

## UNIVERSITYOFSPLIT

### FACULTY OF ELECTRICAL ENGINEERING, MECHANICAL ENGINEERING AND NAVAL ARCHITECTURE

# DETAILED PROPOSAL OF THE STUDY PROGRAMME

GRADUATE UNIVERSITY STUDY IN COMPUTING

SPLIT, February 2022

### 1.1. List ofmandatory and elective courses

		List ofcourses								
Yearofstudy:	1.									
Semester: I.										
STATUS	CODE	COURSE	НО	ECTS						
314103	CODE	COURSE	L	S	AE	LE	DE	ECIS		
Mandatory	FEMK01	Numerical analysis	30	0	30	0	0	5		
Internation y	FELK04	Computer graphics	30	0	0	30	0	5		
* L = lectures,	* L = lectures, S = seminars, AE = auditoryexcercise, LE = laboratoryexcercise, DE = design excercise									

		List ofcourses								
Yearofstudy:	1.									
Semester: II.	1									
HOURS IN							ER*			
STATUS CODE COURSE		L	S	AE	LE	DE	ECTS			
	FELK05	Programming languages and compilers	30	0	0	30	0	5		
Mandatory	FELG33	Optoelectronic measurement methods	30	0	0	30	0	5		
	FELK07	Advanced computerar chitectures	30	0	0	30	0	5		
Elective	FELK16	Data Warehouse	30	0	0	30	0	5		
	FELK34	Computer games programming	30	0	0	30	0	5		
* L = lectures,	* L = lectures, S = seminars, AE = auditoryexcercise, LE = laboratoryexcercise, DE = design excercise									

		List ofcourses							
Yearofstudy:	2.								
Semester: III									
		0011005	HO	URSI	N SEN	/IESTE	ER*	БОТО	
STATUS CODE		COURSE		S	AE	LE	DE	ECTS	
	FELK08	Multimedia systems	30	0	0	30	0	5	
	FELK11	Grid computing systems	30	0	30	0	0	5	
Mandatory	FETK01	Business information systems	30	0	0	30	0	5	
Manual Or y	FELK12	Embedded systems	30	0	0	30	0	5	
	FELH40	Programming mobile robots and drones	30	0	0	30	0	5	
	FELH41	Medical electronic devices	30	0	0	30	0	5	
* L = lectures,	* L = lectures, S = seminars, AE = auditoryexcercise, LE = laboratoryexcercise, DE = design excercise								

NAME OF THE COURSE	NUMERICAL ANALYSIS						
Code	FEMK01	Year of study	1				
Course teacher	Ivan Slapničar, Ph.D., Full Professor	Credits (ECTS)	5				
Associate teachers	Lana Periša Anita Carević	Type of instruction (number of hours)	L	S	AE	LE	DE
		Percentage of	30		30		
Status of the course	Obligatory	application of e-learning	20				
	COURSE	E DESCRIPTION					
Course objectives	erroranalysisofcomputer polynomialinterpolation, solvingnonlinearequation	andskillsofnumericalanalys raruthmetics, solvingsyste splines, leastsquaresmet ns, solvingdigfferentialequ concepts to naturalscience	msoflin hod, nu ations,	merica	alinteg		
Course enrolment requirements and entry competences required for the course							
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	<ul> <li>estimatedurationofthea</li> <li>explainmainideasbehib</li> <li>derivebasicnumericalm</li> <li>writesimplecomputerprolevellanguages (Matlab</li> <li>findand use computerprandcriticallyestimatethe</li> <li>chooseappropriatenum</li> </ul>	ndnumericalmethods, athodsandillustratetheirpr ograms for numericalmeth oor Julia), rograms for numericalmat	opertie odsin s hodsav	sbyexa some c vailable	amples ofhigle e on In	s, r-	-
	Course content				L nours		\E ours
	1. Computer arithmeticand	lerroranalysis			2		2
	2. Stable and unstable con		nber		2		2
	3. Solving systems of linear and iterative methods.	-		n	2		2
	4. Evaluating functions – H	lorner's method.			2		2
	5. Approximating functions		lls.		2		2
Course content	6. Splines.				2		2
broken down in detail by weekly	· · ·	and minimax method.			2		2
class schedule	<ol> <li>Least squares method and minimax method.</li> <li>Solving nonlinear equations – bisection, Newton's method</li> </ol>						
(syllabus)	and secant method.				2		2
(syllabus)	9. Fixed-point theorem and	d functional iteration.			2		2 2
(syllabus)		- trapezoidal rule, Simpso	n's				2 2 2
(syllabus)	9. Fixed-point theorem and 10. Numerical integration -	- trapezoidal rule, Simpso es.		e	2		2 2 2 2
(syllabus)	<ul> <li>9. Fixed-point theorem and</li> <li>10. Numerical integration -</li> <li>formula and error estimate</li> <li>11. Gaussian quadrature, F</li> </ul>	- trapezoidal rule, Simpso es. Romberg's algorithm and	adaptiv	e	2 2		2 2 2 2 2 2

### 1.2. Course description

	List oflaboratoryor de	esign ex	ercises				E or DE hours
Format of instruction	xlectures seminars and work xexercises <i>on line</i> in entirety partial e-learning field work	kshops	⊡mul ⊡labo	pendent timedia oratory k with me (other			
Studentresponsibiliti es	Regularattendence t	o andac	tiveparticipation	inlecture	sandexcercise	s.	
Screening student	Class attendance	2	Research		Practical traini	ng	
work (name the proportion of ECTS	Experimental work		Report		Self study		2
credits for eachactivity so that	Essay		Seminar essay	,	(Other)		
the total number of ECTS credits is	Tests	0.5	Oral exam		(Other)		
equal to the ECTS value of the course)	Written exam	0.5	Project		(Other)		
Grading and evaluating student work in class and at the final exam	termexam students attainedthroughassig passingthecourseis r 50 points. Afterseme Students which onlythispartoftheexan Students thefinalexamwithcom masimumnumbersof minimum 40 pointsin as follows: 85 and more points - 75-84 points - verygo 60-74 points - verygo 60-74 points - sufficie Students whodidnotp 10 poi thecorrectionexamm passing grade is min	andthes cang inement ninimun ster, two ndidnotp mduring w prehen availabl thefinale excelle bod (4), (3), and ent (2). basstheo nts, aximaln imum o	econdinthewee et 40 points isduringlectures n 20 points on e ofinalexamsand ass one finalexams. hichdidnotpassa sivecourseconte epointsis 80. examand a total ent (5), courseafterfinale cana umberofpointsis	kfollowin , whilet andexce achmid-t twocorree mid- anymid-te ent. Thecor of at leas exams, a ttendcorr s 80, and examand	heremaining rcises. TI ermexams and ctionexams are termexam, In adition for pa st 50 points. Th rectionsexam. the minimum r a total of at le are hele	At e 20 poir neconditio a total of e held. can th ssingthed re grade is ed total co requireme	achmid- nts are on for at least take take take natcase, courseis sformed of at leat On ent for a pints.
Required literature		Title			Number of copies in the library	Availab other i	-
	R. Scitovski, Numerić Sveučilište J. J. Stros Osijek, 2004. I.		http://ww os.hr/~s NM/Nun	citowsk/			

	Lecture materials on FESB e-learning portal.	https://elearni
		ng.fesb.hr
	FESBMat	https://github.co
		m/ivanslapnicar/
		FESBMat
	Netlib	http://www.netlib
		.org
	- D. Goldberg, Whateverycomputerscientistshouldkno	-
	pointarithmetic, <u>http://docs.sun.com/source/806-356</u>	
Optional literature (at	- D. Kincaid, W. Cheney, Numerical Analysis-Mathem	
the time of	Computing, Brooks/Cole Publishing Company, 2002	
submission of study	- G. W. Stewart, Afternotes on Numerical Analysis, Sl	
programme	<ul> <li>S. Singer, Numeričkamatematika, Predavanja, Svet Zagreb, 2009.</li> </ul>	uciliste u Zagrebu, FSB,
proposal)	<ul> <li>S. Singer, Numeričkamatematika, Vježbe, Sveučilišt</li> </ul>	e u Zagrebu, ESB
	Zagreb, 2009	e u Zagrebu, i OD,
	– homework	
Quality assurance	<ul> <li>short tests</li> </ul>	
methods that ensure	– quizzes	
the acquisition of exit	<ul> <li>mid-term exams</li> </ul>	
competences	– final exam	
	<ul> <li>student questionnaires</li> </ul>	
Other (as the		
proposer wishes to		
add)		

NAME OF THE COURSE	COMPUTER GRAPHICS						
Code	FELK04	Year of study	1.				
Course teacher	Vladan Papić, Ph.D., FullProfessor	Credits (ECTS)	5				
Accesiete teachere	Denis Štajduhar, mag.	Type of instruction	L	S	AE	LE	DE
Associate teachers	ing.	(number of hours)	30	0	0	30	0

Status of the course		rcentage of plication of e-learning		
		ESCRIPTION		
Course objectives	<ul> <li>understanding of compute</li> <li>design and applications of</li> </ul>	nciples and algorithms of compute r graphics technologies, computer graphics algorithms in ( graphical libraries in programming	C progran	
Course enrolment requirements and entry competences required for the course	None			
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	<ul> <li>transformation for view,</li> <li>recommend type of shadin</li> <li>critical argue on possibilitie technologies,</li> <li>model simpler objects with</li> <li>create simpler animations</li> </ul>	phical transformations in order to a ng and animation in order to achiev es and limitations of various displa n computer modelling software tool	ve desired y and har ls, ,	d result, dcopy
Course content broken down in detail by weekly class schedule (syllabus)	Course content Uvod Imageelements, vectorand ras interactivegraphicsconcept Basicalgorithmsofcomputergra Primitivesfillingandclipping Graphical hardware Antialiasing Geometrictransformations Objectsin 3D space Curvesandsurfaces Lightningandshading Animation List of laboratory exercises Introducton to OpenGL OpenGLexercise: Animation OpenGLexercise: Textures OpenGLexercise: Textures OpenGLexercise: Colorblendin OpenGLexercise: 3D Blender: modelling	phics	hours         2         2         2         4         2         4         2         3         2         3         2         3         2         3         2         3         2         3         2         3         2         3         2         3         2         3         2         3         2         3         2         3         2         3         2         3         2         3         3         3         3         3         3         3         3         3         3         3         3         3         3         3         3         3         3	hours hours
Format of instruction	Blender: animation ☐ lectures ☐ seminars and workshops ☐ exercises ☐ on line in entirety ☐ partial e-learning ☐ field work	<ul> <li>☑ independent assignment</li> <li>☑ multimedia</li> <li>☑ laboratory</li> <li>□ work with mentor</li> <li>□ (other)</li> </ul>	nts	4

