1; 716-726	
	4. Musić, Josip; Cecić, Mojmil; Zanchi, Vlasta: "Real-time body orientation estimation based on two-layer stochastic filter architecture", Automatika : časopis za automatiku, mjerenje, elektroniku, računarstvo i komunikacije, 51 (2010), 3; 264-274	
	5. Musić, Josip; Murray-Smith, Roderick: "Virtual Hooping: teaching a phone about hula-hooping for Fitness, Fun and Rehabilitation", Proceedings of Mobile Human Computer Interaction (MobileHCI) 2010. 309-312	
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)		
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	1. Compressive sensing and super-resolution in surveillance systems based on optical sensors and UAVs, 2015-2017, Bilateral Croatia-Montenegro cooperation, project lead	
	2. Supervised and unsupervised learning from imbalanced datasets for assistance in movement of persons with low vision, 2014-2015, Bilateral Croatia-Slovenia cooperation, project lead	
	3. Prototyping a module for automatization of industrial floor scrubbers, 2014-2016, Split-Dalmatia county and Odabir d.o.o., project lead	
	4. Computer intelligence for classification and support of human activities, 2014 - , Faculty/University project, researcher	
	5. Biomechanics of human motion, control and rehabilitation, 2007-2014, Ministry of science, education and sports,	

	researcher
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?-pedagoške kompetencije?	/
PRIZES AND AWARDS, STUDENT EVALUATION	
Prizes and awards for teaching and scholarly/artistic work	/
Results of student evaluation taken in the last five years for the course that is comparable to the course described in the form (evaluation organizer, average grade, note on grading scale and course evaluated)	/

First and last name and title of	
teacher	Julije Ožegović, Ph.D., Full Professor
The course he/she teaches in the proposed study programme	Digital Systems Projecting
GENERAL INFORMATION ON COL	JRSE TEACHER
Address	Istarska 2, 21000 Split, HR
Telephone number	+385 21 305825
E-mail address	julije.ozegovic@fesb.hr
Personal web page	www.fesb.hr/~julije
Year of birth	1954.
Scientist ID	91795
Research or art rank, and date of last rank appointment	Scientific Advisor, 2008-03-12
Research-and-teaching, art-and- teaching or teaching rank, and date of last rank appointment	Senior Full Professor, 2013-09-15
Area and field of election into research or art rank	Technical Sciences, Field Electrical engineering
INFORMATION ON CURRENT EMP	PLOYMENT
Institution where employed	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Date of employment	1979-10-01
Name of position (professor, researcher, associate teacher, etc.)	Professor
Field of research	Digital electronics, Computer networks, Automata theory
Function	Head of Chair of Digital Systems and Computer Network
INFORMATION ON EDUCATION -	Highest degree earned
Degree	PhD
Institution	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Place	Split
Date	1998-02-27
INFORMATION ON ADDITIONAL T	RAINING
Year	
Place	
Institution	
Field of training	
MOTHER TONGUE AND FOREIGN	LANGUAGES
Mother tongue	Croatian
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	English (5)
COMPETENCES FOR THE COURS	;E
	Digital Electronics, Undergraduate study of Electrotechnics,
	2006/2007 - today
Earlier experience as course teacher of similar courses (name title of course, study programme where it is/was offered, and level of study programme)	Discrete systems and structures, Undergraduate study of Computing, 2006/2007 - today
	Computer Networks, Undergraduate study of Electrotechnics, 2006/2007 - today
	Computer Networks, Undergraduate study of Computing, 2006/2007 - today
	Digital Electronics, Graduate study of Electrotechnics (pre- Bologna), 1998/1999 -2006/2007

	Discrete systems and structures, Graduate study of Computing (pre-Bologna), 19982000/2001 - 2006/2007
	Computer Networks, Graduate study of Electrotechnics (pre- Bologna), 1998/1999 -2007/2008
	Computer Networks, Graduate study of Computing (pre- Bologna), 1998/1999 -2007/2008
Authorship of university/faculty textbooks in the field of the course	Julije Ožegović, Digitalna i mikroprocesorska tehnika, ISBN 953-6806-26-6, Split University, 2000, several editions Julije Ožegović, Digital electronics, Discrete systems and structures, elearning.fesb.hr, updated from 1998 Julije Ožegović, Computer Networks, elearning.fesb.hr, updated from 1998
	Kedžo, Ivan; Ožegović, Julije; Kristić, Ante: Contention Overhead — Adaptive Binary Priority Countdown protocol, SoftCOM 2013, ISBN 978-953-290-043-9
	Kristić, Ante; Ožegović, Julije; Kedžo, Ivan: Mathematical model of simplified Constrained Priority Countdown Freezing protocol, The 18th IEEE Symposium on Computers and Communications (ISCC'13), 2013, ISBN 978-1-4673-2711
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	Kristić, Ante; Ožegović, Julije; Kedžo, Ivan: Improved mathematical model of simplified Constrained Priority Countdown Freezing protocol, SoftCOM 2013, ISBN 978-953- 290-043-9
	Kristić, Ante; Ožegović, Julije; Kedžo, Ivan: Mathematical model of Constrained Priority Countdown Freezing Protocol, SoftCOM 2014, ISBN 978-9-5329-0052-1
	Ines Ramadza, Julije Ozegovic, Vesna Pekic: Class based tunnel exclusion router architecture, SoftCOM 2014, ISBN 978-9-5329-0052-1
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	 Media access mechanism modelling for wireless local networks (MAMM), FESB Split, od 2014. HGCAL - CERN CMS, from 2015.
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences	Me4CataLOgue – Teaching and administrative personnel training
PRIZES AND AWARDS, STUDENT	EVALUATION
Prizes and awards for teaching and scholarly/artistic work	Coauthor of awarded paper - ISCC conference 2013.
Results of student evaluation taken in the last five years for the course that is comparable to the course described in the form (evaluation organizer, average grade, note on grading scale and course evaluated)	4
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most) The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences PRIZES AND AWARDS, STUDENT Prizes and awards for teaching and scholarly/artistic work Results of student evaluation taken in the last five years for the course that is comparable to the course described in the form (evaluation organizer,	networks (MAMM), FESB Split, od 2014. 2. HGCAL - CERN CMS, from 2015. Me4CataLOgue – Teaching and administrative personnel training EVALUATION Coauthor of awarded paper - ISCC conference 2013.