Studentresponsibiliti es	The presence on lec Performed all require				0 % of the time	es schedu	led.
Screening student	Class attendance	1,5	Research		Practical traini	ng	
work (name the proportion of ECTS	Experimental work		Report		Individual worl	<	1,4
credits for eachactivity so that	Essay		Seminar essay	0,8	Laboratory exe	ercises	0,5
the total number of ECTS credits is equal to the ECTS	Tests	0,2	Oral exam		Preparation fo laboratory exe		0,5
value of the course)	Written exam	0,1	Project		(Other)		
Grading and evaluating student work in class and at the final exam	lecturing and the sec are answering parts exams are carried o The requirement for writtenandaccepted In finalgrading (inper seminar workwithmat (30%+30%+30%+10) Final grade isformed Percentage Grade 50% to 61% sufficient 62% to 74% good (3) 75% to 87% verygood 88% to 100% excelled	they did ut as wr passing seminal rcentage ax. 30% 0%). dinthefol nt (2) bd (4)	d not pass in the itten testsanditla grade is 50% p workandpositiv e), eachmidterm lab. exercisesw	midtern asts for r ooints on e asses examco	ns. The midtern nax. 60 minutes eachmidterme sment of labora ntributeswithma	n and fina s. xamorfina atory exer ax. 30%,	l alexam, cises.
Required literature (available in the library and via other		Title	)		Number of copies in the library	Availabi other r	-
media)	<ul> <li>T Papić, V.: Intro Facultytextbook,</li> </ul>			phics,		e-lear por	-
Optional literature (at the time of submission of study programme proposal) Quality assurance methods that ensure the acquisition of exit competences	<ul> <li>J.D.Foley, A.Dar PrinciplesandPra Company, 1996.</li> <li>D.Hearn, M.P.Ba 1996.</li> <li>F.S.Hill, Jr. i S.M Pearson education Shreiner, D., Wo Kompjuter bibliot</li> <li>Evaluation of res</li> <li>Feedback from s</li> <li>Self-evaluation of Institutional and</li> </ul>	actice (s aker, Co l. Kelley on, 2007 o, M., N <u>eka, 20</u> sults in a students of teach	econdeditionin C mputer Graphics , Computer Grap 7. eider, J., Davis, 07. accordance with s via surveys ers	C), Addis s, C Ver ohicsUsi T., Ope the abo	son-WesleyPub sion, Prentice F ngOpenGL, 3rc nGL vodič za p	lishing Iall; 2nd e d edition, rogramer	
Other (as the proposer wishes to add)							

NAME OF THE COURSE	PROGRAMMING LANGU	JAGES AND COMPILERS	6				
Code	FELK05	Year of study	1.				
Course teacher	Ivo Mateljan, Ph.D., FullProfessor Marjan Sikora, Ph.D., AssistantProfessor	Credits (ECTS)	5				
Associate teachers	Marjan Sikora, Ph.D., AssistantProfessor	Type of instruction (number of hours)	L 30	S 0	AE 0	LE 30	DE
Status of the course	Obligatory	Percentage of application of e-learning	0				
	COURS	E DESCRIPTION					
Course objectives	- Understandingoflexica	rative, OOP, functionaland Ianalysisand LL(1) and LF torsprograms: ELL, LEX a	R(1) par	sing	inglan	guage	s
requirements and entry competences required for the course	None						
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	functionalandlogicpro Define language gran Make recursive desce Make parser using El Make lexical analyser Make LR(1) parser us Define program struc Define attributed gran Make simple interpret	nmar with BNF and EBNF ent parser LL parser generator r using program LEX sing program YACC tures for compilers: symbo nmar and semantic action	ol tables s		AST		
	Course content				L hours		\E burs
	Historyandelementsofprog	ramminglanguages			2		
	Lexical, syntaticandseman	ticanalysis			2		
	Recursivedescentparser				2		
	Embeddingsemanticanalys	sis			2		
	Lexicalanalysisand DFA				2		
	Generatorsof LL and LR ta	able drivenparsers			2		
Course content	Attributedgrammar				2		
broken down in	Structures for semanticana				2		
detail by weekly	Assemblerandrun-time stru				2		
class schedule	Introduction to codegenera				2		
(syllabus)	Functionallanguages – Scl	heme			2		
	Logicallanguage – Prolog				2		
	Scriptlanguages				2	·	
	List oflaboratoryor design						nours
	Intepreterofmathematicalex	kpressions					2 2
	Using LEX						
	Using VAC						/
	Using YAC Interpreter design using LE	X and YACC					2
	Using YAC Interpreter design using LE Writingassembler program						2 2 2

	WritingScheme prog	ram						2
	Writing Prolog progra							2
Format of instruction	<ul> <li>☑ lectures</li> <li>☑ seminars and wor</li> <li>☑ exercises</li> <li>□ on linein entirety</li> <li>☑ partial e-learning</li> <li>□ field work</li> </ul>	kshops		⊡mul <sup>:</sup> □labo	ependen timedia oratory k with m (othe			
Studentresponsibiliti es								
Screening student work (name the	Class attendance	2	Researc	h		Practical traini	ng	
proportion of ECTS credits for	Experimental work		Report			Individualwork		2
eachactivity so that the total number of	Essay		Semina essay			Progr. Exercis	е	0.5
ECTS credits is	Tests		Oral exa	ım		Exercise test		0.2
equal to the ECTS value of the course)	Written exam	0.1	Project		0.2			
Grading and evaluating student work in class and at the final exam	laboratory exercise. of laboratory exercise Grade (in percentag the activities in perce • SR – semina • LV – laborat • UI – final ex	ses and e) is for Grac entage: ar, tory ass	50 % po med acco le(%) = 0	oints or	n each s o the for	seminar work o rmula: ' + 0,8 UI		
Required literature (available in the		Title	9			Number of copies in the library		bility via <sup>·</sup> media
library and via other media)	Ivo Mateljan: Prevoc FESB, 2004	ditelji i in	terpreter	, skript	a,		Inte	ernet
	LEX – manual, UNI>						-	ernet
	YACC – manual, UN	IIX					Inte	ernet
Optional literature (at the time of submission of study programme proposal)	Aho, Sethi, Ullman: 1986. A. Appel: ModernCo							
Quality assurance methods that ensure the acquisition of exit competences	<ul> <li>Evaluation of res</li> <li>Feedback from s</li> <li>Self-evaluation of</li> <li>Institutional and</li> </ul>	students of teach	s via surv ers	eys		ove learning out	comes	
Other (as the proposer wishes to add)								

NAME OF THE COURSE	OPTOELECTRONIC ME	ASUREMENT METHODS					
Code	FELG33	Year of study	1				
Course teacher	Ivo Stančić, Ph.D., Assistant Professor	Credits (ECTS)	5				
Associate teachers		Type of instruction (number of hours)	L 30	S	AE	LE 30	DE
Status of the course	Elective	Percentage of application of e-learning	0			30	
	COURS	E DESCRIPTION	I				
Course objectives	<ul> <li>Operate with linear, IR</li> <li>Apply camera to control</li> </ul>	principles of camera and op / night and heat cameras of industrial process or use ata from laser range finder	it as a s	senso			
Course enrolment requirements and entry competences required for the course							
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	<ul> <li>Apply algorithms for 3</li> <li>Apply algorithm for su</li> </ul>	e of camera and camera o 3D reconstruction of motior arface reconstruction ser range finders and creat	1				
	Course content		L hours		\E ours		
	Introduction to optoelectro	nics			2		
	Machinevisionaandcompu	tervision			2		
	Mathematicaldescriptionof	camerasandgeometryof a	space		4		
	Lenseoptical system andd		· ·			_	
		istorsions			2		
	Color system andphotoser				2		
	Color system andphotoser Inudstrialcameras, linearca	nsitivechips	tems		2		
	Inudstrialcameras, linearca	nsitivechips ameras, motioncapturesyst	tems		2 2		
	Inudstrialcameras, linearca	nsitivechips ameras, motioncapturesyst	tems		2 2 2		
	Inudstrialcameras, linearca IR camerasandapplication Stereovisionsystems	nsitivechips ameras, motioncapturesyst	tems		2 2 2 2		
Course content	Inudstrialcameras, linearca IR camerasandapplication Stereovisionsystems 3D scanners	nsitivechips ameras, motioncapturesyst s	tems		2 2 2 2 2 2		
broken down in	Inudstrialcameras, linearca IR camerasandapplication Stereovisionsystems 3D scanners Laser rangefindersand LID	nsitivechips ameras, motioncapturesyst s DAR	tems		2 2 2 2 2 2 2 2		
broken down in detail by weekly	Inudstrialcameras, linearca IR camerasandapplication Stereovisionsystems 3D scanners Laser rangefindersand LID Nightvisioncamerasandima	nsitivechips ameras, motioncapturesyst s DAR	tems		2 2 2 2 2 2 2 2 2 2		
broken down in detail by weekly class schedule	Inudstrialcameras, linearca IR camerasandapplication Stereovisionsystems 3D scanners Laser rangefindersand LID Nightvisioncamerasandima Future ofoptoelectronics	nsitivechips ameras, motioncapturesyst s DAR ageintensifiers	tems		2 2 2 2 2 2 2 2 2 2 2 2 2		
broken down in detail by weekly	Inudstrialcameras, linearca IR camerasandapplication Stereovisionsystems 3D scanners Laser rangefindersand LID Nightvisioncamerasandima Future ofoptoelectronics Introduction to optoelectro	nsitivechips ameras, motioncapturesyst s DAR ageintensifiers nics	tems		2 2 2 2 2 2 2 2 2 2		
broken down in detail by weekly class schedule	Inudstrialcameras, linearca IR camerasandapplication Stereovisionsystems 3D scanners Laser rangefindersand LID Nightvisioncamerasandima Future ofoptoelectronics Introduction to optoelectro List oflaboratoryor design	nsitivechips ameras, motioncapturesyst s DAR ageintensifiers nics exercises			2 2 2 2 2 2 2 2 2 2 2 2 2	hc	ours
broken down in detail by weekly class schedule	Inudstrialcameras, linearca IR camerasandapplication Stereovisionsystems 3D scanners Laser rangefindersand LID Nightvisioncamerasandima Future ofoptoelectronics Introduction to optoelectro List oflaboratoryor design Introduction to Matlab: image	nsitivechips ameras, motioncapturesyst s DAR ageintensifiers nics exercises ge loading, capture and ed	liting		2 2 2 2 2 2 2 2 2 2 2 2 2	hc	ours 2
broken down in detail by weekly class schedule	Inudstrialcameras, linearca IR camerasandapplication Stereovisionsystems 3D scanners Laser rangefindersand LID Nightvisioncamerasandima Future ofoptoelectronics Introduction to optoelectro List oflaboratoryor design Introduction to Matlab: ima Introduction to Matlab: vide	nsitivechips ameras, motioncapturesyst s DAR ageintensifiers nics exercises ge loading, capture and edi to loading, capture and edi	liting		2 2 2 2 2 2 2 2 2 2 2 2 2	hc	ours 2 2
broken down in detail by weekly class schedule	Inudstrialcameras, linearca IR camerasandapplication Stereovisionsystems 3D scanners Laser rangefindersand LID Nightvisioncamerasandima Future ofoptoelectronics Introduction to optoelectro List oflaboratoryor design Introduction to Matlab: ima Introduction to Matlab: ima Introduction to Matlab: vide Camera calibration and dis	nsitivechips ameras, motioncapturesyst s DAR ageintensifiers nics exercises ge loading, capture and edi tortion removal	liting ting		2 2 2 2 2 2 2 2 2 2 2 2 2	hc	ours 2 2 2 2
broken down in detail by weekly class schedule	Inudstrialcameras, linearca IR camerasandapplication Stereovisionsystems 3D scanners Laser rangefindersand LID Nightvisioncamerasandima Future ofoptoelectronics Introduction to optoelectro List oflaboratoryor design Introduction to Matlab: ima Introduction to Matlab: ima Introduction to Matlab: ima Introduction to Matlab: vide Camera calibration and dis Movement reconstruction f	nsitivechips ameras, motioncapturesyst s DAR ageintensifiers nics exercises ge loading, capture and edi tortion removal rom single camera in single	liting ting e plane		2 2 2 2 2 2 2 2 2 2 2 2 2	hc	ours 2 2 2 2 2
broken down in detail by weekly class schedule	Inudstrialcameras, linearca IR camerasandapplication Stereovisionsystems 3D scanners Laser rangefindersand LID Nightvisioncamerasandima Future ofoptoelectronics Introduction to optoelectron List oflaboratoryor design Introduction to Matlab: ima Introduction to Matlab: ima Introduction to Matlab: ima Introduction to Matlab: vide Camera calibration and dis Movement reconstruction f	nsitivechips ameras, motioncapturesyst s DAR ageintensifiers nics exercises ge loading, capture and edi tortion removal rom single camera in single	liting ting e plane		2 2 2 2 2 2 2 2 2 2 2 2 2	hc	ours 2 2 2 2 2 2 2
broken down in detail by weekly class schedule	Inudstrialcameras, linearca IR camerasandapplication Stereovisionsystems 3D scanners Laser rangefindersand LID Nightvisioncamerasandima Future ofoptoelectronics Introduction to optoelectro List oflaboratoryor design Introduction to Matlab: ima Introduction to Matlab: ima Introduction to Matlab: ima Introduction to Matlab: vide Camera calibration and dis Movement reconstruction f	nsitivechips ameras, motioncapturesyst s DAR ageintensifiers nics exercises ge loading, capture and edi tortion removal rom single camera in single vith stereovision system in	liting ting e plane		2 2 2 2 2 2 2 2 2 2 2 2 2	hc	ours 2 2 2 2 2
broken down in detail by weekly class schedule	Inudstrialcameras, linearca IR camerasandapplication Stereovisionsystems 3D scanners Laser rangefindersand LID Nightvisioncamerasandima Future ofoptoelectronics Introduction to optoelectron List oflaboratoryor design Introduction to Matlab: ima Introduction to Matlab: ima Introduction to Matlab: vide Camera calibration and dis Movement reconstruction f Movement reconstruction v Laser and IR rangefinders	nsitivechips ameras, motioncapturesyst s DAR ageintensifiers nics exercises ge loading, capture and edi tortion removal rom single camera in single vith stereovision system in econstruction	liting ting e plane		2 2 2 2 2 2 2 2 2 2 2 2 2		ours 2 2 2 2 2 2 2 2 2 2
broken down in detail by weekly class schedule	Inudstrialcameras, linearca IR camerasandapplication Stereovisionsystems 3D scanners Laser rangefindersand LID Nightvisioncamerasandima Future ofoptoelectronics Introduction to optoelectro List oflaboratoryor design Introduction to Matlab: ima Introduction to Matlab: vide Camera calibration and dis Movement reconstruction f Movement reconstruction v Laser and IR rangefinders 3D scanners and surface reconstruction	nsitivechips ameras, motioncapturesyst s DAR ageintensifiers nics exercises ge loading, capture and edi tortion removal rom single camera in single vith stereovision system in econstruction	liting ting e plane space		2 2 2 2 2 2 2 2 2 2 2 2 2		ours 2 2 2 2 2 2 2 2 2 2 2

Format of instruction	□ lectures □ seminars and workshops □ exercises □ on linein entirety □ partial e-learning □ field work								
Studentresponsibiliti es									
Screening student work (name the	Class attendance	1	Research			Practical traini	ng		
proportion of ECTS credits for	Experimental work	perimental work Report I			Impended rese	earch	1,7		
eachactivity so that the total number of	Essay		Seminar essay		1	Laboratory exe	ercises	1	
ECTS credits is	Tests	0,2	Oral exam	۱		(Other)			
equal to the ECTS value of the course)	Written exam	0,1	Project			(Other)			
	During the semester project assignments							endar or	
	The requirement for and 50 % points on a are allowed to have the final midterm ave Midterm consists of midterms consist of	average at least erage is of both	midterm ex 45% of tota at least 50 theoretical	kam (( al poir % of t l que	M1 + M nts on e otal poi stions	2)/2) or the fina each midterm e nts. and numerical	l exam. S xams, as problem	tudents long as is. The	
Grading and	into two groups.	4 90030					100300113	aiviaca	
evaluating student work in class and at	In determining the fi (or project assignme								
the final exam	Final grade (based on percentages) is formed as follows:								
	Percentage         Grade           50% do 62%         sufficient (2)           63% do 74%         good (3)           75% do 86%         very good (4)           87% do 100%         excellent (5)								
	In case student does not complete midterms or project exams he/she needs to take the final exam in which case it contributes with 60% toward final grade, and laboratory exercises again with 40%.								
Required literature		Title	)			Number of copies in the library	Availabi other r	-	
(available in the library and via other media)	<ul> <li>Hartley, R., Zisse 'Multipleviewgeo (Cambridge Univ</li> </ul>	metrying	computervis						
, ,	<ul> <li>Shapiro, G., Stoo (Prentice-Hall, 20)</li> </ul>		G.C.: 'Com	puter	vision'				
Optional literature (at the time of submission of study programme proposal)									
Quality assurance methods that ensure the acquisition of exit competences	<ul> <li>Annual analysis</li> <li>Feedback from s</li> </ul>	<ul> <li>Keeping records of student attendance.</li> <li>Annual analysis of course statistics in terms of midterm and finals exams.</li> <li>Feedback from students via surveys.</li> <li>Teacher self-evaluation.</li> </ul>							

	- Feedback from graduated students (or senior students) on course content relevance.
Other (as the proposer	/
wishes to add)	

NAME OF THE COURSE	ADVANCED COMPUTER	ADVANCED COMPUTER ARCHITECTURES							
Code	FELK07	Year of study	1						
Course teacher	Sven Gotovac, Ph.D., FullProfessor	Credits (ECTS)	5						
Associate teachers	Dunja Gotovac, TeachingAssistant	Type of instruction (number of hours)	L 30	S	AE	LE 30	DE		
Status of the course	Obligatory	Percentage of application of e-learning	0						
	COURS	E DESCRIPTION							
<ul> <li>Course objectives</li> <li>Training students for:         <ol> <li>Recognize the architecture of modern computer systems.</li> <li>Choose the appropriate computer architecture according to the problem being solved computer architecture</li> <li>Estimates the impact of computer architecture and its components on system performance</li> <li>Develop, adapt and implement solutions on multi-processor and multi-core systems.</li> </ol> </li> </ul>									
Course enrolment requirements and entry competences required for the course	Computer Architecture								
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	Learning outcomes expected at the level of the course (4 to 10 learningStudents will be able to:1.Understand the Architecture of Modern Computer Systems2.Determine the impact of individual components on the performance of a computer system3.Choose the appropriate computer architecture according to the problem being actual								
	Course content				L		\E ours		
Course content broken down in detail by weekly	Introduction to the course, Brief description of the topics to be considered, Brief subjects from the course Digital Architecture: Programming Architecture, Pipeline, Fast Memory								
class schedule	Pipeline architecture				2				
(syllabus)	Instruction execution paral		tions.		2				
	Out of Order Execution. Br				2				
	Cache. Various Cache Arc	hitecture			2				

	Memory Performance	e Optim	ization				2	
	ChipSet	•					2	
	MESI Protocol						2	
	Multi Core Processo	ors					2	
	Many Core Process	or – Xec	n Phi				4	
	Graphical Processin						4	
	Application Example	-					4	
	List oflaboratoryor d		ercises				L	LE hours
		lulti-threading programming. Performance exmples						
	Cache impact on exe		performar	nce				4 4
		PU CUDA Programming						
	Problem implementa				y-Core	and CUDA		14
	architecture. Perform ⊠lectures	lance co	mpansor	l.				
	Seminars and wor	kshons			•	t assignmer	nts	
		Konopo			imedia			
Format of instruction	$\Box$ on line in entirety			⊠labo	-			
	□partial e-learning				c with m			
	☐field work				(othe	er)		
Studentresponsibiliti	The presence on lec	tures in	the amo	unt of a	t least 7	0 % of the t	times sche	eduled.
es	Performed all require							
Screening student	Class attendance	1	Researc	h		Practical tra	aining	
work (name the proportion of ECTS	Experimental work	0	Report		1	Laboratory	_	5 1
credits for	_		Seminar	•		Preparation for		
eachactivity so that the total number of	Essay		essay			laboratory exercises		0,5
ECTS credits is	Tests		Oral exa	ım		Self-study		0,5
equal to the ECTS value of the course)	Written exam		Project		1			
Grading and evaluating student work in class and at the final exam	Written exam         Project         1           There are two midterms and final exams. The first midterm exam is after 7 weeks of lecturing and the second one is after the next 6 weeks. First midterm test lasts 60 minutes and consists of 5 to 7 theoretical questions and numerical problems, second midterm is practical example and final tests consist of 6 theoretical questions and numerical problems and example solving. In the final exams students that did not pass the midterm exams take part. The midterm and final exams are carried out as written tests. The requirement for passing grade is the positive assessment of laboratory exercises and 50 % points on each midterm exam or the final exam. Grade (in percentage) is formed according to the formula: Grade(%) = 0,33 LV + 0,33 (M1 + M2)           the activities in percentage:         •           LV – laboratory assessment,         •           M1, M2 – test results.         The group of students who passed the exam is divided into four groups: 15% of the best gets the grade A (excellent), 35% of the following B (very good), the next 35% rating C (good), and the last 15% rating D, E           ). A group of students who did not pass the exam gains FX score (additional work is required), or F (significant additional work is required). In accordance with the Rulebook for Exam, only two exam periods are organized in the exam period after the completion of classes.           According to Article 65 of the Statute of the Faculty, the student is obliged to participate in all forms of teaching and attend: lectures at least 70% of teaching hours							