First and last name and title of	
teacher	Vladan Papić, Ph.D., Full Professor
The course he/she teaches in the	Computer graphics
proposed study programme	Computer methods in bioengineering
GENERAL INFORMATION ON COU	
Address	Makarska 2, 21000 Split
Telephone number	(021) 305649
E-mail address	vpapic@fesb.hr
Personal web page	www.fesb.hr/~vpapic
Year of birth	1968
Scientist ID	227412
Research or art rank, and date of	Scientific Adviser, 20/4/2010
last rank appointment	
Research-and-teaching, art-and- teaching or teaching rank, and date	Soniar Full Professor 17/12/2015
of last rank appointment	Senior Full Professor, 17/12/2015
Area and field of election into	
research or art rank	Technical Sciences, Field Computer science
INFORMATION ON CURRENT EMP	IOYMENT
Institution where employed	Faculty of Electrical Engineering, Mechanical Engineering and
	Naval Architecture
Date of employment	1/7/20097
Name of position (professor,	Professor
researcher, associate teacher, etc.)	
Field of research	Computer Vision, Expert Systems
Function	Vice-dean for bussines
INFORMATION ON EDUCATION - H	lighest degree earned
Degree	PhD
Institution	Faculty of Electrical Engineering, Mechanical Engineering and
	Naval Architecture
Place	Split
Date	12/2/2002
INFORMATION ON ADDITIONAL TR	RAINING
Year	
Place	
Institution	
Field of training	
MOTHER TONGUE AND FOREIGN	
Mother tongue	Croatian
Foreign language and command of foreign language on a scale from 2	English (5)
(sufficient) to 5 (excellent)	
Foreign language and command of	
foreign language on a scale from 2	Italian (2)
(sufficient) to 5 (excellent)	
Foreign language and command of	
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	
COMPETENCES FOR THE COURS	
Earlier experience as course	Computers in technical systems (PMF, Informatika i tehnička
teacher of similar courses (name	kultura, Undergraduate study programme, 2002-2009.)
title of course, study programme	Electronics (PMF, Informatika i tehnička kultura, Undergraduate
where it is/was offered, and level of study programme)	study programme 2002 – 2009.) Systems theory (FESB, EIT, Undergraduate study programme,
	2009-), Computer graphics ((FESB, Computing, Undergraduate
	study programme, 2003-)
Authorship of university/faculty	V.Papić, Lectures in electronics, University textbook, 2005. (in
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textbooks in the field of the course	Croatian)
textbooks in the held of the course	V. Papić, Computer graphics, Faculty textbook, 2013. (in
	Croatian)
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	 J. Musić, T. Marasović, V. Papić, I. Orović, S. Stanković, Performance of compressive sensing image reconstruction for search and rescue, IEEE Geoscience and Remote Sensing Letters, Volume 13, Issue 11, November 2016, Pages 1739-1743. J. Musić, I. Orović, T. Marasović, V. Papić, S. Stanković, Gradient Compressive Sensing for Image Data Reduction in UAV Based Search and Rescue in the Wild, Mathematical Problems in Engineering, Volume 2016, 2016. I. Orović, V. Papić, C. Ioana, X. Li, S. Stanković, Compressive Sensing in Signal Processing: Algorithms and Transform Domain Formulations, Mathematical Problems in Engineering, Volume 2016, 2016. T. Marasović, V. Papić, V. Zanchi, LMNN metric learning and fuzzy nearest neighbour classifier for hand gesture recognition, Journal on Multimodal User Interfaces, Volume 9, Issue 3, 27 August 2015, Pages 211-221. T. Marasović, V. Papić, J. Marasović, Motion-based gesture recognition algorithms for robot manipulation, International journal of advanced robotic systems. 12 (2015), 51; 1-13.
Professional and scholarly articles	
published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	 »Technology transfer infrastructure in the Croatian Adriatic region« - TTAdria (IPA IIIc), 2013-2015. "Computer intelligence for recognition and support of human activities " (RIPrePAkt) (FESB), 2013 (lead researcher). "Search and rescue system prototype based on image processing " (FESB - Statim d.o.o.), 2014 (lead researcher) "Advanced methods of 3D virtualization – towards virtual turism and digitalization of cultural heritage" (FESB – Neir d.o.o.), 2015 (researcer). International bilateral project Croatia- "Compressive sensing and superresolution in surveillance systems based on optical sensors and UAVs ", Contract with MZOS RH and MZT Republike Crne Gore, 2015-2016. (researcher)
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?	
PRIZES AND AWARDS, STUDENT I	EVALUATION
Prizes and awards for teaching and	Mentor of best student (Marko Trninić) in field of social and
scholarly/artistic work	humanistic scienses (annual award HRZZ, 2010).
Results of student evaluation taken in the last five years for the course that is comparable to the course described in the form (evaluation organizer, average grade, note on grading scale and course evaluated)	4.7/5
First and last name and title of	

First and last name and title of teacher	Goran Petrović, Ph.D., Associate Professor
The course he/she teaches in the proposed study programme	Measurements and Signal Processing

GENERAL INFORMATION ON COU	
Address	Split, Ruđera Boškovića 32
Telephone number	+385 21 305 731
E-mail address	petrovic@fesb.hr
Personal web page	
Year of birth	1971
Scientist ID	248882
Research or art rank, and date of	Research scientist 19.12. 2012.
last rank appointment	
Research-and-teaching, art-and-	Associate professor 19.12. 2012.
teaching or teaching rank, and date	
of last rank appointment	
Area and field of election into	Technical sciences, electrical engineering
research or art rank	
INFORMATION ON CURRENT EMP	LOYMENT
Institution where employed	FESB
Date of employment	30. 03. 1998.
Name of position (professor,	professor
researcher, associate teacher, etc.)	
Field of research	Electrical and process measurement, Signal processing
Function	Head of Department for power engineering
INFORMATION ON EDUCATION - H	Highest degree earned
Degree	PhD
Institution	FESB
Place	Split
Date	24. 03. 2006.
INFORMATION ON ADDITIONAL TR	AINING
Year	
Place	
Institution	
Field of training	
MOTHER TONGUE AND FOREIGN	
Mother tongue	Croatian
Foreign language and command of	English; very good (4)
foreign language on a scale from 2 (sufficient) to 5 (excellent)	
Foreign language and command of	
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	
Foreign language and command of	
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	
COMPETENCES FOR THE COURS	
Earlier experience as course teacher of similar courses (name	 Measurement and signal processing, Electrical engineering, graduate
title of course, study programme	2. Process measurement, Electrical engineering, graduate
where it is/was offered, and level of	3. Instrumentation in electrical engineering, Electrical
study programme)	engineering, undergraduate
olday programmo,	onginooning, undorgruddato