	Title	Number of copies in the library	Availability via other media				
Required literature (available in the library and via other media)	<ul> <li>Hennesy&amp; Patterson, "Computer Architecture: A QuantitativeApproach", 5rd edition, Morgan Kaufmann, 2011.</li> </ul>	2	Electronic copy On e-learning				
	<ul> <li>Edward Kandrotand Jason Sanders, CUDA byExample: An Introduction to General-Purpose GPU, NVidi, 2010.</li> </ul>	1	Electronic copy On e-learning				
Optional literature (at the time of submission of study programme proposal)	<ul> <li>Ribarić, S.: Naprednije arhitekture mikroprocesora, Tehnička knjiga, Zagreb</li> </ul>						
Quality assurance methods that ensure the acquisition of exit competences	<ol> <li>Class attendance records.</li> <li>Evaluation of results in accordance with the above learning outcomes</li> <li>Feedback from students via surveys</li> <li>Self-evaluation of teachers</li> <li>Feedback from students who have already graduated.</li> <li>Institutional and non-institutional evaluations</li> </ol>						
Other (as the proposer wishes to add)							

NAME OF THE COURSE	DATA WAREHOUSE								
Code	FELK16	Year of study 1.							
Course teacher	Stipo Čelar, Ph.D., Associate Professor	Credits (ECTS)	(ECTS) 5						
Associate teachers		Type of instruction	L	S	AE	LE	DE		
Associate teachers		(number of hours)	30			30			
Status of the course	Elective Percentage of application of e-learning 0								
COURSE DESCRIPTION									
Course objectives	business systems, - understanding of the I	plying of dimensional data ht,			ation s	system	s and		
Course enrolment requirements and entry competences required for the course	The students should previously pass one of the two courses s and entry s required - Databases or understand the concept of relational database (if this course is emroled								
Learning outcomes expected at the level	Students will be able to:								

of the course (4 to 10 learning outcomes)	<ul> <li>define the role, advantages and technologies of DW in information systems and business systems,</li> <li>identify and critically evaluate DW architectures for a small business system (up to 10 dimensions),</li> <li>design a dimensional model for a small business system,</li> <li>develop a whole DW project for a small business system,</li> <li>work as a part of a larger DW project team.</li> </ul>							
	Course content						L	AE
		Maraha		`\			hours 2	hours
	Introduction to Data DW technologies & o		•	)			2	
	DW technologies & O	t	2					
	DW history and char		2					
	Business processes						2	
	ETL	(introduc					2	
	Dimensional model.	Star scl	nema vs.	snowfla	ake sch	ema	2	
	First midterm pause			01101110		onna		
	Fact table. Example						2	
Course content	Dimensional table. S		e kevs. E	xample	S		2	
broken down in	DW projects and me				-		2	
detail by weekly	OLAP tools and ana		•	r			2	
class schedule	Business Intelligence						2	
(syllabus)	DW projects exampl		Ŭ				2	
	Second midterm par							
	List of laboratory exe							LE hours
	Introduction to the wo					teams		2
	Installation and configuration of DW environment.							
	Business process (B		2					
	BP analysis – <i>short µ</i> DW architecture desi		2					
	Dimensional model c		4					
	DW physical design		2					
	DW detailed design (		4					
	OLAP cube							4
	Reporting – short pre	esentatio	on					2
Format of instruction	<ul> <li>☑ lectures</li> <li>□ seminars and wo</li> <li>☑ exercises</li> <li>□ on line in entirety</li> <li>□ partial e-learning</li> <li>□ field work</li> </ul>	rkshops		□ mul ⊠ labo	timedia	nentor	nts	
Studentresponsibiliti es	The presence on lect Well made (written r						times sche	eduled.
Screening student	Class attendance	1	Researc	h	0,8	Practical tr	aining	1
work (name the proportion of ECTS	Experimental work		Report			Individual	work	1
credits for eachactivity so that	Essay		Semina essay			Laboratory		s 0,2
the total number of ECTS credits is equal to the ECTS	Tests		Oral exa	am	0,5	Preparation laboratory		
value of the course)	Written exam		Project		0,5	(Oth	ner)	
Grading and evaluating student	There is no midterm work on a practical p done in small projec	oroject –	they cre	ate you	r own D	ata Wareho	ouse. The	project is

work in class and at the final exam	their work on a project (business problem, concept, model, design, reports) several times in a semester. The exam is taken individually or in small groups (project teams), carried out as practical oral exam (based on team's project). The exam is public and may be attended by all students who had passed it already. Grade (in percentage) is formed according to the formula: Grade(%) = 0,8 OE + 0,2 LE							
	<ul> <li>the activities in percentage:</li> <li>OE – oral exam,</li> <li>LE – laboratory assessment (<i>written project</i>)</li> </ul>	material).						
	Title	Number of copies in the library	Availability via other media					
Required literature (available in the library and via other media)	• S. Čelar: Authorised lectures, FESB		e-learning portal					
	<ul> <li>William Inmon: Building the Data Warehouse (2005) John WileyandSons, ISBN 978-81-265- 0645-3</li> </ul>							
	<ul> <li>Kimball, R., Ross, M.: The Data Warehouse Toolkit, TheDefinitiveGuide to DimensionalModeling, Third Edition, John Wiley&amp;Sohns, 2013</li> </ul>							
	<ul> <li>S. Čelar: Authorised instructions for laboratoryexercises, FESB</li> </ul>		e-learning portal					
Optional literature (at the time of	<ul> <li>Kimball, R., Ross, M.: The Data Warehouse Tool DimensionalModeling, SecondEdition, Wiley Con</li> </ul>							
submission of study programme proposal)	Todman, C.: Designing a Data Warehouse: Supp Management, 1st Edition, Prentice Hall PTR, ISE							
Quality assurance methods that ensure the acquisition of exit competences	<ul> <li>Evaluation of results in accordance with the above</li> <li>Feedback from students via surveys</li> <li>Self-evaluation of teachers</li> <li>Institutional and non-institutional evaluations</li> </ul>	ove learning ou	utcomes					
Other (as the proposer wishes to add)								

NAME OF THE COURSE	COMPUTER GAMES PROGRAMMING								
Code	FELK34	Year of study	1.						
Course teacher	Jadranka Marasović, Ph.D., FullProfessor	Credits (ECTS)	5						
Associate teachers	Tea Marasović, Ph.D., AssistantProfessor	Type of instruction (number of hours)	L 30	S 0	AE 0	LE 30	DE 0		
Status of the course	Elective	Percentage of	0						
	COURS	application of e-learning							
Course objectives	Enabling students to acqui and development of compo- by working through differ programming.	re basic theoretical and pr uter video games – from co	oncept	to fina	l imple	ementa			
Course enrolment requirements and entry competences required for the course	None								
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	<ul> <li>use Unity game develo content;explain how the</li> <li>build a simple world us animated characters in</li> <li>arrange and edit basic</li> <li>use C# programming la</li> <li>incorporate artificial interview</li> </ul>	ter completing this course, students will be able to: use Unity game development platform to create interactive 2D and 3D content;explain how the physics engine works; build a simple world using built-in primitive shapes, readily available assets and animated characters imported from 3D modelling programs; arrange and edit basic GUI elements; use C# programming language to set up basic game functionality; incorporate artificial intelligence in the game; make a simple computer video game and prepare it for publishing.							
	Course content				L hours		\E ours		
	Introduction. History of cor	nputer games.			2		0		
	General game development				2		0		
	Getting started with Unity. objects. Materials and text	3	2		0				
	Scripting in Unity.				2		0		
	Designing the game's GUI clocks.	: buttons, sliders, status ba	ars and		4		0		
	Introduction to game physi and object interaction. Dis	playing results.		on	2		0		
Course content	Adding sound effects and	·	ras.		2		0		
broken down in	Particle systems. Skeletal				2		0		
detail by weekly class schedule	Multi-player games. Tic Ta				2		0		
(syllabus)	Artificial intelligence in gan				4	_	0		
	Lighting the world. Creatin	<u> </u>			2		0 nours		
	List oflaboratoryor design exercises								
	Making a simple game: Po						2		
	Making a simple collection						2		
	Maze game: Setting up bas						2		
	Maze game: Animating obj						2		
	Maze game: Saving and loading the game.						2 2		
	3D puzzle game: Level design. Light maps.								
	3D puzzle game: Staging p		oting	01/0	0.04	+	2		
	3D puzzle game: Importing mechanics.	animated characters. Cre	aung m	overn	ent		4		

	3D puzzle game: The	e game	manager.				2			
Format of instruction	<ul> <li>☑ lectures</li> <li>☑ seminars and worl</li> <li>☑ exercises</li> <li>☑ on linein entirety</li> <li>☑ partial e-learning</li> <li>☑ field work</li> </ul>	□ seminars and workshops       □ multimedia         □ exercises       □ multimedia         □ on linein entirety       □ work with         □ partial e-learning       □ (ott)					,			
Studentresponsibiliti es	Minimum of 70 perce exercises.	ent lectu	ire attendance.	Complet	ing all the requi	ired labor	atory			
Screening student work (name the	Class attendance	1.5	Research	Practical traini	ng					
proportion of ECTS credits for	Experimental work		Report		Individual work	(	1			
eachactivity so that the total number of	Essay		Seminar essay		Laboratory exe	ercises	1.5			
ECTS credits is	Tests	0.5	Oral exam		(Other)					
equal to the ECTS value of the course)	Written exam	0.5	Project		(Other)					
Grading and evaluating student work in class and at the final exam	62% to 74% goo 75% to 87% very	ssignme positiv and a m etermine s: G de icient (2 d (3) /good (4 ellent (5 compass pass a entire co	ent, depending o ve grade is the ninimum of 40 per- ed based on the rade [%] = 0.5 * () () () () () () () () () ()	n the ag e attend ercent co total nu M1 + 0. 0urse lo d-term require	preement with the ance and comported answers a mber of points 5*M2 pad or selected exams. The of ment for pass	he studer nmitment at each m earned, v earned, v correction ing the e	f it that exam is			
Required literature (available in the library and via other		Title	•		Number of copies in the library	Availab other i	•			
media)	1. T. Marasović, J	. Maras	ović; Authorized	lectures		e-Lea por	-			
Optional literature (at the time of submission of study programme proposal)	<ol> <li>T. Miller; "Begini 672-32661-2.</li> <li>K. C. Finney; "3I 1-59200-136-X.</li> <li>S. Blackman; "B ISBN: 978-1-430</li> </ol>	D Game eginning	Programming A g 3D Game Dev	All in One	e", Premier Pre	ss, 2004.	ISBN:			
Quality assurance methods that ensure the acquisition of exit competences	<ul> <li>Keeping records on class attendance</li> <li>Annual analysis of exam results</li> <li>Student survey on teaching performance</li> <li>Teacher self-evaluation</li> <li>Feedback information from graduates regarding course content relevancy</li> </ul>									
Other (as the proposer wishes to add)										

NAME OF THE COURSE	MULTIMEDIA SYSTEMS								
Code	FELK08	Year of study	2.						
Course teacher	Mladen Russo, Ph.D., Assistant Professor	Credits (ECTS)	5						
Associate teachers	Jelena Čulić, mag. ing. Martina Bašić, mag. ing.	Type of instruction (number of hours)	L 30	S 0	AE 0	LE 30	DE 0		
Status of the course	Obligatory	Percentage of application of e-learning	0	•	Ů	00	0		
COURSE DESCRIPTION									
<ul> <li>Course objectives</li> <li>Training students for:         <ul> <li>understanding of multimedia systems and virtual reality</li> <li>knowledge of the properties and methods for generating speech, audio, image and video signals (including 3D images and video)</li> <li>understanding of the most important algorithms for compressing speech, audio, image and video signals</li> </ul> </li> </ul>									
Course enrolment requirements and entry competences required for the course	None.								
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	<ul> <li>explain the basic princ compression of audio s</li> <li>demonstrate the freque define the most import and video signals</li> </ul>		nd their	r appli spee	cation		age		
	Course content				L		λE		
	Introduction. History of mu Overview of multimedia so applications.				hours 2		ours 0		
	Audio signal. How humans modelling.	hear and speak. Speech			2		0		
Course content broken down in	Generic compression tech specific algorithms (mp3).				2		0		
detail by weekly class schedule (syllabus)	Speech specific algorithms and applications in mobile encoding speech and audi	dards fo	or	2		0			
(Jynabus)	Color in images and video people perceive electroma colors.			2		0			
	Color models for image sig models for video signal (Yt color models (HSB, HLS, H signal (resolution, depth, m formats (gif, tiff, jfif, ps, bm	ed	2		0				

work in class and at the final exam	Grade(%) = 0,5*M1+0,5*M2; M1, M2 – midterm test results. The final grade is determined as follows: Percentage Grade 50% to 61% sufficient (2) 62% to 74% good (3) 75% to 87% very good (4) 88% to 100% excellent (5)							
During a semester there are two midterms and final exam. Final exam and midterms are held according to the calendar of classes. At the final exam students take the test from the complete course if they do not have a positive grade on the midterms or take the midterm that they did not pass. At the make-up and commission exam students take the test from the complete course.Grading and evaluating studentThe requirement for passing grade is 50% points on each midterm exam or the final exam. Grade (in percentage) is formed according to the formula:								
equal to the ECTS value of the course)	Written exam	0,1	Project			(Oth	•	
the total number of ECTS credits is	Tests	0,2	essay Oral exa	m		(Oth		
proportion of ECTS credits for eachactivity so that	Experimental work Essay		Report Seminar			Individual v		1,7
Screening student work (name the	Class attendance	3	Researc	h		Practical tra	0	
Studentresponsibiliti es	The presence on lect Performed all require				t least 7	0 % of the t	imes sche	eduled.
Format of instruction	<ul> <li>☑ lectures</li> <li>□ seminars and wor</li> <li>☑ exercises</li> <li>□ on line in entirety</li> <li>□ partial e-learning</li> <li>□ field work</li> </ul>	rkshops		□ mul ⊠ labo	ependen timedia oratory k with m (othe		nts	
	CAVE system							2
	Multimedia systems o 3D images	on mobi	le device	s (Andr	old prog	ramming)		2
	Multimedia systems o	on mobi	le device	s (Andr	oid prog	ramming)		2
	Multimedia systems					ramming)		2
	Image compression ( MPEG – influence of	· ,	rames or	video	nuality			2
	Image compression (	,						2
	Image compression (	JPEG)						2
	Frequency masking 3D sound							2
	Speech specific algo	rithms (	LPC)					2
	Sound recording. Sea			and ur	voiced s	speech. Pito	ch period.	2
	vision. Software and	ision. Software and hardware for virtual reality.						
	Fundamentals of virt	ual real				: (3D)	2	0
	Video compression:						2	0
	Video compression:			-2.			2	0
	Video compression: Video compression:			2			2	0
	Image compression.						2	0
	Digital television and requirements.			mats a	nd mem	ory	2	0
	Basics of video and						_	

Required literature (available in the library and via other	Title	Number of copies in the library	Availability via other media
media)	H. Dujmić: Multimedijskisustavi, internal script	1	e-learning portal
Optional literature (at the time of submission of study programme proposal)	<ul> <li>Steinmetz, Nahrstedt: "Multimedia Fundamentals Processing", Prentice Hall, 2002</li> <li>Rao, Bojkovic, Milovanovic: "Multimedia Commun StandardsandNetworks", Prentice Hall, 2002</li> </ul>		-
Quality assurance methods that ensure the acquisition of exit competences	<ul> <li>Evaluation of results in accordance with the above</li> <li>Feedback from students via surveys</li> <li>Self-evaluation of teachers</li> <li>Institutional and non-institutional evaluations</li> </ul>	e learning out	comes
Other (as the proposer wishes to add)			

NAME OF THE COURSE	GRID COMPUTING SYST	RID COMPUTING SYSTEMS								
Code	FELK11	Year of study	2.							
Course teacher	Eugen Mudnić, Ph.D., Assistant Professor	Credits (ECTS)	5							
Associate teachers		Type of instruction	L	S	AE	LE	DE			
Associate teachers		(number of hours)	30	0	30					
Status of the course	Obligatory	Percentage of application of e-learning	0							
	COURSE	E DESCRIPTION								
Course objectives	Training students for									

					computing systems				
	<ul> <li>Further evolving computing syst</li> </ul>	•	wledge a	nd skill:	s for design and us	se of distrib	outed		
Course enrolment requirements and entry competences required for the course	Previously taken cou languages.	urses : D	Distributed	d comp	uting systems, Pro	gramming			
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	<ul> <li>Install and use v</li> <li>Install and use 0</li> <li>Write and executive</li> </ul>	Determine applicability of grid computing for different computational tasks. Install and use virtualized computer environments. Install and use Grid computing system. Write and execute complex jobs in Grid environment. Determine job costs and performance in Grid environment.							
	Course content					L hours	AE hours		
	Introduction to Grid s Grid computing.	systems	. Techno	logical	background of	2	2		
	Grid architecture and	d functio	onality.			2	2		
	Grid systems classif	ication.				2	2		
	Virtualization and Gr	id syste	ms.			2	2		
	Grid data manageme	ent – fui	nctions, r	equiren	nents	2	2		
	Replication and effic	ient dat	a manage	ement.		2	2		
	Metadata in Grid sys					2	2		
	Job brokering for Gr		ms.			2	2		
Course content	First midterm exam	,							
broken down in	Job scheduling algo	rithms fo	or paralle	compu	iters	2	2		
detail by weekly	Job scheduling algo		-			2	2		
class schedule (syllabus)	HTCondor - distributed parallelization of computationally 2 intensive tasks								
	Grid security					2	2		
	Cloud computing sys	stems				2	2		
	Second midterm exa					2	2		
	List of laboratory exe					2	LE hours		
Format of instruction	<ul> <li>☑ lectures</li> <li>☑ seminars and workshops</li> <li>☑ exercises</li> <li>☑ on line in entirety</li> <li>☑ partial e-learning</li> <li>☑ independent assignments</li> <li>☑ independent assignments</li> <li>☑ multimedia</li> <li>□ laboratory</li> <li>□ work with mentor</li> </ul>								
	☐ field work				(other)				
Studentresponsibiliti es	The presence on lec	tures in	the amo	unt of a	t least 70 % of the	times sche	eduled.		
Screening student	Class attendance	1,7	Researc	:h	Practical t	raining			
work (name the proportion of ECTS	Experimental work		Report		Individual	work	2,0		

credits for eachactivity so that the total number of	Essay		Seminar essay		Laboratory exe	ercises	0,0		
ECTS credits is equal to the ECTS	Tests	0,2	Oral exam		Preparation fo laboratory exe		0,0		
value of the course)	Written exam	0,1	Project	1,0	(Other)				
Grading and evaluating student work in class and at the final exam	<ul> <li>There are two midterms and final exams. The first midterm exam is after 7 weeks of ecturing and the second one is after the next 6 weeks. Each midterm test consists of 20 questions and final tests consist of 20 theoretical questions and numerical problems. In the final exams students that did not pass the midterm exams take part. The midterm and final exams are carried out as written tests. The requirement for passing grade is 50 % points on each midterm exam or the final exam. Final grade in percentage) is formed according to the formula:</li> <li>Grade(%) = 0.1 NP + 0.45 (M1 + M2)</li> <li>The activities in percentage:</li> <li>NP - attendance at lectures,</li> <li>M1, M2 – test results.</li> </ul>								
Required literature (available in the		Title	•		Number of copies in the library	Availabi other r	-		
	E. Mudnić: Author				copies in		nedia		
(available in the library and via other	E. Mudnić: Author Introduction to Grid ( Kumar, CRC Press,	orised Le	ectures, FESB ing, Frédéric Ma		copies in the library	other r e-learnin portal	nedia Ig		
(available in the library and via other media) Optional literature (at the time of submission of study programme	Introduction to Grid	Comput Taylor & sults in a students of teacher	ectures, FESB ing, Frédéric Mag & Francis Group, accordance with a via surveys ers titutional evaluat	2009 the abc	copies in the library Jie Pan, Kiat-A	other r e-learnin portal n Tan, At	nedia Ig		

NAME OF THE COURSE	BUSINESS INFORMATION SYSTEMS										
Code	FETK01	Year of study 2.									
Course teacher	Stipo Čelar, Ph.D., Associate Professor	Credits (ECTS)	5								
Associate teachers	MiliTurić, mag. comp.	Type of instruction	L	S	AE	LE	DE				
Associate teachers	Ivan Drnasin, mag. Comp.	(number of hours)	30			30					
Status of the course	Obligatory	Percentage of application of e-learning	0								
	COURSE	E DESCRIPTION									
Course objectives		lication of Business Inform lyse of product's and mate ormation systems (IS),									