Authorship of university/faculty	
textbooks in the field of the course	
	1. Bosnić, Juraj Alojzije; Petrović, Goran; Malarić, Roman. Estimation of the wall thermal properties through comparison of experimental and simulated heat flux // 21ST IMEKO TC-4 measurement. Budapest, 2016.
	2. Mostarac, Petar; Malarić, Roman; Petrović, Goran. Measurement of frequency spectrum with interpolated adaptive chirp-z transformation // XXI IMEKO world congres. Prag,: Czech Technical University in Prague, 2015. 2008-2011.
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	3. Petrović, Goran; Malarić, Roman; Ivana, Kardum. Matlab based flickermeter // 20th IMEKO TC4 International Symposium and 18th International Workshop on ADC Modelling and Testing. Benevento: University of Sannio, 2014. 31-34.
	 4. Lorincz, Josip; Matijević, Tončica; Petrović, Goran. On interdependence among transmit and consumed power of macro base station technologies. // Computer communications. 50 (2014); 10-28
	5. Petrović, Goran; Kilić, Tomislav; Garma, Tonko. Measurement and Estimation of the Extremely Low Frequency Magnetic Field of the Overhead Power Lines. // Elektronika ir elektrotechnika. 19 (2013), 7; 33-36.
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	 Smart grid metrology infrastructure, HRZZ Research Projects 2015- Extracting electric energy from human body for supplying autonomous biomedical devices and new PVDF transducer optimization, Bilateral Croatian Italian scientific project 2010- 2013.
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?-pedagoške kompetencije?	
PRIZES AND AWARDS, STUDENT I	EVALUATION
Prizes and awards for teaching and	
scholarly/artistic work Results of student evaluation taken	
in the last five years for the course	
that is comparable to the course described in the form (evaluation	
organizer, average grade, note on	
grading scale and course evaluated)	

First and last name and title of	han Slannižar, Dh.D., Full Professor
teacher	Ivan Slapničar, Ph.D., Full Professor
The course he/she teaches in the proposed study programme	Numerical Analysis
GENERAL INFORMATION ON COU	RSE TEACHER
Address	FESB, R. Boškovića 32, B803
Telephone number	021 305893
E-mail address	ivan.slapnicar@fesb.hr
Personal web page	http://www.fesb.hr/~slap
Year of birth	1961
Scientist ID	30650
Research or art rank, and date of last rank appointment	scientific counselor
Research-and-teaching, art-and- teaching or teaching rank, and date of last rank appointment	Full Professor, permanent position, since 2008
Area and field of election into research or art rank	Area od Natural Sciences, Field of Mathematics
INFORMATION ON CURRENT EMP	LOYMENT
Institution where employed	FESB, Split
Date of employment	1985
Name of position (professor,	Full Professor
researcher, associate teacher, etc.)	
Field of research	Mathematics
Function	Head of the Chair of Mathematics
INFORMATION ON EDUCATION - H	lighest degree earned
Degree	dr. sc. (dr. rer. Nat.)
Institution	Fernuniversität Hagen
Place	Hagen, Germany
Date	October 1992
INFORMATION ON ADDITIONAL TR	AINING
Year	2014
Place	Cambridge, MA, USA
Institution	Massachusetts Institute of Technology
Field of training	Fulbright-Schuman International Educator/Lecturer Grant
Year	2009/2010
Place	Berlin, Germany
Institution	Technische Universität Berlin
Field of training	FP7 People "Marie Curie" Intra European Fellowship
Year	2001/2002
Place	Logan, UT, SAD
Institution	Utah State University
Field of training	Visiting Professor of Mathematics
MOTHER TONGUE AND FOREIGN	LANGUAGES
Mother tongue	Croatian
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	English (5)
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	German (5)
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	
COMPETENCES FOR THE COURSE	

Earlier experience as course	Lecturer of various courses since 1992.	
teacher of similar courses (name		
title of course, study programme		
where it is/was offered, and level of		
study programme)	han Oleanižan Matamatika (, EEOD, Onlit, 2000, (Manualia	
Authorship of university/faculty	Ivan Slapničar, Matematika 1, FESB, Split, 2002. (Manualia	
textbooks in the field of the course	Universitatis studiorum Spalatensis)	
	Ivan Slapničar, Josipa Barić i Marina Ninčević, Matematika 2 –	
	zbirka zadataka, FESB, Split, 2010. (Manualia Universitatis	
	studiorum Spalatensis)	
	1. Jakovčević Stor, Nevena; Slapničar, Ivan; Barlow, Jesse L.	
	Forward stable eigenvalue decomposition of rank-one	
	modifications of diagonal matrices, Linear Algebra and its	
	Applications. 487 (2015) 301-315.	
	2. Jakovčević Stor, Nevena; Slapničar, Ivan.	
	Forward Stable Computation of Roots of Real Polynomials	
	with Real Simple Roots, Applied Mathematics and Information	
Professional, scholarly and artistic	Sciences. 11 (2017) 33-41.	
articles published in the last five	3. Jakovčević Stor, Nevena; Slapničar, Ivan; Barlow, Jesse L.	
years in the field of the course (5	Accurate eigenvalue decomposition of real symmetric	
works at most)	arrowhead matrices and applications, Linear algebra and its	
	applications. 464 (2015) 62-89.	
	4. Slapničar, Ivan. Symmetric matrix eigenvalue techniques,	
	Handbook of Linear Algebra, Hogben, Leslie (ed.). Chapman &	
	Hall / CRC, Boca Raton, 2013, pp. 55-1-55-23.	
	5. Slapničar, Ivan. On the spectra of generalized Fibonacci and Fibonacci-like operators., Operators and Matrices. 6	
	(2012) 49-62.	
Professional and scholarly articles	(2012) 43-02.	
published in the last five years in		
subjects of teaching methodology		
and teaching quality (5 works at		
most)		
Professional, science and artistic	1. Accurate and fast matriox algorithms and applications,	
projects in the field of the course	project MZOS No. 372783-1289, 2007- 2013, principal	
carried out in the last five years (5	investigator.	
at most)	2. Optimization of parameter dependent mechanical systems,	
,	HRZZ research project No. 9540, 2015-2019, collaborator.	
The name of the programme and		
the volume in which the main		
teacher passed exams in/acquired		
the methodological-psychological-		
didactic-pedagogical group of		
competences?		
PRIZES AND AWARDS, STUDENT EVALUATION		
	Prize of the Fernunivesität Hagenu for the best disseration,	
Prizes and awards for teaching and	1992.	
scholarly/artistic work	Prize of the Croatian Mathematical Society Nagrada for the	
	young scientist, 1996.	
Results of student evaluation taken in	Evaluations organized by the Quality Enhancement Centre of	
the last five years for the course that	the University of Split each semester. Average grade is 4.5 on	
is comparable to the course	the 1-5 scale.	
described in the form (evaluation		
organizer, average grade, note on grading scale and course evaluated)		
grading scale and course evaluated)		
First and last name and title of		
teacher	Ivo Stančić, Ph.D., Assistant Professor	
The course be/she teaches in the		

Optoelectronic measurement methods

The course he/she teaches in the

proposed study programme

GENERAL INFORMATION ON COURSE TEACHER	
Address	R. Boškovića 32
Telephone number	+ 385 (0)21 305 879
E-mail address	istancic@fesb.hr
Personal web page	http://marjan.fesb.hr/~istancic/
Year of birth	1984.
Scientist ID	291143
Research or art rank, and date of	Research associate (October 2013)
last rank appointment	
Research-and-teaching, art-and-	
teaching or teaching rank, and date	Assistant professor (March 2017)
of last rank appointment	
Area and field of election into	Technical sciences, Electrical engineering
research or art rank	
INFORMATION ON CURRENT EMP	
Institution where employed	Faculty of electrical engineering, mechanical engineering and naval architecture, University of Split
Date of employment	4.5.2007.
Name of position (professor,	Assistant professor
researcher, associate teacher, etc.)	
Field of research	Electrical engineering / electronics
Function	
INFORMATION ON EDUCATION - H	
Degree	PhD
Institution	Faculty of electrical engineering, mechanical engineering and naval architecture, University of Split
Place	Split
Date	30. 11. 2012.
INFORMATION ON ADDITIONAL TR	AINING
Year	
Place	
Institution	
Field of training	
MOTHER TONGUE AND FOREIGN	LANGUAGES
Mother tongue	Croatian
	English (5)
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	
Foreign language and command of	Italian (2)
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	
COMPETENCES FOR THE COURS	
Earlier experience as course	
teacher of similar courses (name	
title of course, study programme where it is/was offered, and level of	
study programme)	

	M. Bonković, J. Musić, I. Stančić, Microcontrollers and
Authorship of university/faculty textbooks in the field of the course	embedded network systems based on Arduino development environment, faculty script, 2014.
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	1. Stančić, Ivo; Grujić, Tamara; Panjkota Ante. Design, Development, and Evaluation of Optical Motion- Tracking System Based on Active White Light Markers. IET science measurement & technology. 7 (2013), 4; 206-214.
	2. Stančić, Ivo; Grujić, Tamara; Bonković, Mirjana. New Kinematic Parameters for Quantifying Irregularities in the Human and Humanoid Robot Gait. // International Journal of Advanced Robotic Systems. 9 (2012) ; 215-1-215-8
	 Stančić, Ivo; Musić, Josip; Zanchi, Vlasta. Improved structured light 3D scanner with application to anthropometric parameter estimation
	4. Stančić, Ivo; Musić, Josip; Cecić, Mojmil. A Novel Low-Cost Adaptive Scanner Concept for Mobile Robots. // Ingeniería e Investigación. 34 (2014), 3; 37-43
	 Stančić, Ivo; Brajović, Miloš; Orović, Irena; Musić, Josip. Compressive sensing for reconstruction of 3D point clouds in smart systems
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	1. Compressive sensing and super-resolution in surveillance systems based on optical sensors and UAVs, 2015-2017, Bilateral Croatia-Montenegro cooperation, researcher.
	2. Supervised and unsupervised learning from imbalanced datasets for assistance in movement of persons with low vision, 2014-2015, Bilateral Croatia-Slovenia cooperation, researcher.
	3. Prototyping a module for automatization of industrial floor scrubbers, 2014-2016, Split-Dalmatia county and Odabir d.o.o., researcher.
	4. Development and implementation of methods for identification of bio-system and environment, 2014 - , Faculty/University project, researcher.
	5. Biomechanics of human motion, control and rehabilitation, 2007-2014, Ministry of science, education and sports, researcher.
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences.	

PRIZES AND AWARDS, STUDENT EVALUATION	
Prizes and awards for teaching and scholarly/artistic work	FESTO prize for young scientist and researchers DAAAM Symposium "Intelligent Manufacturing & Automation, Vienna, Austria, 26.11.2011.
	Best paper award in "Symposium on Smart Environment Technologies" during SofCOM 2016 conference.
Results of student evaluation taken	
in the last five years for the course that is comparable to the course	
described in the form (evaluation	
organizer, average grade, note on	
grading scale and course evaluated)	

First and lost name, and title of	
First and last name and title of teacher	Darko Stipaničev, Ph.D., Full Professor
The course he/she teaches in the proposed study programme	Artificial intelligence Computational intelligence (neuro-fuzzy-genetic systems) Digital control Digital image processing and analysis Modelling and control of vessels and ground vehicles Process control
GENERAL INFORMATION ON COU	RSE TEACHER
Address	Matoševa 26, 21000 Split
Telephone number	+385 91 4305 643
E-mail address	darko.stipanicev@fesb.hr
Personal web page	http://laris.fesb.hr/dstip-e.html
Year of birth	1955
Scientist ID	44861
Research or art rank, and date of	Scientific Adviser in Computer Science, 2006
last rank appointment	Scientific Adviser in Electrical Engineering, 1997
Research-and-teaching, art-and- teaching or teaching rank, and date of last rank appointment	Senior Full Professor, 2002
Area and field of election into	Technical Systems, Field Electrical engineering
research or art rank	Technical Systems, Fireld Computer sciences
INFORMATION ON CURRENT EMP	LOYMENT
Institution where employed	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Date of employment	1981
Name of position (professor,	Professor
researcher, associate teacher, etc.)	
Field of research	Computer Science – Artificial Intelligence, Electrical Engineering - Automatic Control
Function	Head of Chair of Modelling and Intelligent Systems
INFORMATION ON EDUCATION - H	
Degree	PhD
Institution	Electrotechnical Faculty University of Zagreb
Place	Zagreb
Date	1987
INFORMATION ON ADDITIONAL TR	RAINING
Year	1988-89
Place	London
Institution	Queen Mary College
Field of training	post-doctoral specialisation
MOTHER TONGUE AND FOREIGN	LANGUAGES
Mother tongue	Croatian
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	English (5)
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	Italian (4)
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	