	- understanding of							110	
Course enrolment	<ul> <li>application of design of design of design of the second sec</li></ul>	sign, im	plementa	ition and	d mainte	enance of tra	ansactiona	IIS.	
requirements and entry competences required for the course	None								
Learning outcomes expected at the level of the course (4 to 10 learning outcomes)	<ul> <li>design a small B</li> <li>participate in dev</li> <li>choose technologious</li> <li>business environ</li> </ul>	classify different types of BIS, design a small BIS, participate in development, implementation and maintenance of ERP solutions, choose technologically and functionally adequate BIS solution for a bigger business environments, plan and manage a larger BIS implementation project.							
	Course content						L	AE	
	Introduction to Busir BIS inthebusiness	iess Info	ormation	System	s (BIS).	Role of	hours 2	hours	
	BIS types						2		
	BIS development me	athodolo	nies LIM		<b>)</b>		2		
	Business Process M		· ·				2		
	Process. Event. Info		·	ont Eur	otion		2		
							2		
	The basic concepts Financial and accou					of			
	document managem	• •	0003303.	ine pro	1003503	5 01	2		
	First midterm exam	ion i							
Course content	Item - the product - (	repro) r	naterial -	raw ma	aterials -	_	0		
broken down in	commodities in busi						2		
detail by weekly class schedule	Work order. Bill of M						2		
(syllabus)	Types of production Traceability	(discret	e, proces	s, repe	atable).		2		
	Price calculation (pu	rchase	and prod	uction).	VAT ca	alculation	2		
	MRP and ERP syste	ms. Clo	oud syste	ms			2		
	Methodologies selection		-		formatio	on systems	2		
	Second midterm exa								
	List of laboratory exe	ercises						LE hours	
	Introduction to the wo	ork meth	nod. Defir	ning of I	oroject	eams and s	eminar	2	
	Weekly meetings wit	h a men	tor (profe	essor / a	assistar	t)		4	
	Exercisesinthe test E					7		10	
	Exercisesinthe test s				ЗУ			6	
	Seminar presentatior	n (with c	olleague	s)				4	
	☑ lectures			inde	anendei	nt assignme	nts		
	$\boxtimes$ seminars and wo	rkshops			timedia	-	into		
Format of instruction	⊠ exercises				oratory				
	□ on line in entirety				k with n	nentor			
	□ partial e-learning				(othe				
<u> </u>	☐ field work				``				
Studentresponsibiliti es	The presence on lect Performed all require				t least 7	0 % of the t	times sche	duled.	
Screening student work (name the	Class attendance	1	Researc	ch	0,4	Practical tra	aining		
proportion of ECTS credits for	Experimental work		Report			Individual v	work	2	
eachactivity so that	Essay		Semina essay	r	0,5	Laboratory	exercises	0,7	

the total number of					Prepar	ation fo	or.		
ECTS credits is	Tests	0,2	Oral exam	0,2	laborat			s	
equal to the ECTS value of the course)	Written exam		Project			(Other)		-	
Grading and evaluating student work in class and at the final exam	<ul> <li>There are two midterms and final exams. The first midterm exam is after 7 weeks of ecturing and the second one is after the next 6 weeks of lecturing. Each midterm est consists of 5 to 10 theoretical questions and numerical problems. The final test consists of aprox. 10 theoretical questions and numerical problems. In the final exams students that did not pass the midterm exams take part. The midterms and inal exams are carried out as written tests. The requirement for passing grade is he positive assessment of laboratory exercises and 50 % points on each midterm exam or the final exam. After that the students take the oral exam.</li> <li>Brade (in percentage) is formed according to the formula: Grade(%) = 0,3 OE + 0,2 LE + 0,25 (M1 + M2)</li> <li>he activities in percentage:</li> <li>OE – oral exam,</li> <li>LE – laboratory assessment,</li> <li>M1, M2 – test results.</li> </ul>								erm Il test Il and e is
		Title						ilabilit er med	
Required literature (available in the	• S. Čelar: Authori	S. Čelar: Authorised lectures, FESB					е	learni porta	-
library and via other media)	<ul> <li>S. Čelar: Authoris FESB</li> </ul>	sed inst	ructions for semi	nar,			e	learni porta	•
	<ul> <li>M. Turić; S. Čela laboratoryexercis</li> </ul>			s for			e	learni porta	•
Optional literature (at the time of submission of study programme proposal)	Nancy H. Bancro UpperSaddleRive			SAP R/3	3. Prenti	ce Hall	PTR	,	
Quality assurance methods that ensure the acquisition of exit competences	<ul> <li>Feedback from</li> <li>Self-evaluation</li> </ul>	student of teacl			ove leai	rning o	utcom	ies	
Other (as the proposer wishes to add)									
NAME OF THE COURSE	EMBEDDED SYST	EMS							
Code	FELK12	ľ	Year of study		2				
Course teacher	Sven Gotovac, Ph.D FullProfessor	).,	Credits (ECTS)		5				
Associate teachers	Dunja Gotovac, TeachingAssistant		Type of instruction (number of hours		L 30	S	AE	LE 30	DE
Status of the course	Obligatory		Percentage of application of e-I	earning	0				
	C	DURSE	DESCRIPTION		-				
Course objectives	<ul> <li>Training students to:</li> <li>1. Analyze and design embedded computing systems.</li> <li>2. Create related software support.</li> <li>3. Select and customize system support according to the system requirements</li> <li>4. Select and match the circuits and software solution (hardware-software co-design)</li> <li>5. Analyze complexity and system performance.</li> </ul>								
Course enrolment requirements and		,	, , ,						

entry competences required for the										
course Learning outcomes expected at the level	Students will be able 1. Design embedd	ed comp								
of the course (4 to 10 learning outcomes)	<ol> <li>Design and build</li> <li>Select and mate</li> <li>Analyze and evaluation</li> </ol>	h the ne	eds of sy	/stem s	oftware					
,	Course content			<u></u>			L hours	AE hours		
	Introduction, Importa embedded computin	ng syster	ms.				2	nours		
	Design methods of e						2			
		bols for design of embedded computing systems.								
		nbedded systems hardware and their interconnections.								
		/licroprocessor, microcontroller								
	Digital signal proces						2			
Course content	Different peripherals						2			
broken down in detail by weekly	The interface proble architecture, logic ci	rcuits, ti	me diagra	ams, ar			2			
class schedule	Connecting analog a		al system	IS.			2			
(syllabus)	Sensors and actuate			-			2			
	Software support for			-	systems	•	2			
	Operating Systems						2			
	Operating systems f		-				2			
	Hardware-software		·	les.			4			
	List oflaboratoryor d							LE hours 6		
	ARM and AVR microprocessors/microcontrollers.									
	Assembler programn		orny DI bo	ord Ar	duina h	ord		4 4		
	EMBEST IDE board, Application for one o			aru, Ar		Jaiu		4		
	Project		alus					12		
	⊠lectures									
	⊠seminars and wor	kshops			•	t assignmer	nts			
	□exercises	•			timedia					
Format of instruction	□ <i>on line</i> in entirety				oratory					
	□partial e-learning				k with m othe)					
	□field work				(othe	, i <i>)</i>				
Studentresponsibiliti es	The presence on lect Performed all require				t least 7	'0 % of the t	times sche	eduled.		
Screening student work <i>(name the</i>	Class attendance	1	Researc	:h		Practical tr	aining			
proportion of ECTS credits for	Experimental work		Report			Laboratory	exercises	5 1		
eachactivity so that the total number of	Essay		Seminal essay	•		Preparation laboratory		0,5		
ECTS credits is	Tests		Oral exa	im		Self-study		0,5		
equal to the ECTS value of the course)	Written exam		Project		2					
Grading and evaluating student work in class and at the final exam	There are two midte lecturing and the se minutes and consists midterm is practical numerical problems pass the midterm ex written tests. The r	cond or s of 5 to exampl and ex cams tal	ne is afte 7 theoret le and fin ample sc ke part. T	r the ne ical que al tests lving. I he mid	ext 6 we estions a consis n the fir term an	eeks. First n and numeric t of 6 theor nal exams s d final exam	nidterm te cal problem etical que students th ns are car	st lasts 60 ns, second stions and nat did not ried out as		

	laboratory exercises and 50 % points on each midterm (in percentage) is formed according to the formula:	n exam or the f	inal exam. Grade					
	Grade(%) = 0,33 LV + 0,33 (M	11 + M2)						
	<ul> <li>the activities in percentage:</li> <li>LV – laboratory assessment,</li> <li>M1, M2 – test results.</li> </ul>							
Required literature (available in the	Title	Number of copies in the library	Availability via other media					
library and via other media)	<ul> <li>Wayne Wolf, Computers as ComponentsPrinciplesofEmbedded Computing Systems Design, Morgan Kaufmann 2008.</li> </ul>	1	Electronic copy On e-learning					
Optional literature (at the time of submission of study programme proposal)	<ul> <li>Frank Vahid, Tony D. Givargis, Embedded Syster Hardware/Software Introduction, John Wiley 200<sup>o</sup></li> <li>Qing Li, Caroline Yao, "Real-Time Concepts for E Publishedby CMP Books, 2003. ISBN: 1-57820-1</li> </ul>	1, ISBN 0-471 Embedded Sys	-38678-2					
Quality assurance methods that ensure the acquisition of exit competences	<ol> <li>Publishedby CMP Books, 2003. ISBN: 1-57820-124-1</li> <li>Class attendance records.</li> <li>Evaluation of results in accordance with the above learning outcomes</li> <li>Feedback from students via surveys</li> <li>Self-evaluation of teachers</li> <li>Feedback from students who have already graduated.</li> <li>Institutional and non-institutional evaluations</li> </ol>							
Other (as the proposer wishes to								

NAME OF THE COURSE	PROGRAMMING MOBILE ROBOTS AND DRONES					
Code	FELH40	Year of study	2.			
Course teacher	Mirjana Bonković, Ph.D., Full Professor Josip Musić, Ph.D., Assistant Professor	Credits (ECTS)	5			