Earlier experience as course	Process Modelling and Control (1995 – 2005)
teacher of similar courses (name	Process control (2005 – today)
title of course, study programme	Digital control (2005 – today)
where it is/was offered, and level of	Modelling and Control of Maritime and Land Vehicles (1995 –
study programme)	today)
Authorship of university/faculty textbooks in the field of the course	D.Stipaničev, J.Marasović, Digitalno vođenje on-line (Digital control on-line), on-line (Web) book, MZT – Informatički projekt,
	2004. http://laris.fesb.hr/digitalno_vodjenje
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	 D.Stipaničev, J.Božičević, Fuzzy Feedforward and Composite Control, Transaction Inst. Measurement and Control (UK), 8(2), 1986, pp. 67-75 D.Stipaničev, Vođenje i zaštita vjetroelektrana u autonomnom elektro-energetskom sistemu, Sunčana energija, 8(2), 1987, pp.91-96 D.Stipaničev, Diskretno vođenje složenih sustava adaptivnim, nelinearnim PID regulatorima, Elektrotehnika, 34(3-4), 1991, pp.153-161 D.Stipaničev, Fuzzy Relational Models for Intelligent Control, u knizi R. Hanus, P.Kool, S.Tzafestas(ed) "Mathematical and Intelligent Models in System Simulation", J.C.Baltzer AG Scientific Pub.Co., 1991, pp.275-279 M.De Neyer, D.Stipaničev, R.Gorez, Intelligent Self- organising Controllers and their Application to the Control of Dynamic Systems, u knjizi R.Hanus, P.Kool, S.Tzafestas(ed) "Mathematical and Intelligent Models in System Simulation", J.C.Baltzer AG Scientific Pub.Co., 1991, pp.287-292
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	 Project Vision based intelligent observers (ViO) (2012 – 2016) Project 023-0232005-2003 – AgISEco – Agent based intelligent systems for environmental monitoring, Contract with Ministary of Science RH (2006 - 2012)
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?	
PRIZES AND AWARDS, STUDENT	EVALUATION
Prizes and awards for teaching and scholarly/artistic work	
Results of student evaluation taken	4,4/5
in the last five years for the course	· · · ·
that is comparable to the course	
described in the form (evaluation	
organizer, average grade, note on	
grading scale and course	
evaluated)	
evalualeu)	

First and last name and title of teacher	Ljiljana Šerić, Ph.D., Assistant Professor
The course he/she teaches in the	
proposed study programme	Artificial Intelligence
GENERAL INFORMATION ON COU	RSE TEACHER
Address	FESB, Ruđera Boškovića 32, 21000 Split
Telephone number	+385 (0)21 305 651
E-mail address	ljiljana.seric@fesb.hr
Personal web page	http://www.fesb.hr/~ljiljana
Year of birth	1979.
Scientist ID	272906
Research or art rank, and date of last rank appointment	Senior Research Associate, 14.02.2013.
Research-and-teaching, art-and- teaching or teaching rank, and date of last rank appointment	Assistant professor, 02.12.2013.
Area and field of election into research or art rank	Technical sciencies, Computer Science
INFORMATION ON CURRENT EMP	LOYMENT
Institution where employed	University of Split, Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Date of employment	02.12.2013.
Name of position (professor,	Assistant professor
researcher, associate teacher, etc.)	
Field of research	Science and education
Function	Assistant professor
INFORMATION ON EDUCATION - H	Highest degree earned
Degree	PhD
Institution	University of Split, Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Place	Split
Date	06.10.2010.
INFORMATION ON ADDITIONAL TR	AINING
Year	
Place	
Institution	
Field of training	
MOTHER TONGUE AND FOREIGN	
Mother tongue	Croatian
Foreign language and command of	
foreign language on a scale from 2 (sufficient) to 5 (excellent)	English (5)
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	German (3)
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	
COMPETENCES FOR THE COURS	E
Earlier experience as course teacher of similar courses (name title of course, study programme where it is/was offered, and level of study programme)	1. Course name: Artificial Intelligence Name of the study programme in which the course is offered: Automation and Systems, Electrical Engineering, Computer Engineering, Telecommunications and Computer Science, Computer Science The level of the study programme: Graduate study
	2. Course name: Intelligent Systems

	Name of the study programme in which the subject is taught: Electrical Engineering and Information Technology The level of the study programme: Postgraduate study 3. Course name: Web intelligence and large data sets Name of the study programme in which the subject is taught: Electrical Engineering and Information Technology The level of the study programme: Postgraduate study
Authorship of university/faculty textbooks in the field of the course	 Stipaničev Darko, Šerić Ljiljana. Artificial intelligence. Split, FESB - Internal script, 2012. Bodrožić Ljiljana. Programming languages of artificial intelligence. Split, FESB - Internal script, 2007.
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	 Doko Alen, Štula Maja, Šerić Ljiljana. Improved sentence retrieval using local context and sentence length. Information processing & management, 49 (2013), 6, 1301-1312. Šerić Ljiljana, Stipaničev Darko, Štula Maja. Engineering of holonic multi agent intelligent forest fire monitoring system. Al communications, 26 (2013), 3; 303-316. Šerić Ljiljana, Krstinić Damir, Braović Maja, Milatić Ivan; Mirčevski Aljoša, Stipaničev Darko. Holonic Multi Agent System for Data Fusion in Vehicle Classification. Proceedings of 10th International KES Conference on Agents and Multi-Agent Systems: Technologies and Applications (KES-AMSTA-16). 2016. Stipaničev Darko, Šerić Ljiljana, Krstinić Damir, Bugarić Marin. Wildfire video observers network with physical and virtual sensors. Proceeding of 10th EARSeL Forest Fire Special Interest Group Workshop - Sensors, Multi-Sensor Integration, large Volumes: New opportunities and Challanges in Forest Fire Research, Themistocleous, Kyriacos ; Hadjimitsis, Diofantos; Gitas, Ioannios ; Boschetti, Luigi (ur.). Limassol, Cyprus, 2015. Ukić Nenad, Maras Josip, Šerić Ljiljana. The influence of cyclomatic complexity distribution on the understandability of xtUML models, Software quality journal, PP (2016)
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	AgiSeco – Agent Oriented Intelligent Systems for Environement Monitoring and Control, MZOS, 2007-2012 HOLISTIC – Adriatic Holistic Forest Fire Protection, IPA, 2014- in progres Wind Risk Prevention Projekt – ECHO, Civil Protection Automatic vehicle classification based on computer vision and data fusion
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological-didactic-pedagogical group of competences.	
PRIZES AND AWARDS, STUDENT I	EVALUATION
Prizes and awards for teaching and	20 best junior reasearchers, 2013
scholarly/artistic work Results of student evaluation taken in the last five years for the course that is comparable to the course described in the form (evaluation organizer, average grade, note on grading scale and course evaluated)	

First and last name and title of	¥
teacher	Maja Štula, Ph.D., Full Professor
The course he/she teaches in the	Computer systems
proposed study programme	Programming agents
GENERAL INFORMATION ON COL	JRSE TEACHER
Address	R. Boškovića 32, Split
Telephone number	021305852
E-mail address	maja.stula@fesb.hr
Personal web page	http://marjan.fesb.hr/~kiki/moja_stranica.htm
Year of birth	1971
Scientist ID	248946
Research or art rank, and date of	
last rank appointment	
Research-and-teaching, art-and-	Full professor
teaching or teaching rank, and	
date of last rank appointment	Taskaisel Osianaas, Osmautas anaineaning
Area and field of election into	Technical Sciences, Computer engineering
research or art rank	
INFORMATION ON CURRENT EMP	
Institution where employed	Faculty of Electrical Engineering, Mechanical Engineering and
	Naval Architecture
Date of employment	15.06.1998.
Name of position (professor,	Professor
researcher, associate teacher,	
etc.) Field of research	
Function	
INFORMATION ON EDUCATION -	
Degree	PhD
Institution	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Place	Split
Date	06.05.2005.
INFORMATION ON ADDITIONAL T	
INFORMATION ON ADDITIONAL T	RAINING
Voor	
Year	
Place	
Place Institution	
Place Institution Field of training	
Place Institution Field of training MOTHER TONGUE AND FOREIGN	
Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue	Croatian
Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of	
Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2	Croatian
Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	Croatian English, 5
Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2	Croatian
Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of	Croatian English, 5
Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language a scale foreign language a scale foreign language a sc	Croatian English, 5
Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of foreign language on a scale from 2	Croatian English, 5
Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language and command prove a scale foreign language a scale foreign language a scale foreign language a sc	Croatian English, 5
Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of foreign language on a scale from 2	Croatian English, 5 Italian, 2
Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent)	Croatian English, 5 Italian, 2
Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) COMPETENCES FOR THE COURS Earlier experience as course teacher of similar courses (name	Croatian English, 5 Italian, 2 SE Internet programming, Undergraduate study in Computing Windows programming, Graduate study in Electronics and
Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) COMPETENCES FOR THE COURS Earlier experience as course teacher of similar courses (name title of course, study programme	Croatian English, 5 Italian, 2 E Internet programming, Undergraduate study in Computing
Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) COMPETENCES FOR THE COURS Earlier experience as course teacher of similar courses (name title of course, study programme where it is/was offered, and level of	Croatian English, 5 Italian, 2 SE Internet programming, Undergraduate study in Computing Windows programming, Graduate study in Electronics and
Place Institution Field of training MOTHER TONGUE AND FOREIGN Mother tongue Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) Foreign language on a scale from 2 (sufficient) to 5 (excellent) COMPETENCES FOR THE COURS Earlier experience as course teacher of similar courses (name title of course, study programme	Croatian English, 5 Italian, 2 SE Internet programming, Undergraduate study in Computing Windows programming, Graduate study in Electronics and

textbooks in the field of the course	FESB, 2010.
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	 Markić, Ivan; Štula, Maja; Maras, Josip.Intelligent Multi Agent Systems for Decision Support in Insurance Industry // / Biljanović, Petar (ur.).Rijeka : Croatian Society for Information and Communication Technology, Electronics and Microelectronics - MIPRO, 2014. 1368-1373 Stipaničev, Darko; Bugarić, Marin; Krstinić, Damir; Šerić, Ljiljana; Jakovčević, Toni; Braović, Maja; Štula, Maja.New generation of automatic ground based wildfire surveillance systems // Advances in forest fire research.Coimbra, Portugal : Imprensa da Universidade de Coimbra, 2014. 1455-1466 Štula, Maja; Stipaničev, Darko; Maras, Josip. Distributed Computation Multi-agent System. // New generation computing. 31 (2013) , 3; 187-209 Štula, Maja; Krstinić, Damir; Šerić, Ljiljana. Intelligent Forest Fire Monitoring System. // Information systems frontiers. 14 (2012) , 3; 725-739
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	 Golčić, Hrvoje; Skelić, Ivana; Štula, Maja. Razvoj, implementacija i korištenje dodataka za osobe s oštećenjem vida u Moodle sustavu, 2015. (brošura). Golčić, Hrvoje; Skelić, Ivana; Štula, Maja. Accessibility Issues Faced By Blind and Visually Impaired Persons in the Field of Studying and Education // Proceedings of CIET 2014 / Plazibat, Bože ; Kosanović, Silvana (ur.).Split : University of Split, 2014. S-187-S-198
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	IPNAS (Inteligentni Protupožarni NAdzorni Sustav) sustav, stručni DICES – Distributed Component-based Embedded Software Systems, UKF Agentski orijentirani inteligentni sustavi nadzora i zaštite okoliša, MZOŠ
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?-pedagoške kompetencije?	
PRIZES AND AWARDS, STUDENT	EVALUATION
Prizes and awards for teaching	
and scholarly/artistic work Results of student evaluation taken	
in the last five years for the course	
that is comparable to the course described in the form (evaluation	
organizer, average grade, note on	
grading scale and course	
evaluated)	

teacher	Božo Terzić, Ph.D., Full professor	
	· · · · · · · · · · · · · · · · · · ·	
The course he/she teaches in the		
proposed study programme	Electric Servo Drives	
GENERAL INFORMATION ON COUL	RSE TEACHER	
Address	Elemova 5, 21312 Podstrana HR	
Telephone number	+385 91 4305609	
E-mail address	bterzic@fesb.hr	
Personal web page		
Year of birth	1962.	
Scientist ID	138865	
Research or art rank, and date of		
last rank appointment	Scientific Adviser, 9/7/2009	
Research-and-teaching, art-and-		
teaching or teaching rank, and	Senior Full Professor, 18/9/2014	
date of last rank appointment		
Area and field of election into	Technical Sciences, Field Electrical angineering	
research or art rank	Technical Sciences, Field Electrical engineering	
INFORMATION ON CURRENT EMPI	LOYMENT	
Institution where employed	Faculty of Electrical Engineering, Mechanical Engineering and	
	Naval Architecture	
Date of employment	1986.	
	Professor	
researcher, associate teacher,		
etc.)		
	Electrical Drives, Power Converters	
Function	Head of Chair of Electrical Drives and Automation	
INFORMATION ON EDUCATION - H	Highest degree earned	
Degree	PhD	
Institution	Faculty of Electrical Engineering, Mechanical Engineering and	
	Naval Architecture	
	Split	
Date	25/11/1998	
INFORMATION ON ADDITIONAL TR	RAINING	
Year		
Place		
Institution		
Field of training		
MOTHER TONGUE AND FOREIGN I	LANGUAGES	
Mother tongue	Croatian	
Foreign language and command of		
foreign language on a scale from 2	English (4)	
(sufficient) to 5 (excellent)		
Foreign language and command of		
foreign language on a scale from 2	German (2)	
(sufficient) to 5 (excellent)		
COMPETENCES FOR THE COURSE		
Earlier experience as course teacher	Electrical drives - Professional study programme of Electrical	
of similar courses (name title of	engineering, Testing of Electrical Equipement - Graduate study programme of	
course, study programme where it is/was offered, and level of study	Power engineering	
programme)		
Authorship of university/faculty		
textbooks in the field of the course		
textbooks in the field of the course Professional, scholarly and artistic	1. Terzić, Božo; Despalatović, Marin; Slutej, Alojz. Magnetization Curve Identification of Vector-Controlled	