Associate teachers	Miroslav Dujmović, BSc (external collaborator)		ype of instructionLSAEnumber of hours)3000				LE 30	DE 0
Status of the course	Elective	Percenta	,	0	0	0	30	0
	COURSI	E DESCR		I				
Course objectives	<ul> <li>Training students for:</li> <li>understanding basic working principles and limitations of individual robot components (actuators, sensors and control units).</li> <li>understanding and applying number of different techniques for solving problems in the robotics domain such as control and navigation, as well as programming robot/drone to perform desired task.</li> </ul>							
Course enrolment requirements and entry competences required for the course	None							
Learning outcomes expected at the level of the course (4 to	C#, Python, Java).							
10 learning outcomes)	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowler C#, Python, Java).</li> </ul>	dge in hig	her level prograr	nming	langua	ages (e		sual
5	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowle</li> </ul>	dge in hig bath plann (drone) co	her level programing and navigation	nming	langua	ages (e	e.g. Vis	sual ours 2 2
outcomes)	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowle C#, Python, Java).</li> <li>evaluate efficiency of p Course content</li> <li>Introduction: mobile robot ( Microcontrollers. Arduino II Sensors: sensor character types: incremental encode</li> </ul>	dge in hig bath plann (drone) co DE for rob istics, unc	her level program ing and navigation imponents. int control. ertainty represen	nming on algo	rithms	ages (6 5. Dr	e.g. Vis	ours 2
outcomes) Course content broken down in detail by weekly	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowlen C#, Python, Java).</li> <li>evaluate efficiency of provide the content</li> <li>Course content</li> <li>Introduction: mobile robot (Microcontrollers. Arduino III Sensors: sensor characteric types: incremental encode sensors, vision sensors.</li> <li>Mobile robot kinematics. Discontrol, PID controller, specification</li> </ul>	dge in hig path plann (drone) co DE for rob istics, unc rs, position rive. Mobi	her level program ing and navigation imponents. bot control. ertainty represent in and orientation ile robot control no sition controller.	nming on algo ntation, o senso modes:	rithms senso rs, ine	ages ( 6. or ertial	e.g. Vis	ours 2 2
outcomes) Course content broken down in detail by weekly class schedule	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowle C#, Python, Java).</li> <li>evaluate efficiency of p Course content</li> <li>Introduction: mobile robot of Microcontrollers. Arduino II Sensors: sensor character types: incremental encode sensors, vision sensors.</li> <li>Mobile robot kinematics. D control, PID controller, spe Robot localization: Kalman</li> </ul>	dge in hig path plann (drone) co DE for rob istics, unc rs, position rive. Mobi rive. Mobi red and pc n, particle a	her level program ing and navigation imponents. bot control. ertainty represent in and orientation ile robot control no sition controller.	nming on algo ntation, o senso modes:	rithms senso rs, ine	ages ( 6. or ertial	e.g. Vis	ours 2 2 4 4 4
outcomes) Course content broken down in	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowle C#, Python, Java).</li> <li>evaluate efficiency of p Course content</li> <li>Introduction: mobile robot ( Microcontrollers. Arduino II Sensors: sensor character types: incremental encode sensors, vision sensors.</li> <li>Mobile robot kinematics. D control, PID controller, spe Robot localization: Kalman Navigation: planning and c</li> </ul>	dge in hig bath plann (drone) co DE for rob istics, unc rs, positio rive. Mobi ed and pc i, particle a control.	her level program ing and navigation imponents. pot control. ertainty represent n and orientation ile robot control no position controller. and information	nming on algo ntation, o senso modes:	rithms senso rs, ine	ages ( 6. or ertial	e.g. Vis	ours 2 2 4 4 4 4 2
outcomes) Course content broken down in detail by weekly class schedule	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowlen C#, Python, Java).</li> <li>evaluate efficiency of provide the content</li> <li>Introduction: mobile robot (Controllers. Arduino II)</li> <li>Sensors: sensor character</li> <li>types: incremental encode sensors, vision sensors.</li> <li>Mobile robot kinematics. Discontrol, PID controller, sper</li> <li>Robot localization: Kalman</li> <li>Navigation: planning and control with navigation error</li> </ul>	dge in hig bath plann (drone) co DE for rob istics, unc rs, positio rive. Mobi ed and pc i, particle a control.	her level program ing and navigation imponents. pot control. ertainty represent n and orientation ile robot control no position controller. and information	nming on algo ntation, o senso modes:	rithms senso rs, ine	ages ( 6. or ertial	e.g. Vis	ours 2 2 4 4 4 4 2 2 2
outcomes) Course content broken down in detail by weekly class schedule	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowle C#, Python, Java).</li> <li>evaluate efficiency of p Course content</li> <li>Introduction: mobile robot of Microcontrollers. Arduino II Sensors: sensor character types: incremental encode sensors, vision sensors.</li> <li>Mobile robot kinematics. D control, PID controller, spe Robot localization: Kalman Navigation: planning and c Control with navigation error</li> <li>Visual servoing.</li> </ul>	dge in hig path plann (drone) co DE for rob istics, unc rs, position rive. Mobi rive. Mobi rive. Mobi rive and po n, particle a control. or as inpu	her level program ing and navigation imponents. bot control. ertainty represent in and orientation ile robot control in position controller. and information in t.	nming on algo ntation, o senso modes:	senso rithms senso rs, ine on-of	ages (6 S. pr ertial f	e.g. Vis	ours 2 2 4 4 4 2 2 2 2
outcomes) Course content broken down in detail by weekly class schedule	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowlen C#, Python, Java).</li> <li>evaluate efficiency of provide the content</li> <li>Introduction: mobile robot (Controllers. Arduino II)</li> <li>Sensors: sensor character</li> <li>types: incremental encode sensors, vision sensors.</li> <li>Mobile robot kinematics. Discontrol, PID controller, sper</li> <li>Robot localization: Kalman</li> <li>Navigation: planning and control with navigation error</li> </ul>	dge in hig path plann (drone) co DE for rob istics, unc rs, position rive. Mobi rive. Mobi rive. Mobi rive and po n, particle a control. or as inpu	her level program ing and navigation imponents. bot control. ertainty represent in and orientation ile robot control in position controller. and information in t.	nming on algo ntation, o senso modes:	senso rithms senso rs, ine on-of	ages (6 S. pr ertial f	e.g. Vis	ours 2 2 4 4 4 4 2 2
outcomes) Course content broken down in detail by weekly class schedule	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowle C#, Python, Java).</li> <li>evaluate efficiency of p Course content</li> <li>Introduction: mobile robot of Microcontrollers. Arduino II Sensors: sensor character types: incremental encode sensors, vision sensors.</li> <li>Mobile robot kinematics. D control, PID controller, spe Robot localization: Kalman Navigation: planning and c Control with navigation error</li> <li>Visual servoing.</li> </ul>	dge in hig path plann (drone) co DE for rob istics, unc rs, position rive. Mobi ed and po a, particle a control. or as inpu	her level program ing and navigation imponents. bot control. ertainty represent in and orientation ile robot control in position controller. and information in t.	nming on algo ntation, o senso modes:	senso rithms senso rs, ine on-of	ages (6 S. pr ertial f	e.g. Vis	ours 2 2 4 4 4 2 2 2 2
outcomes) Course content broken down in detail by weekly class schedule (syllabus)	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowlen C#, Python, Java).</li> <li>evaluate efficiency of provide the content</li> <li>Introduction: mobile robot of the control lers. Arduino III</li> <li>Sensors: sensor characteric types: incremental encode sensors, vision sensors.</li> <li>Mobile robot kinematics. Discontrol, PID controller, specific termination in the control of the control sensors.</li> <li>Navigation: planning and control with navigation error visual servoing.</li> <li>Selected practical examples</li> <li>List of laboratory or design</li> </ul>	dge in hig bath plann (drone) co DE for rob istics, unc rs, position rive. Mobi ed and po a, particle a ontrol. or as inpu es of contr exercises onment.	her level program ing and navigation imponents. bot control. ertainty represent in and orientation ile robot control in position controller. and information in t.	nming on algo ntation, o senso modes:	senso rithms senso rs, ine on-of	ages (6 S. pr ertial f	e.g. Vis	ours       2       2       4       4       2       2       4       2       2       4       2       2       4       2       2       4
outcomes)	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowle C#, Python, Java).</li> <li>evaluate efficiency of p Course content</li> <li>Introduction: mobile robot ( Microcontrollers. Arduino II Sensors: sensor character types: incremental encode sensors, vision sensors.</li> <li>Mobile robot kinematics. D control, PID controller, spe Robot localization: Kalman Navigation: planning and c Control with navigation error Visual servoing.</li> <li>Selected practical example</li> <li>List of laboratory or design Arduino development enviror</li> </ul>	dge in hig bath plann (drone) co DE for rob istics, unc rs, position rive. Mobi ed and pc a particle a control. or as inpur es of contr exercises onment. or.	her level program	nming on algo ntation, o senso modes:	senso rithms senso rs, ine on-of	ages (6 S. pr ertial f	e.g. Vis	ours       2       2       4       4       2       2       2       4       2       2       4       3
outcomes)	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowle C#, Python, Java).</li> <li>evaluate efficiency of p Course content</li> <li>Introduction: mobile robot ( Microcontrollers. Arduino II Sensors: sensor character types: incremental encode sensors, vision sensors.</li> <li>Mobile robot kinematics. D control, PID controller, spe Robot localization: Kalman Navigation: planning and c Control with navigation error Visual servoing.</li> <li>Selected practical example</li> <li>List of laboratory or design Arduino development enviror</li> <li>Digital I/O – ultrasonic sens</li> </ul>	dge in hig bath plann (drone) co DE for rob istics, unc rs, position rive. Mobi ed and pc a particle a control. or as inpur es of contr exercises onment. or.	her level program	nming on algo ntation, o senso modes:	senso rithms senso rs, ine on-of	ages (e s. or ertial f	e.g. Vis	ours         2         2         4         4         2         2         4         2         2         4         0urs         2         3         3
Outcomes)	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowlen C#, Python, Java).</li> <li>evaluate efficiency of provide the content</li> <li>Introduction: mobile robot of the control of</li></ul>	dge in hig bath plann (drone) co DE for rob istics, unc rs, position rive. Mobi ed and pc a particle a control. or as inpur es of contr exercises onment. or.	her level program	nming on algo ntation, o senso modes:	senso rithms senso rs, ine on-of	ages (e s. or ertial f	E.g. Vis	ours       2       2       4       4       2       2       4       2       2       4       2       3       2       2
outcomes)	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowlen C#, Python, Java).</li> <li>evaluate efficiency of provide the content</li> <li>Introduction: mobile robot of the control of</li></ul>	dge in hig path plann (drone) co DE for rob istics, unc rs, position rive. Mobi red and po particle a ontrol. or as input es of contr exercises onment. or. notors and	her level program	nming on algo ntation, o senso modes:	senso rithms senso rs, ine on-of	ages (e s. or ertial f	E.g. Vis	ours       2       2       4       4       2       2       4       2       3       2       3       2       4
outcomes)	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowle C#, Python, Java).</li> <li>evaluate efficiency of p Course content</li> <li>Introduction: mobile robot ( Microcontrollers. Arduino II Sensors: sensor character types: incremental encode sensors, vision sensors.</li> <li>Mobile robot kinematics. D control, PID controller, spe Robot localization: Kalman Navigation: planning and c Control with navigation error Visual servoing.</li> <li>Selected practical example</li> <li>List of laboratory or design Arduino development enviror Digital I/O – ultrasonic sensis</li> <li>Motor control. Connection m Line following.</li> <li>Obstacle avoidance.</li> <li>Working on project assignm</li> </ul>	dge in hig path plann (drone) co DE for rob istics, unc rs, position rive. Mobi red and po particle a ontrol. or as input es of contr exercises onment. or. notors and	her level program	nming on algo ntation, n senso modes: iilter.	langua rithms senso rs, ine on-off drone	ages (6	E.g. Vis	ours       2       2       4       4       2       2       4       2       2       4       2       3       2       2
outcomes)	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowlen C#, Python, Java).</li> <li>evaluate efficiency of provide the content</li> <li>Introduction: mobile robot of the control of</li></ul>	dge in hig path plann (drone) co DE for rob istics, unc rs, position rive. Mobi red and po particle a ontrol. or as input es of contr exercises onment. or. notors and	her level program	nming on algo ntation, n senso modes: iilter.	langua rithms senso rs, ine on-off drone	ages (6	E.g. Vis	ours       2       2       4       4       2       2       4       2       3       2       4
outcomes)	<ul> <li>demonstrate application servoing).</li> <li>apply acquired knowle C#, Python, Java).</li> <li>evaluate efficiency of p Course content</li> <li>Introduction: mobile robot ( Microcontrollers. Arduino II Sensors: sensor character types: incremental encode sensors, vision sensors.</li> <li>Mobile robot kinematics. D control, PID controller, spe Robot localization: Kalman Navigation: planning and c Control with navigation error Visual servoing.</li> <li>Selected practical example</li> <li>List of laboratory or design Arduino development enviror Digital I/O – ultrasonic sensis</li> <li>Motor control. Connection m Line following.</li> <li>Obstacle avoidance.</li> <li>Working on project assignm</li> </ul>	dge in hig path plann (drone) co DE for rob istics, unc rs, position rive. Mobi red and po particle a ontrol. or as input es of contr exercises onment. or. notors and ients.	her level program	nming on algo ntation, n senso modes: iilter.	langua rithms senso rs, ine on-off drone	ages (6	E.g. Vis	ours       2       2       4       4       2       2       4       2       3       2       4