years in the field of the course (5 works at most)	 Induction Motor at Low-Load Conditions. // Automatika - Journal for Control, Measurement, Electronics, Computing and Communications, 53 (2012), 3; 1-8. Jadrić, Martin; Terzić, Božo; Despalatović, Marin; Majić, Goran; Slutej, Alojz; Šimić, Toni. Identification of Rotor Resistance and Transient Inductance of Induction Motors Using Frequency Selection Criterion // Proceedings of the 2012 XXth International Conference on Electrical Machines / Nogueiras Meléndez, Andrés A. (ur.). Marseille, Francuska : IEEE IES, 2012. 978-984. Terzić, Božo; Despalatović, Marin; Majić, Goran; Gladina, Željko: Mjerenja i analiza karakteristika upuštača asinkronih motora u postrojenju mlina cementa 2 u tvornici Cemex – Pogon Sv. Juraj, Naručitelj: Siemens, 2014. Terzić, Božo; Despalatović, Marin; Majić, Goran; Stergulc, Marjan; Kriletić, Ante; Šormaz, Krste: Frequency Converter Design for High Speed Permanent Magnet Generator in Cogeneration Plants,, Technical Journal, Scientific- professional Journal of University North, Vol. 10, No. 3-4, Croatia, 2016.
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	 Domestic sceintific project: On-line parameter identification of synchronous generator, project leader, 2011. – 2013., funding the project: MZOŠ International development project: Development of electric drives for crane systems operating in hard environment, project leader, 2008. – 2013., in cooperation with swedish company ABB Crane Systems that fully funded the project. Researche and development project: A safer and more efficient cogeneration / trigeneration plants, project leader, 20142016., project was funded from EU structural funds.
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?	
PRIZES AND AWARDS, STUDENT	EVALUATION
Prizes and awards for teaching and scholarly/artistic work	
Results of student evaluation taken in the last five years for the course that is comparable to the course described in the form (evaluation organizer, average grade, note on grading scale and course evaluated)	From 4 to 4,8.

First and last name and title of	lvica Veža , Ph.D., Full Professor
teacher	
The course he/she teaches in the	Production management
proposed study programme	Project management
GENERAL INFORMATION ON COU	RSE TEACHER
Address	Odeska 13, 21000 Split, HR
Telephone number	+385 21 305933
E-mail address	iveza@fesb.hr
Personal web page	
Year of birth	1951.
Scientist ID	095643
Research or art rank, and date of last rank appointment	Scientific Adviser - Mechanical Engineering, 08.03.2001. Scientific Adviser – Fundamental Technical Science 05.07.2006.
Research-and-teaching, art-and- teaching or teaching rank, and date of last rank appointment	Senior Full Professor, 23.01.1998.
Area and field of election into research or art rank	Technical Sciences, Field Industrial engineering
INFORMATION ON CURRENT EMP	LOYMENT
Institution where employed	Faculty of Electrical Engineering, Mechanical Engineering and Naval Architecture
Date of employment	1/1/1981
Name of position (professor,	Professor
researcher, associate teacher, etc.)	
Field of research	Plant Layout, Organization, Production Engineering
Function	Head of Chair of Inudstrial Engineering
INFORMATION ON EDUCATION - H	Highest degree earned
Degree	PhD
Institution	Faculty of Mechanical Engineering and Naval Architecture
Place	Zagreb
Date	9/11/2001
INFORMATION ON ADDITIONAL TR	
Year	
Place	1983/84 Stuttaget Cormonu
	Stuttgart, Germany
Institution	University of Stuttgart, Fraunhofer – Institut fuer Produktiontechnik und Automatisierung
Field of training	Plant Layout, Simulation
INFORMATION ON ADDITIONAL TR	
Year Place	1991 Berlin Germany
Institution	Berlin, Germany Technical University of Berlin, Fraunhofer IPK
Field of training	
	Design of Assembly Systems
MOTHER TONGUE AND FOREIGN	
Mother tongue	Croatian
Foreign language and command of	English (4)
foreign language on a scale from 2	
(sufficient) to 5 (excellent)	Cormony (4)
Foreign language and command of	Germany (4)
foreign language on a scale from 2 (sufficient) to 5 (excellent)	
Foreign language and command of	
Foreign language and command of foreign language on a scale from 2	
Foreign language and command of foreign language on a scale from 2 (sufficient) to 5 (excellent)	
Foreign language and command of foreign language on a scale from 2	E Economics and Production Organisation, Undergraduate study

toophor of similar sources (some	programmo
teacher of similar courses (name title of course, study programme	programme
where it is/was offered, and level of	
study programme)	
Authorship of university/faculty textbooks in the field of the course	Veža, Ivica: Bilić, Boženko; Gjeldum, Nikola; Mladineo, Marko: "Upravljanje projektima", Fakultet elektrotehnike,
	strojarstva i brodogradnje, Split, 2011.
Professional, scholarly and artistic articles published in the last five years in the field of the course (5 works at most)	 Perić, Tunjo; Babić, Zoran; Veža, Ivica: Vendor selection and supply quantities determination in a bakery by AHP and fuzzy multi-criteria programming. International journal of computer integrated manufacturing. 26 (2013), 9; 816-829 Veža, Ivica; Mladineo, Marko: SUSTAINABILITY THROUGH PRODUCTION NETWORKS. Management and Production Engineering Review. 4 (2013), 4; 33-39 Gjeldum, Nikola; Bilić, Boženko; Veža, Ivica. Investigation and modelling of process parameters and workpiece dimensions influence on material removal rate in CWEDT process. International journal of computer integrated manufacturing. 28 (2015), 7; 715-728 Takakuwa, Soemon; Veža, Ivica: Technology Transfer and World Competitiveness. Procedia Engineering. 69 (2014); 121-127 Banduka, Nikola; Veža, Ivica; Bilić, Boženko: An integrated lean approach to Process Failure Mode and Effect Analysis (PFMEA): A case study from automotive industry. Advances in Production Engineering & Management. 11 (2016), 4; 355-365
Professional and scholarly articles published in the last five years in subjects of teaching methodology and teaching quality (5 works at most)	 Gečevska, Valentina; Čuš, Franci; Chiabert, Paolo; Veža, Ivica: LINKING LEAN PRODUCTION WITH PRODUCT LIFECYCLE MANAGEMENT FOR SUSTAINABLE BUSINESS ENVIRONMENT, DEVELOPMENT OF INTELLIGENT AND INNOVATIVE TOOLS FOR PRODUCTION PROCESS ENGINEERING AND SUSTAINABLE MANAGEMENT, Čuš, F.; Gečevska, V. (Ed.). Maribor, Slovenija: Faculty of Mechanical engineering, Maribor, 2013. 19-39. Čelar, Stipe; Turić, Mili; Dragičević, Srdjana; Veža, Ivica. Digital Learning Factory at FESB – University of Split , ZBORNIK RADOVA YU INFO 2016, 2016. 001-006 Veža, Ivica; Gjeldum, Nikola; Mladineo, Marko: Logistics Personal Excellence by Continuous Self-Assessment (LOPEC): Pilot Implementation - Case Studies. Conference Proceedings - MTSM 2014, Split, 2014. 39-46 Stojkić, Željko; Veža, Ivica; Bošnjak, Igor. CONCEPT OF INFORMATION SYSTEM IMPLEMENTATION (CRM AND ERP) WITHIN INDUSTRY 4.0, Proceedings of the 26th DAAAM International Symposium, Vienna, DAAAM International, 2016. 912-919
Professional, science and artistic projects in the field of the course carried out in the last five years (5 at most)	 2008 – 2013 Project TEMPUS-2008-IT-JPCR 144 959, Master Study Program in Product Lifecycle Management with Sustainable Production 2011-2014 LEONARDO DA VINCI Project "LOPEC - Logistics personnel excellence by continuous self- assessment", FESB Split, University of Reutlingen 2013-2016 Network of Innovative Learning Factories NIL, "System - Learning Factory", FESB, Split, University of Reutlingen 2013-2016 Know-how Exchange on the Consequences and
	Challenges of the Integration of Key Enabling Technologies

	 in European Manufacturing for the Danube Region, Fraunhofer Institute for Systems and Innovation Research ISI – Karlsruhe 7. 2014-2018 Innovative Smart Enterprise, INSENT, Croatian Science Foundation, Zagreb 	
The name of the programme and the volume in which the main teacher passed exams in/acquired the methodological-psychological- didactic-pedagogical group of competences?		
PRIZES AND AWARDS, STUDENT EVALUATION		
Prizes and awards for teaching and scholarly/artistic work		
Results of student evaluation taken in the last five years for the course that is comparable to the course described in the form (evaluation organizer, average grade, note on grading scale and course evaluated)	4,9/5	

2.16. Optimal number of students

The admission quote for the first year of studies is 50.

2.17. Estimate of costs per student

Annual costs of studies per student amount to HRK 25,000.00

2.18. Plan of procedures of study programme quality assurance

In keeping with the European standards and guidelines for internal quality assurance in higher education institutions (according to "Standards and Guidelines of Quality Assurance in the European Higher Education Area") on the basis of which the University of Zagreb defines procedures for quality assurance, the proposer of the study programme is obliged to draw up a plan of procedures of study programme quality assurance.

Documentation on which the quality assurance system of the constituent part of the University is based:

- Regulations on the quality assurance system of the constituent part (enclose if existing)
- Handbook on the quality assurance system of the constituent part (enclose if it exists)

Description of procedures for evaluation of the quality of study programme implementation:

- Fore each procedure the method needs to be described (most often questionnaires for students or teachers, and self-evaluation questionnaire), name the body conducting evaluation (constituent part, university office), method of processing results and making information available, and timeframe for carrying out evaluation
- If procedure is described in an attached document, name the document and the article.

Evaluation of the work of teachers and part-time teachers	 Student evaluation of quality of instruction and teaching activities conducted through student survey (printed questionnaires) Survey is organised and conducted by the Quality Enhancement Committee of the Faculty (Committee) Survey results are processed automatically at the University Survey is conducted each semester The Committee presents cumulative results of the survey at the sessions of the Faculty Council. The report is published at the Faculty web site. All procedures are conducted in accordance with the Regulations on organisation and role of the quality assurance system of the University of Split, Regulations on procedure of student evaluation of the quality of teachers and teaching of the University of Split and Regulations on the quality enhancement system of FESB.
Monitoring of grading and harmonization of grading with anticipated learning outcomes	Committee for study programmes in Graduate university study programme in Automation and Systems is monitoring the harmonisation of grading and learning outcomes. All the procedures are conducted in accordance with the Rules of procedure of the Faculty Council and the Rules of procedure of the Department, since the Committees for

	study programmes are bodies of the Faculty Council and are accountable to the Faculty Council.
Evaluation of availability of resources (spatial, human, IT) in the process of learning and instruction	 Student evaluation of work performance of administrative and supporting services, learning infrastructure and student life is conducted through e-survey Evaluation is conducted using an on-line questionnaire which the students complete in each year of study, except the final year Survey is organised by the Quality Enhancement Centre of the University of Split, and is implemented by the Quality Enhancement Committee) Survey results are processed automatically at the University Survey is conducted every year Survey results are presented at the Faculty Council sessions and published at the Faculty web site.
Availability and evaluation of student support (mentorship, tutorship, advising)	 Administrative and supporting services are available to students to provide support in their study activities Supervisors/ mentors are appointed for students' final papers and diploma thesis
Monitoring of student pass/fail rate by course and study programme as a whole	 Analysis of student pass rate by courses and study programmes is carried out once a year Analysis of pass rate by study programmes is carried out by the University in cooperation with the Committee Analysis by courses and study programmes is carried out by the Faculty Management Board Results of both analyses are presented at the Faculty Council sessions and published at the Faculty web site.
Student satisfaction with the programme as a whole	 Student evaluation of work performance of administrative and supporting services, learning infrastructure and student life is conducted through e-survey Evaluation is conducted using an on-line questionnaire which the students complete following the completion of studies Survey is organised by the Quality Enhancement Centre of the University of Split, and is implemented by the Quality Enhancement Committee) Survey results are processed automatically at the University Survey results are presented at the Faculty Council sessions and published at the Faculty web site.
Procedures for obtaining feedback from external parties (alums, employers, labour market and other relevant organizations)	 Once every month, the Faculty Management Board meets with the alumni representatives Once a year, during the annual FESB anniversary event, round tables and workshops are organised with representatives of employers and other stakeholders
Evaluation of student practical education (where this applies)	Professional training is an elective course of the study programme. Head of the professional training from the receiving institution and the head of professional training from the Faculty are appointed to students who enrol professional training course. During the training student writes Professional training report which describes working tasks covered by the professional training. Students are

	obliged to complete professional training in accordance with the Regulation on professional training. Professional training report is validated by the head of professional training from the receiving institution and the head of professional training from the Faculty. Professional training is not evaluated. In addition to the Professional training report student completes a Questionnaire on professional training that evaluates student's satisfaction with organization and performance of the professional training.
Other evaluation procedures carried out by the proposer	 Internal audit of the quality assurance system is conducted once every year Self-evaluation is carried out every 5 years All the procedures are conducted in line with the Quality Assurance Handbook of FESB.
Description of procedures for informing external parties on the study programme (students, employers, alums)	 All information are available through the Faculty web site: <u>https://www.fesb.hr</u> Visits to the faculty are organised for high-school students from Split and the wider region Participation at University fairs Public media presentations