	□ on line in entirety			□ wor	k with m	entor		
	□ partial e-learning				(othe	r)		
	□ field work							
Studentresponsibiliti es	The presence on lect Performed all require				t least 7	0 % of the time	s schedu	ıled.
Screening student	Class attendance	1,5	Researc	h		Practical trainir	ng	
work (name the proportion of ECTS	Experimental work		Report			Individual work		2
credits for eachactivity so that the total number of	Essay		Seminar essay			Laboratory exe	ercises	1
ECTS credits is equal to the ECTS	Tests	0,2	Oral exa	m		Preparation for laboratory exer		0,1
value of the course)	Written exam	0,2 Project			(Other)			
Grading and evaluating student work in class and at the final exam	requirement for pass 50 % points on avera allowed to have at le final midterm averag Grade (in percentag Grade(%) = 0,1L + 0 where: • L – laborato • M1, M2 – m According to Article teaching activities a exercises. If student part in the final exam	age mid east 45% je is at l e) is for 0,25M1 ry asses idterm to 65. of attendin t does r	term exar % of total east 50% med accc + 0,65M2 ssment, est results Faculty's g at lease not meet	n ((M1 - points c of total ording to s. Bylaw, st 70% these c	+ M2)/2) on each points. o the form student of lector riteria, s	or the final exa midterm exams mula: is required to ures, and 100 the or he won't	participa % of lat be able	te in all poratory to take
		Titl	е			Number of copies in the library	Availab	oility via media
	TSiegwart, R., N D., Autonomous 2011.						teacher	/Internet
Required literature (available in the	Thomas Braunl, robot design and systems, Spring	d applica	ations wit				teacher	/Internet
library and via other media)	<ul> <li>S. Thrun, W. Bu Robotics, MIT P</li> </ul>	-		obabilis	tic		teacher	/Internet
	<ul> <li>Saeed B. Niku: I Analysis, Syster 2001.</li> </ul>	ntroduc	tion to Ro		e Hall,		tead	cher
	<ul> <li>M. Bonković, J. "Mikroregulatori Arduino razvojno FESB</li> </ul>	i ugradl	penimreži					rning rtal

	<ul> <li>J. Musić, M. Bonković: Authorised lecture notes, FESB</li> </ul>	e-learning portal			
Optional literature (at the time of submission of study programme proposal)	<ul> <li>Tadej Bajd: Osnove robotike, Fakulteta za elektrotehniko, Univerza v Ljubljani, 2000.</li> <li>Kovačić, Laci, Bogdan, Osnove robotike, Fakultet elektrotehnike i računarstva, Zagreb, 1999.</li> </ul>				
Quality assurance methods that ensure the acquisition of exit competences	<ul> <li>Keeping records of student attendance.</li> <li>Annual analysis of course statistics in terms of midterm and fina</li> <li>Feedback from students via surveys.</li> <li>Teacher self-evaluation.</li> <li>Feedback from graduated students (or senior students) on cour relevance.</li> <li>Periodic institutional evolution of course teachers.</li> </ul>				
Other (as the proposer wishes to add)	1				

NAME OF THE COURSE	MEDICAL ELECTRONIC DEVICES						
Code	FELH41	Year of study 2.					
Course teacher	Antonio Šarolić, Ph.D., Full Professor Ivan Marinović, Ph.D., Full Professor	Credits (ECTS)	5				
Associate teachers	Niko Ištuk, mag. ing. el.	Type of instruction	L	S	AE	LE	DE
Associate teachers		(number of hours)	30			30	
Status of the course	Elective	Percentage of application of e- learning	0				
	COURSE DESCRIPTION						
Course objectives	<ul> <li>learning the types, realizations and application areas of electronic/communication/information technology in medical domain</li> <li>knowledge on therapeutic, diagnostic and control medical electronic devices</li> <li>understanding the specifics of functional and safety requirements for medical electronic devices</li> <li>understanding and application of success criteria for medical device innovation and development</li> </ul>						
Course enrolment requirements and entry competences required for the	None.						
course							

	Students will be able to:						
Learning outcomes expected at the level of the course (4 to 10 learning	<ul> <li>employ their knowledge on electronic/communication/information technology for analysis and development of medical devices</li> <li>use the knowledge of human physiology, especially electrophysiology, for analysis and development of medical devices</li> <li>analyze the components of medical electronic devices and their interaction</li> </ul>						
	with human body medical electronic devices						
outcomes)	- conceive the electronic circuits for application in a medical device						
	- characterize a medical electronic device from the aspect of						
	<ul> <li>critically assess the success of innovation and development</li> </ul>	or a med	AE				
	Course content	hours	hours				
	Basics of human electrophysiology and electrophysiology	2	0				
	Measurement medical electronic devices	2	0				
	Diagnostic medical electronic devices	2	0				
	Therapeutic medical electronic devices	2	0				
	Electronic circuits and components in medical devices	6	0				
	Circuits and devices for electric and magnetic stimulation at	2	0				
	low frequencies		Ŭ				
	Circuits and devices for thermal procedures at high	2	0				
	frequencies Electrical safety aspects and electromagnetic compatibility						
	aspects of medical electronic devices	2	0				
	Control and auxiliary medical electronic devices. E-Health.						
Course content	Theranostic medical electronic devices – unifying the	2	0				
broken down in	therapeutics and diagnostics in innovative medical devices and	2					
detail by weekly	methods						
class schedule	Translational resaerch and development of medical devices						
(syllabus)	from lab to clinics (from the workbench to the bedside).	2	0				
	Assessment of clinical and economic efficacy of medical	2					
	technology (Health Technology Assessment - HTA)						
	Clinical studies: principles and implementation of clinical trials	2	0				
	of medical devices		LE hours				
	List of laboratory or design exercises						
	Basics of human electrophysiology						
	Amplifier circuits						
	Electrostimulator circuits						
	Noise and disturbance suppression in electronic devices						
	Electromagnetic compatibility testing						
	Electrical safety testing						
	Measurements of dielctric properties of tissues						
	Measurement, diagnostic and therapeutic medical electronic de field trip (visit to medical establishments)	evices –	8				
	field trip (visit to medical establishments)						
	□ independent assignme	ents					

Format of instruction	<ul> <li>seminars and workshops</li> <li>exercises</li> <li>on line in entirety</li> <li>partial e-learning</li> <li>field work</li> </ul>			🛛 lab	<ul> <li>multimedia</li> <li>laboratory</li> <li>work with mentor</li> <li>(other)</li> </ul>			
Studentresponsibiliti es	Student is required to attend the lectures and audito at least 70% of the schedule.					ory exercises in	n the am	ount of
Screening student	Class attendance	1	Researc	h		Practical traini	ing	
work (name the proportion of ECTS	Experimental work	0,5	Report			Laboratory exe	0,5	
credits for	Essay		Seminar	essay	1	Individual wor	k	1
eachactivity so that	Mid-exam	0,5	Oral exa	m		(Other)		
the total number of ECTS credits is equal to the ECTS value of the course)	Written exam	0,5	Project			(Other)		
Grading and evaluating student work in class and at the final exam	Lectures are given in collaboration of prof. Šarolić (2/3 of lecture hours) and prof. Marinović (1/3 of lecture hours). Exam: presentation and defense of the seminar essay							
Required literature (available in the library and via other media)	Title					Number of copies in the library	Availability via other media	
(available in the library and via other	Ante Šantić: Biomec knjiga, Zagreb, 1995 Jaakko Malmivuo & Bioelectromagnetist of Bioelectric and Bi University Press, Ne	5. Robert m - Princ omagne	Plonsey: ciples and etic Fields	l Applic	cations			
(available in the library and via other	<ul> <li>knjiga, Zagreb, 1995</li> <li>Jaakko Malmivuo &amp;</li> <li>Bioelectromagnetist</li> <li>of Bioelectric and Bi</li> <li>University Press, Ne</li> <li>Handbook of bio</li> <li>Bioengineering and</li> <li>Ben Greenebaum, 6</li> <li>Handbook of biolog</li> <li>Medical Aspects of</li> <li>Press, 2007.</li> <li>The Biomedical Enge</li> </ul>	Robert m - Princ omagne w York, logical e d Biophys CRC Press gical effec Electrom	Plonsey: ciples and tic Fields 1995. effects of ical Aspect 5, 2007. cts of elect agnetic Fie	Applic , Oxfor electro is of Elec romagne elds, Ed.	cations d omagnet ctromagn etic fields Frank S.	tic fields (third o etic Fields, Ed. Fra s (third edition): B Barnes and Ben G	ank S. Barı iological a ireenebau	nd m, CRC
(available in the library and via other media) Optional literature (at the time of submission of study programme	<ul> <li>knjiga, Zagreb, 1995</li> <li>Jaakko Malmivuo &amp;</li> <li>Bioelectromagnetist</li> <li>of Bioelectric and Bi</li> <li>University Press, Ne</li> <li>Handbook of bio</li> <li>Bioengineering and</li> <li>Ben Greenebaum, G</li> <li>Handbook of biolog</li> <li>Medical Aspects of</li> <li>Press, 2007.</li> </ul>	Robert Robert omagne ow York, logical e Biophys CRC Press gical effec Electrom gineering	Plonsey: ciples and tic Fields 1995. effects of ical Aspect 5, 2007. cts of elect handbook	Applic , Oxfor electro is of Elec romagne elds, Ed.	cations d omagnet ctromagn etic fields Frank S.	tic fields (third o etic Fields, Ed. Fra s (third edition): B Barnes and Ben G	ank S. Barı iological a ireenebau	nd m, CRC